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111 CASTILIAN DRIVE GOLETA CALIFORNIA 93017 TELEPHONE, 1805) 968-9621 TELEX: 658448 CABLE, MOSELEY

Warranty

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All equipment designed and manufactured by Moseley Associates, Inc. is warranted against defects in workmanship and material that develop under normal use within a period of one (1) year, or (2) years for all MRC series equipment, from the date of original shipment, and is also warranted to meet any specifications represented in writing by Moseley Associates, Inc., so long as the purchaser is not in default under his contract of purchase and subject to the following additional conditions and limitations:

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1. The sole responsibility of Moseley Associates, Inc. for any equipment not conforming to this Warranty shall be, at its option:

A. To repair or replace such equipment or otherwise cause it to meet the represented specifications either at the purchaser's installation or upon the return thereof f.o.b. Goleta, California, as directed by Moseley Associates, Inc.; or

B. To accept the return thereof f.o.b. Goleta, California, credit the purchaser's account for the unpaid portion, if any, of the purchase price, and refund to the purchaser, without interest, any portion of the purchase price theretofore paid; or

C. To demonstrate that the equipment has no defect in workmanship or material and that it meets the represented specifications, in which event all expenses reasonably incurred by Moseley Associates, Inc., in so demonstrating, including but not limited to costs of travel to and from the purchaser's installation, and subsistence, shall be paid by purchaser to Moseley Associates, Inc.

2. In case of any equipment thought to be defective, the purchaser shall promptly notify Moseley Associates, Inc., in writing, giving full particulars as to the defects. Upon receipt of such notice, Moseley Associates, Inc. will give instructions respecting the shipment of the equipment, or such other manner as it elects to service this Warranty as above provided.

3. This Warranty extends only to the original purchaser and is not assignable or transferable, does not extend to any shipment which has been subjected to abuse, misuse, physical damage, alteration, operation under improper conditions or improper installation, use or maintenance, and does not extend to equipment or parts not manufactured by Moseley Associates, Inc. and such equipment and parts are subject to only adjustments as are available from the manufacturer thereof.

4. No other warranties, express or implied, shall be applicable to any equipment sold by Moselev Associates. Inc. and no representative or other person is authorized by Moseley Associates, Inc. to assume for it any liability or obligation with respect to the condition or performance of any equipment sold by it, except as provided in this Warranty. This Warranty provides for the sole right and remedy of the purchaser and Moseley Associates, Inc. shall in no event have any liability for consequential damages or for loss, damage or expense directly or indirectly arising from the use of equipment purchased from Moseley Associates, Inc.

CUSTOMER SERVICE INFORMATION

Moseley Associates, Inc. has a Technical Services Department to assist product users who experience difficulties. Our service is available at two levels: telephone consultation and factory service. Different circumstances apply whether the product(s) are under Warranty/Service Agreement status or outside Warranty/Service Agreement status.

<u>Please read the manual</u>; a large portion of telephone calls to Moseley request information which is needed due to non-familiarity with the equipment. The majority of those questions are already answered by the Installation/Operation sections of each manual. If these do not help your problem, the first step in any factory service transaction should always be telephone consultation.

PRODUCTS COVERED BY WARRANTY/SERVICE AGREEMENT

Telephone Consultation

If telephone consultation/assistance is necessary, please have the following information available prior to calling the factory:

- A. Model Number and Serial Number of unit,
- B. Shipment date or date of purchase of Extended Service Agreement,
- C. Module identification markings,
- D. Be prepared to accurately describe the problems with your unit: Constant or intermittent? Precise symptoms? Meter readings? Operational frequency of unit?

Once you are prepared with this information, contact our Technical Services Department for assistance. A Technical Services Representative who knows your product(s) is available during normal work hours (8:00 a.m. to 5:00 p.m., Pacific Time, Monday to Friday). Please do not get upset if the particular Representative you should talk to is busy. Leave your name, call letters, equipment type and telephone number(s) where you can be reached in the next few hours. Someone will get back to you as soon as possible.

Please understand that telephone calls should be kept as short as possible - ultimately our costs in tying up a Technical Service Representative for unnecessary periods of time must result in higher charges on our Service Agreements. It is better to listen to explanations/suggestions/procedures and to call back if you are continuing to experience problems.

If telephone assistance is required, our telephone number is:

(805)968-9621

Emergency (Only) Telephone Consultation

The above number applies to both normal working hours and to emergency out-of-hours consultation.

Emergency service is provided from 5:00 p.m. to 10:00 p.m., Pacific Time, Monday to Friday, and from 8:00 a.m. to 10:00 p.m., Pacific Time, on weekends and holidays.

This service is for <u>emergencies only</u>. Please do not expect our Representative to know the status of your order, to take spare parts orders and the like.

Arrangements for factory service can be made after consultation with the factory Technical Service Representative and his assignment to you of a Return Authorization (R.A.) Number. This number expedites your equipment's routing from the Receiving Department to Technical Services.

PRODUCTS OUT OF WARRANTY/NOT COVERED BY A SERVICE AGREEMENT

Telephone Consultation

If telephone consultation/assistance is necessary, please have the following information available prior to calling the factory:

- A. Model Number and Serial Number of unit,
- B. Module identification markings,
- C. Be prepared to accurately describe the problems with your unit: Constant or intermittent? Precise symptoms? Meter readings? Operational frequency of unit?
- D. The number of your account and name that account is under (parent organization or whatever) OR major credit card details.

The latter is, unfortunately, necessary because the costs of consultation on an older unit - for which a customer has not purchased an Extended Service Agreement - are enormous; we are happy to provide about fifteen minutes of totally free telephone consultation - and the majority of problems can be solved in that time. Beyond that, we are forced to charge - and we do that at our current hourly rate - in quarter-hour units of time.

Once you are prepared with this information, contact our Technical Services Department for assistance. A Technical Services Representative who knows your product(s) is available during normal work hours (8:00 a.m. to 5:00 p.m., Pacific Time, Monday to Friday). Please do not get upset if the particular Representative you should talk to is busy. Leave your name, call letters, equipment type and telephone number(s) where you can be reached in the next few hours. Someone will get back to you as soon as possible.

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GENERAL

Replacement Modules

Moseley Associates encourages the purchase of recommended spare parts kits to allow the customer to be totally self-sufficient with regard to parts. We recognize that there are extenuating circumstances when troubleshooting to the component level is neither practical nor possible. If this is the case, replacement module exchange may be the most expedient way of correcting the problem. Each product manual lists recommended spares.

Non-frequency sensitive replacement modules are normally available for immediate shipment. If you require a replacement module from Moseley Associates, please give your shipping address to our Technical Services Engineer. If the module or equipment to be supplied to your company is to be held at the airport with a telephone number to call, please provide at least two telephone numbers. This will often expedite the delivery or pickup of the replacement module or equipment.

Field Repair

Always try to isolate the problem to a specific area or module, if possible. By comparing the actual wave shapes and levels with those referenced on the block and level diagrams or schematics, the problem often can be localized to the component level.

If an integrated circuit is suspect, carefully remove the original and plug in the new one in the same direction. These devices are installed one way only. Plugging in a new device backward may damage the newlyinstalled component or the surrounding circuitry. ICs occasionally exhibit temperature-sensitive characteristics. If a suspicious device operates intermittently or appears to drift, Freeze Mist may aid in diagnosing the problem.

If a soldered component has to be removed from a printed circuit board, do the following:

Use a 40 W soldering iron with a 1/8 inch tip. Do not use a soldering gun. Excessive heat may cause damage!

Remove all solder contacting the lead or leads from the component and from the associated printed circuit pad. To assist in the removal of the solder, solder-sipping braid, such as solder wick, is very useful. Once the solder has been removed, remove the component from the board.

When installing the new component, pre-bend the leads of the replacement component so they will easily fit into the appropriate PC board holes. Solder each lead of the component to the bottom side of the board with a 40 W soldering iron with a 1/8 inch tip. Always use a good brand of rosin-core solder. The solder joint should be smooth and shiny. Also, be sure that excessive heat is not used in this soldering operation. Excessive heat will damage the printed circuit pad that comes in contact with the new component. Finally, cut each lead of the replacement component close to the solder on the pad side of the printed circuit board with a pair of diagonal cutters. Then remove all residual flux with either flux cleaner or a cotton swab moistened with flux cleaner.

Factory Service

When returning your equipment to Moseley Associates, Inc., the following suggestions are offered to assist you. If you are returning a module, ensure that the module is packed sufficiently to withstand the rigors of the journey. Make sure the shipping carton is packed evenly and fully, with packing material filling all voids so that the module cannot shift inside the shipping carton. The package should also be marked in red with the words "Electronic Equipment" or "Fragile." Remember, the condition of the module is totally dependent on the care taken in the packing. Reference the Return Authorization Number that you had previously obtained from the factory on the outside of the carton or on the shipping label. Make sure that the name of your company is listed on the shipping label, and insure your module appropriately. If you are shipping a complete chassis, all modules should be tied down as they were originally received. On some Moseley Associates equipment, shipping screws are required on the underside or topside of the chassis. In this case, printing on the chassis will indicate where such screws should be installed and secured.

Include any and all descriptions of the difficulties encountered with your equipment in the field. This will greatly assist us in processing your equipment and returning it as expeditiously as possible.

Use the original shipping carton in which your equipment was supplied, if possible. Ensure that the carton is packed evenly and fully with packing material filling any voids so that the chassis cannot shift inside the carton. Make sure the carton is sealed properly with either nylon-reinforced tape or shipping sealing tape. Mark the outside of the carton "Electronic Equipment - Fragile" in big, red letters. This will assist the survival of the equipment in the shipping process. Again, bear in mind that the survival of the unit depends almost solely on the preparation taken in shipping it.

When returning your equipment to our factory, please address it to the following:

MOSELEY ASSOCIATES, INC. Attn: Technical Services Dept. 111 Castilian Drive Goleta, California 93117

Display your Return Authorization Number clearly on the shipping label and insure the equipment for the appropriate amount.

All equipment must be shipped prepaid; Moseley Associates, Inc. will return the equipment prepaid under warranty and Service Agreement conditions, and either freight collect or billed for equipment not covered by warranty or a Service Agreement.

WARNING

This equipment generates, uses, and can radiate radio frequency energy and if not installed and used in accordance with the instruction manual, may cause interference to radio communications. This equipment complies with the requirements in Part 15 of FCC Rules for a Class A computing device. Operation of this equipment in a residential area may cause unacceptable interference to radio and TV reception requiring the operator to take whatever steps are necessary to correct the interference.

INSTRUCTION MANUAL

MODEL MRC-1 MICROPROCESSOR REMOTE CONTROL SYSTEM

REMOTE TERMINAL

MOSELEY ASSOCIATES, INC. Santa Barbara Research Park lll Castilian Drive Goleta, California 93017

Rev. 9 June 1980

(805) 968-9621

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1.0 SYSTEM INTRODUCTION

1.1 INTRODUCTION

The MRC-1 Microprocessor Remote Control System is a modular solid-state microprocessor-based system designed to meet the needs of the broadcaster to obtain remote indications of analog and status information, and to provide remote control of his equipment.

The MRC-1 consolidates, into one convenient package, all the features of existing moderately-priced remote control systems that require numerous auxiliary devices to function as a system in addition to many features normally found in large-scale remote control systems. The many features incorporated into the MRC-1 are made possible through the use of a microprocessor as the main control and logic element_of each Remote and Control Terminal.

The flexibility of the microprocessor has also led to some changes in the terminology that is used to describe the functions performed by the MRC-1 and the way it is connected as a system. It is highly recommended that personnel installing an MRC-1 for the first time completely read and understand the manual before attempting to connect the MRC-1 to the user's equipment. There are two separate manuals for a complete MRC-1 system. One manual is for the Control Terminal; the second manual for the Remote Terminal.

1.1.1 Manual Organization

This manual has been designed to guide the user through the many features of the MRC-1 in a logical manner. Following the system specifications and unpacking instructions, Section 4 defines the operation of the Remote and Control Terminals. Once the operation of the system is mastered, Section 5 describes how to connect the MRC-1 to equipment being monitored and controlled. Section 6 defines the adjustment and calibration of the unit. Section 7 is a guide to maintenance of equipment should any difficulties be encountered. Section 8 contains circuit card descriptions, schematics and illustrations organized by type of circuit card. The last section will contain data for any options that were ordered as a part of the system. Should options be ordered at some future time, the option data may be appended to this manual by the user.

1.1.2 Technician Safety

The compact and modular design of the MRC-1, with convenient access to all modules and wiring, dictates that, from a safety standpoint, no lethal voltages be accidentally accessible to the technician. With the exception of the AC mains, which are made difficult to access, all internal voltages are less than 15 volts in magnitude. The user-applied voltages are limited to a maximum of 48 volts at any terminal (generally less) so that, when performing normal maintenance on the equipment, no lethal voltages are present inside the chassis. All high-voltage power switching and control must be performed indirectly by equipment external to the MRC-1.

1.2 SYSTEM OVERVIEW

An MRC-1 system consists of a Control Terminal and from one to nine Remote Terminals. Each Remote Terminal may access up to

MRC-1

32 status inputs (ON/OFF), 32 telemetry inputs (analog), and up to 64 command outputs (ON/OFF).

The Control Terminal communicates with each of the Remote Terminals over a single communications circuit that connects all locations. The communication circuit may be either 2-wire or 4-wire (or equivalent) telephone lines, STL subcarrier, aural SCA or private radio/ microwave links. Figure l-l is a typical illustration of the Control Terminal connected to several Remote Terminals.

In operation, one of the remote sites is selected for display at the Control Terminal. The value of each of the 32 status inputs is displayed on a set of 32 LED's. Calibrated analog values are digitally displayed one at a time. A CHANNEL SELECT key is used to display the desired channel.

The Remote Terminals perform seven (7) basic functions:

- The remote keyboards are used to set up the system. When the system is installed, calibration data, alarm criteria, and so forth, are entered at each Remote Terminal keyboard. These may be changed from the remote keyboards during operation.
- 2. Once the system has been set up, the Remote Terminals process the incoming data according to the details of how the system was set up. The necessary computations for calibration, alarm checking, etc., are performed at the Remote Terminals.
- 3. The Remote Terminals process and transmit data, and turn ON and OFF the command output lines as instructed by the operator activating the Control Terminal.



FIGURE I-I

TYPICAL MRC-I SYSTEM INTERCONNECT

- 4. The Remote Terminals check for alarms and notify the Control Terminal should an alarm condition be found.
- If desired, a remote site may be operated directly from its own front panel, if it is placed in MAINTE-NANCE OVERRIDE mode.
- 6. The Remote Terminals provide a fail-safe output as required in broadcast applications.
- 7. The Remote Terminals continually monitor changes in their individual conditions (e.g., with temperature) and make slight adjustments in calibration calculations as required.

The Control Terminal is specialized to communicate with the various Remote Terminals, requesting display information and processing alarm reports as required. The Control Terminal prepares messages to the various Remote Terminals according to the actions of the user.

Much of the power of the MRC-1 is due to the flexibility available to the user in setting up the system. Specifically:

- Telemetry (analog) channels may be calibrated in three ways:
 a. Directly proportional to input level (linear calibration)
 - b. Proportional to the square of the input level (power calibration)
 - c. Proportional to the product of two telemetry (analog) inputs (indirect calibration)
- Each of these calibrated telemetry (analog) channels may have an upper and lower limit. If these limits have been established, the input is sampled, adjusted

according to calibration, and compared against the limits. Any violation causes an alarm.

- 3. Each of the individual status inputs may be given attributes causing them to "latch" or be inverted before display. Each status input may be set up to trigger an alarm, either on rising edge or falling edge (or both).
- 4. Any command output may be assigned to either the RAISE or LOWER key for any specified channel. "Latching" command lines also may be specified, in which case, pushing RAISE turns the command output ON, and pushing LOWER turns it OFF.
- 5. Telemetry inputs may be assigned "Mute" status inputs. If the "Mute" status input is ON, the telemetry data is displayed and limit-checked normally. If the "Mute" status input is OFF, limit checking is suppressed.

2.0 SYSTEM SPECIFICATIONS

2.1 INTRODUCTION

The MRC-1, as a system, can accommodate a wide variety of options with regard to interfacing the system to the user's equipment. The specifications for each interface, in addition to system specifications, are detailed in this section.

2.2 SYSTEM SPECIFICATIONS

The following are general system specifications for the MRC-1:

Type of System	Microprocessor-based Control and Remote Terminals.
Number of Control Terminals Per System	One (1) Control Terminal active in a system at a time
Number of Remote Terminals	One (1) to nine (9) Remote Termi- nals in a system
Failsafe:	
Control	Complies with current FCC require- ments for AM, FM and TV service. Responds 45 seconds after failure of interconnecting circuit.
Telemetry	Internal timers and monitors for FCC TV compliance
Output	N.C. transistor closure at 48V, 100 mA
Alarm Indications	Visual and aural. Aural alarm defeatable and remoteable.
Maintenance Override	Remote Terminal front-panel con-

Remote Terminal front-panel control provides Remote Terminal "GO HOME" transistor closure and Control Terminal indication. N.O. transistor at 48V, 100mA, isolated. Interconnect

2-wire, 4- wire, FM subcarrier, or Interconnect Classes combinations Nominal 600Ω balanced line. 2-Wire/4-Wire Series 3002 (unconditioned) data channel per Bell System Technical Reference PUB-41004. Two-way non-simultaneous. Nominal send level 0 dBm; receive level -30 dBm minimum Nominal levels 1.5V p-p at $2k\Omega$. FM Subcarrier Frequency range 26 kHz to 185 kHz (Optimal) Modulation Two-tone FSK; 1200 Hz idle, 2200 Hz mark frequencies Data Rate 1200 bits per second Data Format 10 bits, 7-bit ASCII plus parity, start, stop bits Parity by character, longitudinal Data Checking redundancy check and fixed formats Command Functions Number of Command Lines 16, 32, 48 or 64 lines per Remote Terminal Command Line Modes Each line programmable by user for momentary or latching operation Command Line Association Each momentary programmed line is user-assignable to one or more telemetry channels. Each latching line is assignable to one telemetry channel. Tally-Back Front-panel LED indicators at Remote and Control Terminals Response Time 250 ms, nominal Status Functions Number of Channels 16 or 32 channels per Remote Terminal

States	User-programmable for N.O./N.C. activating front-panel LED's
Attributes	Latching or Following Alarm on rising, falling, or both conditions (or no alarm)
Response Time	250 ms, nominal, per site, from status change at Remote Terminal to Control Terminal indication.
Telemetry Functions	
Number of Channels	l6 or 32 channels per Remote Ter- minal
Calibration	Via keyboard at Remote Terminal in user-selected units of measure
Calibration Modes	Linear, power-to-linear, and in- direct power calculation
Display	4 digits with decimal point and polarity sign for value and limits display
Alarms	Fully tolerance-alarmed for high and/or low limits
Muting	User-assignable status channel to cause alarm muting
Input Filtering	Digital two-pole filter
Display Response Time	500 ms, nominal, from request at Control Terminal
Self Check	A self-calibration cycle performed at approximately 4-second inter- vals
Physical Specifications	
Power:	λ.
Standard Control	120/240 VAC 50/60 Hz, 50 watts, nominal
Remote & Expanded Control	120/240 VAC 50/60 Hz, 100 watts, nominal

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Size:

Standa	rd Control	13.3 cm H x 48.3 cm W x 38.1 cm D (5.25" H x 19" W x 15" D) Depth less connectors
Remote	& Expanded Control	17.8 cm H x 48.3 cm W x 39.4 cm D (7" H x 19" W x 15.5" D) Depth less battery or connectors
Operating	Temperature	0° - 50°C

2.3 ANALOG-TO-DIGITAL CONVERTER MODULE

The following specifications apply to the analog-to-digital (A/D) converter assembly supplied as a part of the system:

Channels	l6 channels per module, 2 modules (maximum) per Remote Terminal
Resolution	One part in 1024
Inputs	Double-ended ±3.5 volts nominal, 100k DC bridging
Maximum Input	±5.0 volts. Application of volt- age above this level causes erratic operation of one or more channels. Damage level is ±40 volts.
Sample Interval	A channel is sampled more than twice a second, regardless of the number of channels in the Remote Terminal.
Overall Measurement Accuracy	Better than 0.5%

2.4 TTL STATUS INPUT MODULE

The following specifications apply to the TTL Status Input Module supplied in the MRC-1 system:

Number of Channels 16 per module, 2 modules (maximum) per Remote Terminal

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Input Configuration	Low-power TTL with l0k pull-up to +5 yolts DC
Voltage Reference	Chassis signal ground
Maximum Input Voltage	+5.5 volts DC Contact closure to
Minimum Input Voltage	0.0 volts circuit
Logic High Level Input Voltage	Greater than 2.0 volts
Logic Low Level Input Voltage	Less than 0.8 volts
Short Circuit Output Current	Less than 1.0 ma

2.5 OPTICALLY-ISOLATED STATUS INPUT MODULE

The following specifications apply to the Optically-Isolated Status Input Module that can be interchanged with the TTL Status Module. Both module types may be mixed within a single Remote Terminal:

Number of Channels	16 per module, 2 modules (maximum) per Remote Terminal
Input Configuration	LED optical isolator
Voltage Reference	Two-terminal isolated from refer- ence
Maximum Input Current	30 ma maximum through optical isolator, user-supplied current. User-changeable current limiting resistors

Maximum Voltage

±50 volts above chassis ground

2.6 OPEN COLLECTOR COMMAND OUTPUT MODULE

The Open Collector Command Output Module is supplied in an MRC-1 system for activating external devices:

MRC-1 Rev. 16 Dec 1981 2-5 Number of Outputs16 command outputs per module,
4 modules (maximum) per Remote
TerminalOutput ConfigurationHigh current peripheral driver
integrated circuitVoltage ReferenceChassis signal groundMaximum Voltage48 volts DC, user-suppliedMaximum Current250 ma, user-suppliedVoltage Drop (250 ma)1.5 volts

2.7 OPTICALLY-ISOLATED COMMAND OUTPUT MODULE

The Optically-Isolated Command Output Module can be interchanged with the Open Collector Output Module for activating external devices:

Number of Outputs	16 command output per module; 4 modules (maximum) per Remote Terminal
Output Configuration	Optical isolator driving high- current Darlington
Voltage Reference	Two-terminal
Maximum Voltage	48 volts DC between terminals, user-supplied
Maximum Current	250 ma, user-supplied
Voltage Drop (250 ma)	1.5 volts

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3.0 UNPACKING AND PRE-INSTALLATION CHECKOUT

3.1 UNPACKING

Upon removing the units from the shipping cartons, please inspect them carefully for internal and external damage that may have occurred during transit. Verify that all printed circuit cards are seated firmly in the mother boards. All cards are the same length and all should appear to be seated in the card cage to the same depth.

An instruction manual - Control Terminal or Remote Terminal - is shipped with each unit. There is some terminology that is used to describe the location of components on the PC boards within the card cages. The cards in a Standard Control Terminal are mounted horizontally (component side up) while those in a Remote Terminal or expanded Control Terminal are mounted vertically (component side to the right). The location of the components, i.e., LED's, test points, and switches are always given as if the cards were mounted vertically. The top edge of a card in a Standard Control Terminal is the left-hand edge; the bottom the right side.

Initial checkout of certain options, such as the LOGGER and POWER FAIL/MEMORY are covered in the documentation supplied with the option and presumes that the basic unit pre-installation checks have been performed. All units are checked out as a total system, as ordered.

The main purpose of pre-installation checkout is for the user to gain familiarity with the system while both the Control and

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Remote Terminals are easily accessible and together on a bench at the same location. It is recommended that the user read the entire manual to understand the MRC-1 prior to attempting a hookup to his equipment. While the installation is relatively simple and straightforward, certain details of installation and operation, if overlooked, may cause what appear to be equipment failures.

3.2 POWER SUPPLY SHIPPING HOLDDOWN

A shipping screw is provided to hold down the power supply during transit. The screw is located on the left-hand side of the bottom chassis plate near the rear. Removal of the shipping screw prior to installation of the equipment into the rack will allow removal of the power supply assembly for servicing without removing the entire chassis from the rack.

CAUTION

WHENEVER THE UNIT IS SHIPPED, THE SHIPPING SCREW MUST BE INSTALLED AND SECURELY FAS-TENED. FAILURE TO OBSERVE THIS PRECAUTION CAN RESULT IN PHYSICAL DAMAGE TO THE UNIT AND VOIDS ALL WARRANTIES IF SHIPPED WITH-OUT THE SCREW.

The shipping screw should be saved and taping the screw to the chassis for any possible shipment is encouraged.

3.3 PRE-INSTALLATION CHECKOUT

The following procedures apply to checking the Control and Remote Terminals on a stand-alone basis upon receipt of the units.

 Verify that the power line voltage selector and fuse are set for the line voltage to be applied to the unit. The voltage selector is located

MRC-1 Rev. 10 Nov. 1980 at the left rear of the chassis. The units are shipped for 120 VAC operation, unless otherwise specified. The voltage selected can be observed on the PC card through the window in the AC power connector. To change the voltage, remove the power cord, slide the access window to the left, and with small needle-nose pliers, grasp and remove the PC card. Orient the card for proper operation - either <u>120 VAC or 220 VAC</u> <u>only</u> - and firmly replace the PC card. Install the proper fuse for the applied voltage as indicated by the placard on the AC mains connector. Slide the window to the right and install the AC mains connector.

- 2. Install the backup battery, provided only with the Remote Terminal. Connect the plus terminal of the battery to the red terminal of the CPU I/O connector and the negative to the black terminal of the CPU I/O connector. Batteries are shipped disconnected to prevent complete discharging.
- Open the front panel by turning the knurled screw on the right side of the panel counterclockwise until the fastener disconnects and the panel can be swung open.
- 4. Connect the AC power connector to the AC mains. Depress the "ACK" key on the Remote Terminal front panel in order to clear the "cold start" condition which occurs whenever the Remote Terminal is powered up after the contents of memory have been lost.
- Observe that the three upper LEDs on the CPU board - the bottom slot of the card cage - are ON.

These three LED's monitor the +15, +5 and -15 yolt power supplies and are illuminated when there is voltage present.

- 6. Depress the "Reset" switch on the CPU board. Observe that the single LED near the switch illuminates while the switch is depressed and, for a short period, after the switch is released.
- 7. Observe the top LED on the modem PC board. It should turn ON and OFF at a periodic rate indicating that the Control Terminal is attempting to communicate with Remote Terminals.
- Depress the LAMP TEST key. All LED's and displays on the Terminal should illuminate. A second depression of the LAMP TEST key will restore all LED's and displays.
- 9. This concludes initial checkout. Note that after six seconds an alarm condition will be indicated at the Control Terminal by a flashing "DATA ERROR" LED because of the failure to communicate with a Remote Terminal."

3.4 PRE-INSTALLATION SYSTEM CHECKOUT

Follow the individual checkout procedures for the Control Terminal and each Remote Terminal supplied as part of a system.

The Remote and Control Terminals should be connected back-to-back to verify communications according to the type of communications board supplied.

A. Modem Telco Interface

When telephone lines are used for communication in both directions, this board will be supplied for the Remote and Control Terminals. Two modes of operation are possible; two-wire or four-wire. In the two-wire mode, one telephone pair carries both Remote and Control message transmissions. In the four-wire mode, the Remote and Control Terminal messages are transmitted on separate telephone pairs, giving slightly better noise immunity. Figure 3-1A shows two-wire interconnection techniques. Figure 3-1B shows four-wire interconnection.

CONTROL TERMINAL TELCO INTERFACE

(3AD BOARD FROM BOTTON, OR 3RD BOARD FROM RIGHT)



FIG. 3-IA

TWO-WIRE TELEPHONE LINE INTERCONNECTIONS

MRC-1

CONTROL TERMINAL TELCO INTERFACE

(3RD BOARD FROM BOTTON, OR 3 RD BOARD FROM RIGHT)



FIG 3-18

FOUR-WIRE TELCO INTERFACE

After the units are interconnected, measure the output levels and modem input level and adjust, if necessary, as described in Section 6 of this manual. These levels should be checked again when the unit is installed at the final location. Adjusting these controls, taking into consideration actual telco line loss, will greatly improve communications reliability.

B. Subcarrier Interface

When FM subcarriers are used for data in both directions, this board will be supplied. Interconnection is quite simple. Using two BNC-to-BNC connector cables, interconnect units as shown in Fig. 3-2.



(REMOTE TERMINAL)

FIG. 3-2



C. Subcarrier/Telco Interfaces

When one communication direction is on telephone lines and the other direction is on an FM subcarrier, a combination telephone/ subcarrier board is used at each end. Interconnection is shown in Fig. 3-3.

MRC-1



FIG. 3-3

TELCO / SUBCARRIER COMMUNICATIONS

The user may now connect test inputs to status and telemetry I/O interface and loads to control outputs as desired.

Referring to Section 4 of the Remote Terminal manual, telemetry channels that have inputs may be calibrated. Status channels (with or without input connections) may be programmed. Exercising the MAP function, the effect of commands to RAISE and LOWER may be observed.

In the event that any difficulty is encountered, review thoroughly Sections 4 through 7 to determine the cause of the difficulty. Refer especially to Section 8 for wireline modem or subcarrier modem adjustments.

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FIGURE 4-1

4.0 REMOTE TERMINAL OPERATION

4.1 INTRODUCTION

This section defines the operation of the Remote Terminal from the operator's view point. A detailed description of each key and its effect on the operation of the MRC-1 Remote Terminal is presented. Once familiarity is gained with the system, reference can be made to the last part of this section where a brief summary of the key operation is given.

4.1.1 Front-Panel Controls and Indications

Referring to an actual Remote Terminal or Figure 4.1, the front panel of the Remote Terminal contains the following.

- A. Numeric Displays
 - 1. Site (1 digit)
 - 2. Channel (2 digits)
 - 3. Value/Edit (4 digits + sign)
- B. LED Displays
 - 1. Status Indicators (32 LED's)
 - 2. Status Attribute Indicators (4 LED's)
 - 3. Alarm Indicators (3 LED's)
 - 4. System Indicators (4 LED's)

C. Audible Alarm

D. Keyboard

- 1. Value Entry Keys
- 2. Shift Key
- 3. Function Keys
 - A. "CH"
 - B. "SITE"

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C. "LATCH", "INVERT", "---", "---", and "STAT CLR"

D. "LIN" and "POWER"

E. "HI LIM" and "LO LIM"

- F. "LIMS"
- G. "MAP", "RAISE", and "LOWER"
- H. "MUTE"
- I. "ACK" (ACKNOWLEDGE)
- J. "LAMP TEST"
- K. "MAINT O'RIDE"
- L. FAILSAFE FUNCTIONS

Each of these will be described in turn.

4.1.2 Numeric Displays

The numeric (7-segment) displays at the Remote Terminal provide the following indications under the condition described:

- A. SITE: The SITE display is a single-digit display indicating which site number has been assigned to a Remote Terminal. In an MRC-1 System which consists of a Control Terminal and one to nine Remote Terminals, each remote must be given a unique site number. If two remote terminals have the same site number, both will respond at once when the Control Terminal attempts to communicate with the duplicated site number, and neither will be able to send back data successfully. The site number is automatically assigned according to strapping on the front-panel printed circuit board, and may be changed by using the site key (described in Section 4.5.2).
- B. CHANNEL: The CHANNEL display is a two-digit display indicating which channel is selected. For example, if "01" appears in the channel display, Telemetry Channel 1 may be calibrated, assigned limits, assigned command outputs, raised, lowered, etc. If

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Telemetry Channel 1 has already been calibrated, its current value will appear in the value-edit display.

C. VALUE-EDIT: The VALUE-EDIT display consists of four digits plus sign. It serves two functions: To display values currently being entered in command key sequences, or if no command sequence is being entered the current value of the selected telemetry channel.

While a key sequence is being entered the numeric keys activated are displayed, with each new digit entered pushing previously entered digits to the left. If more than four digits are entered only the last four digits entered are significant, the remaining being lost. A decimal point in the left-most digit indicates that the shift key was activated. Entering a "-" sign as a part of the key sequence affects the sign portion of the display. At the end of a properly executed key sequence the user will see the results as described later in this section for each key sequence. Any error in the key sequence results in an "E" appearing in the display for two seconds whereupon the display returns to whatever was being displayed just prior to the key sequence.

When not displaying key sequences the value appearing in the display for the channel selected can have the following meanings:

- If the channel is uncalibrated, the VALUE-EDIT display remains blank.
- 2. If the channel is in an overflow condition, a flashing "EEEE" will appear in the display. An overflow condition occurs when the telemetry (analog) value for the selected channel is too large to display as calibrated.

For example, if Telemetry Channel 1 is calibrated to display a value of "9000" for 2.0 volts applied, and 5.0 volts is then applied, the resulting value ("22500") will overflow

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the four digits available, and "EEEE" will be displayed.

- 3. If more than about 6 volts is applied, the selected telemetry channel may be in a saturated condition, i.e., the analog-to-digital converter is operating beyond the range where it is accurate. In this case, a flashing "----" will appear in the display.
- 4. Otherwise, the current value of the telemetry channel as calibrated will be displayed.

4.1.3 LED Indications

There are four major groups of LED indications on the front panel to:

- A. Indicate the user's status conditions;
- B. Indicate how a selected status bit has been programmed;
- C. Indicate system details, and;
- D. To indicate system and tolerance alarms.

The functions of each group of LED indicators is as follows:

A. Status Indications

There are 32 red LED's displaying the current value of status channels 1-32. LED's are assigned to channels starting from upper left and proceeding across from left to right. Thus, the first row displays status channels 1-8; the second row displays 9-16; the third row 17-24; and the fourth row 25-32. An "ON" condition is displayed by a steadily lit LED, and an "OFF" condition by an unilluminated LED. If an alarm condition has occurred on a status channel and has not yet been acknowledged, the appropriate LED will flash at a 2 Hz rate. (Alarm conditions may be defined by the user; this and the procedure for acknowledgement will be described later.)

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B. Status Programming

There are four green LED's indicating which attributes, if any, have been assigned to the selected status channel. The LED's are labeled "LATCH", "INVERT", "____ " (Rising edge alarm), and "____" (Falling edge alarm). These attributes are selected and removed via key commands described in later paragraphs of this manual. The specific status bit selected and programming displayed in these LED's is indicated by the channel display.

C. System Details

There are four yellow LED's which indicates various details of the status of the system:

A. The "RAISE/ON" and "LOWER/OFF" LED's show the status of the user-assigned command outputs. If the command channels have been established as momentary in operation, each LED is lit if the assigned command output is "ON" and not lit if the command output is "OFF". For example, suppose channel 12 has been selected for display, with command output 3 established as the raise output, and command output 8 established as the lower output. Then the "RAISE/ON" LED will reflect the status of command output 3 and the "LOWER/OFF" LED that of command output 8.

If a command output of latching type has been established instead, then the "RAISE/ON" light indicates that the command output is "ON" and the "LOWER/OFF" LED indicates that the channel is "OFF".

- B. The LED labeled "LIMITS ON/OFF" is lit if limit checking is enabled.
- C. The yellow LED positioned over the key labeled "MAINT O'RIDE" indicates whether the terminal is in maintenance

override status; the LED is illuminated if so. If the system is in Maintenance Override status, RAISE or LOWER commands issued from the Control Terminal will be ignored, and any failsafe condition will be terminated. If the system is not in Maintenance Override status, RAISE or LOWER command issued from the Remote Terminal keyboard will be ignored.

D. Tolerance Alarms

There are three red LED's which are used to indicate alarm conditions. Two of these, labeled "HI" and "LOW", are used to describe the current condition of the selected telemetry channel with respect to its limits. For example, if Channel 7 is being displayed and the current value of that channel, as calibrated, exceeds its upper limit, the "HI" LED will be lit (and flashing at 2 Hz if the alarm has not been acknowledged by pushing the "ACK" key). This, of course, is only if limit checking has been enabled.

Additionally, the LED labeled "SYS" describes the condition of the analog-to-digital conversion hardware. Each Remote Terminal, at approximately 4-second intervals, makes internal tests of various conditions, including the gain-reference and offset voltages. If any of these violate factory-set tolerances, the "SYS" LED is illuminated until the violation of tolerance ends.

4.1.4 Audible Alarm

Each front panel in an MRC-l system is equipped with an audible alarm. The alarm will sound only if it is enabled via the rearpanel socket. At Remote Terminals, the alarm is used for two functions:

 In case of a power failure where memory has not been preserved (or when starting the system for the first time), the alarm sounds to indicate the necessity to recalibrate

telemetry channels, re-assign attributes, re-enter limits, etc. (I.E., the user must reinitialize the terminal.) Pushing the Acknowledge key turns off the alarm and begins normal operation. Note that, even if the alarm is not enabled via the rear-panel socket, "ACK" must be pushed to begin normal operation.

2. If an unacknowledged alarm condition is found, the audible alarm indicates the presence of the alarm.

4.2 KEYBOARD INTRODUCTION

The MRC-1 Remote Terminal front panel has 20 keys, each with a function. A shift key is used to enable 11 additional functions. Operations on the front panel keyboard are quite similar to operations on a calculator.

The following abbreviations appear on the Remote Terminal keyboard:

Abbreviation	Meaning
STAT CLR	Status Clear
LIN	Calibrate - Linear
INV	Invert
HI LIM	Upper Limit
LO LIM	Lower Limit
	Rising Edge Alarm
	Falling Edge Alarm
LIMS	Limits On/Off
SHFT	Shift
ACK	Acknowledge
MAINT O'RIDE	Maintenance Override

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The MRC-1 is controlled by means of key sequences. If an erroneous or meaningless key sequence is entered, an "E" appears in the value/edit display for 2 seconds.

Examples of this:

1. "SHFT 9"

Undefined - Causes "E"

2. "LIN"

Attempt to calibrate telemetry channel without entering a value.

3. "1 Ø Ø Ø LIN"

This is normally valid, but results in an "E" if an insufficient level is applied to the telemetry input at calibration time.

4.3 VALUE ENTRY KEYS

The value entry keys are the numeric keys $\emptyset-9$, the decimal point key ("."), and the minus sign key ("-"). Some MRC-1 functions, for example, calibrating telemetry channels, demand a value. Entry of values is made possible by the numeric, sign, and point keys. If a function requires a value, the value is entered before the function key is pushed. For example, to calibrate a telemetry channel at $1\emptyset\emptyset\emptyset$ in linear mode, push:

l Ø Ø Ø LIN"

As the value is entered, it appears in the value/edit display. If a mistake is made, the value entered may be cleared by pushing the acknowledge ("ACK") Key. When "ACK" is pushed, or the sequence is

complete, the value/edit display returns to indicating the value or status of the selected telemetry channel as calibrated.

The sign key may be pushed at any time up to the final function key; for instance:

"- 1 Ø Ø Ø LIN" and "1 Ø Ø Ø - LIN"

have the same effect, both calibrating the selected telemetry channel in linear mode at -1000.

Decimal points are entered by pushing "." at the proper point in the key sequence, for instance:

"1 Ø . Ø Ø - LIN"

calibrates the selected telemetry channel in linear mode at $-1\emptyset$. $\emptyset\emptyset$.

If more than four number keys are pushed, only the last four will be used. The excess number keys are shifted off the left end of the value/edit display and are lost as new keys are pushed.

For example:

"- 1 2 3 . 4 1 Ø . Ø \Im LIN" has the same effect as the example immediately preceding. Note that the sign is preserved during the entry.

4.4 SHIFT KEY

The shift key (at the lower right of the keypad) chooses the set of functions engraved on the metal part of the front panel rather than those inscribed on the keytops. The shift action is "Push-On/Push-Off" in nature, each push of the shift key reversing the set of functions selected.

The value/edit display visually indicates the presence or absence of a shift in a command line by a dot (similar in appearance to a

decimal point) at the far left end, to the left of the sign position.

Example to illustrate use of shift key:

"1 Ø Ø Ø SHFT LIN"

calibrates the selected telemetry channel at $1\emptyset\emptyset\emptyset$ in power mode, since "POWER" is engraved on the front panel above the "LIN" key. (This will henceforth be shown in the manual as:

"1 \emptyset \emptyset \emptyset SHFT POWER" using the name of the actual function selected to avoid confusion.)

As further example:

"1 Ø Ø Ø SHFT SHFT LIN"

. calibrates in linear mode since the first push of the shift key selects the "UPPER CASE" power function and the second push reselects the "LOWER CASE" linear calibrate function.

4.5 FUNCTION KEYS

Function keys are always the last keystroke in a key sequence - the effect of the key sequence takes place immediately when a function key is pushed. The various remote terminal functions that are performed by each function key is defined below.

4.5.1 "CH" Channel Key

The "CH" (Channel) key is used to change the selected channel. For example, entering:

"1 7 CH"

Makes 17 the selected channel. "17" will appear in the channel display, and if analog input 17 has been calibrated its current value

will appear in the yalue/edit window. Status Channel 17 may have its latch, invert, or alarm attributes changed. Where applicable, all key sequences will apply to Channel 17.

Pushing the "CH" key with no preceding value will advance the channel by one. Continuing the above example, if we then enter:

"CH"

we will advance to Channel 18. If the selected channel is 32 entering:

"CH"

will make 1 the selected channel.

4.5.2 SITE Key

The "SITE" key is used to assign a different site number to the remote terminal than the one set at the factory or programmed at the rear of the front panel. For example, entering:

"8 SITE"

will make the remote terminal respond as Site 8 rather than its factory-assigned site number. The control terminal will then select this terminal when Site 8 is selected for display. It should be stressed that each remote terminal should have a different site number. If there are two terminals set to the same site number, the system cannot operate.

In the event of a power failure where memory has not been preserved, the remote terminal will, of course, be re-initialized to its factory-assigned site number, regardless of previous use of the site key.

4.5.3 Latch, Invert, L., Keys

The "LATCH", "INVERT", " (Falling Edge Alarm), and " (Rising Edge Alarm) functions are used to assign and remove attributes for selected status channels. Each of these functions is Push-On/Push-Off in nature. The first time the function is invoked the attribute is added, the second time it is removed, etc. The current status of each of these attributes for the selected channel is displayed on the corresponding green status LED's. For each of these functions, the status channel affected is the channel selected for display (as shown in the channel window).

The invert attribute reverses the external value applied to a status channel before it is displayed. If the external state of status Channel 1 is "OFF" and Channel 1 is assigned an invert attribute, the LED corresponding to status Channel 1 will be lit.

The latch attribute causes a status channel to remain in the "ON" condition after a rising edge (after inversion if applicable) is detected. Subsequent edges are disregarded. The status-clear function returns all latched channels to the "OFF" state until the next rising edge. Alarms and muting are invoked on the basis of status value as modified by latch and inversion.

The "____" (Falling Edge Alarm) attribute causes an alarm to occur if a falling edge is detected. Alarms are more fully described in the section describing the "ACKNOWLEDGE" function.

The "____" (Rising Edge Alarm) attribute causes an alarm to occur if a rising edge is detected. Note that if a channel has both "___" and "___" attributes, any edge at all will trigger an alarm.

Examples:

"INV"

reverses the current status of the invert attribute for the selected channel.

"SHFT LATCH"

reverses the latch attribute.

н

reverses the " -_ " attribute.

"SHFT ____"

reverses the "___ attribute.

"SHFT STAT CLR"

releases all latched status channel to the "OFF" state.

Numerical values preceding the function keys in these cases are meaningless, and such key sequences are rejected with an "E". For example:

"1 INV"

does not invert status Channel 1, but rather results in "E" being displayed for two seconds. If Channel 1 is to be inverted, Channel 1 should first be selected using the "CH"key.

4.5.4 "LIN", "POWER" Keys

The "LIN" (linear-calibration) and "POWER" functions are used to calibrate the selected telemetry channel. Linear calibration implies that a change in the external value results in a directly proportional change in the display. For example, if 3 volts are applied to telemetry input 1, and 1 is the selected channel, and

"l Ø Ø LIN"

is entered, whenever 3 volts is again applied, " $1\emptyset\emptyset$ " will be displayed. If 1.5 volt is applied, " $5\emptyset$ " will be displayed, etc.

Power calibration is similar to linear calibration, but the change in displayed value changes as the square of the change in applied value. If 3 volts are applied as before, and

"1 Ø Ø SHFT POWER"

is entered, whenever 3 volts are applied, "løø" will be displayed, just as above. But if 1.5 volt is applied, since the applied value has been halved (multiplied X .5), "25" is displayed (since the square of .5 is .25). Similarly, if 6 volts are applied, "4øø" is displayed.

"INDIRECT METHOD" calibration is also possible, by the convention of entering a negative initial value and choosing power calibration. (A negative number cannot be displayed in a power calibrated channel since no real number may be squared with the result a negative number.) "INDIRECT METHOD" calibration displays a result proportional to the values of the two preceding telemetry channels. For example, if we apply 3 volts to telemetry input 1 and 2 volts to telemetry input 2 and then select Channel 3 for display, and then enter:

"- 1 Ø Ø . Ø SHFT POWER"

Channel 3 will then be calibrated in "INDIRECT METHOD" mode. Whenever the product of levels applied to Channels 1 and 2 equals 6, $1\emptyset\emptyset.\emptyset$ " will be displayed. If we then apply 1 volt to each channel, the product is one sixth of what it was at calibration time, and so one sixth of $1\emptyset\emptyset.\emptyset$, or 16.7 is displayed.

It is good practice to calibrate telemetry inputs with as large as possible a value applied to the input. It is better to apply 5 volts and calibrate than to apply 1 volt and calibrate. This is because analog-to-digital converters return an integer number, proportional to the level applied. So lower levels cause numbers with fewer significant digits to be returned. The calculations for calibration of necessity have a larger percentage error at low values.

For this reason, the MRC-1 will not permit calibration to be made with less than about 256 millivolts applied to the telemetry input. This insures an acceptable level of accuracy. (Better, normally much better, than \emptyset .5%.) An attempt to calibrate with an insufficiently large level results in "E" being displayed for 2 seconds.

4.5.5 LOW LIM, HI LIM Keys

Each telemetry channel may be assigned an upper lmit and a lower limit. If limit checking has been enabled and the telemetry channel as calibrated is found to violate one of the limits, an alarm is initiated.

Examples:

"1 Ø Ø Ø LOW LIM"

establishes 1000 as the lower limit for the selected channel.

"1 Ø 5 Ø HI LIM"

establishes 1050 as the upper limit for the selected channel. The limits may be displayed by omitting to enter the value. Continuing the preceding example, pushing:

"LOW LIM"

will display "løøø for two seconds, and pushing

"SHFT HI LIM"

will display "1050 for two seconds.

Once established, limits may be removed by entering \emptyset as the limit. Entering:

"Ø LOW LIM"

will remove any lower limit established for the selected channel. Similarly,

"Ø SHFT HI LIM" will remove any upper limit.

If no limit has been established, " \emptyset " will be displayed as the limit when a display is requested.

This means, of course, that it is impossible to enter a limit of exactly zero, because the system interprets a limit of zero as no limit at all. This can be circumvented by entering a limit very close to zero. For example, entering:

". Ø Ø Ø l SHFT HİLIM"

makes a number very close to zero the upper limit, whereas entering:

"Ø SHFT HI LIM"

will make a "HIGH LIMIT ALARM" on the selected channel impossible, and is equivalent to no limit at all.

4.5.6 LIMS Key

Limit checking is enabled and disabled via the "LIMS" key. This key operates in a push-on/push-off manner, the first push enabling

limit checking, and the next push disabling limit checking. The current status is indicated by the "LIMITS ON" LED.

4.5.7 MAP Key

The MRC-1 Remote Terminal may administer up to 64 command outputs. To use these, each command output must first be associated with a channel. This process is called "MAPPING", and is normally done when the system is set up. Once "MAPPED", command outputs are activated by pushing the "RAISE" or "LOWER" keys while the appropriate channel is selected.

For example, suppose we select Channel 10 and enter:

"1 SHFT MAP RAISE"

("MAP" is the upper case of the "." key.) Then henceforth, whenever we select Channel 10 and push "RAISE", command output line "1" will be activated for as long as the key is pushed.

Now suppose we enter:

"2 SHFT MAP LOWER"

Similarly, whenever we select Channel 10 and push lower, command output "2" will be activated. Each channel may have two command outputs "MAPPED" to it in this manner. The mapping is removed by entering " \emptyset " as the command output number. Entering:

"Ø SHFT MAP RAISE"

will cause the "RAISE" key to have no effect. Likewise:

"Ø SHFT MAP LOWER" will cause the "LOWER" key to become undefined. Mapping may be displayed as follows: Entering:

"SHFT MAP RAISE"

will display the number of the command output that is assigned to the raise key, and:

"SHFT MAP LOWER"

will display the number of the command output that is assigned to the lower key. In cases where no mapping has been established, "Ø" will be displayed.

Above, we described momentary operation where pushing the "RAISE" or "LOWER" key causes a command output to be activated but only for as long as the key is pushed. Another mode is possible: "LATCH-ING" operation. In latching operation, one command output is assigned to a channel; pushing the "RAISE" key activates the command output to the on condition, and pushing the "LOWER" key turns the command output off.

Latching channels are established by specifying the same command output as both "RAISE" and "LOWER" outputs. For example, if we select Channel 11 and enter:

"3 SHFT MAP RAISE"

followed immediately by

"3 SHFT MAP LOWER"

then the command output 3 will be established as a latching command output for Channel 11.

As the final keystroke ("LOWER") is entered, the LED over the lower key is lit to indicating the latching channel is off. Pushing "RAISE" will turn the channel on and light the LED over the "RAISE" key.

Latching command channels are removed by entering \emptyset , exactly as is done for momentary channels. So:

"Ø SHFT MAP RAISE" followed immediately by;

"Ø SHFT MAP LOWER" will turn off the latching command output and will cause the "RAISE" and "LOWER" keys for the selected channel to again be undefined.

The above text has described the procedure to assign a command output channel. Command outputs that are used in the momentary mode may be assigned to more than one channel. This is particularly advantageous when a single control function - say a final amplifier controller - affects several measured parameters plate voltage, plate current, and measured power output. If these parameters were assigned to Channels 6, 7, and 8 respectively, and command output 4 connected to cause the power controller to increase, with command output 5 causing a decrease, then you can assign the command output 4 and 5 to each of the Channels 6, 7, and 8. To complete key sequence to accomplish this assignment is:

0	ĊН		
4	SHIFT	MAP	RAISE
5	SHIFT	MAP	LOWER
CH			
4	SHIFT	MAP	RAISE
5	SHIFT	MAP	LOWER
CH			
4	SHIFT	MAP	RAISE
5	SHIFT	MAP	LOWER

Then, regardless of which of the three channels is selected for display of the telemetry value, activating the RAISE or LOWER keys will cause the power controller to function appropriately.

4.5.8 MUTE Key

The "MUTE" function is used to enable and disable limit checking on the individual telemetry channels, under the control of a status input. Suppose we select Channel 9 and enter:

"3 Ø SHFT MUTE"

then, Status Channel 3Ø will control limit checking on telemetry Channel 9. Whenever Status Channel 3Ø (after latching and inversion, if specified) is OFF, limit checking on telemetry Channel 9 will cease.

When Status Channel 3Ø LED goes ON again (after latching and inversion, if specified), limit checking resumes after a four-second delay.

In this manner, any telemetry channel may have any status input assigned to it as a mute channel.

A mute channel may be removed by entering \emptyset instead of a valid. status channel number; i.e., entering:

"Ø SHFT MUTE"

will cause the selected channel to have its mute assignment removed.

Mute assignments may be displayed by entering:

"SHFT MUTE"

If no mute assignment has been made for the selected channel, " \emptyset " will be displayed.

Note that it is possible to assign more than one telemetry channel to a single status input for muting purposes. All of the telemetry

channels for the main transmitter can be assigned to one status input that indicates the main transmitter is operational, and all telemetry channels for a backup transmitter assigned to a second status channel that indicates the backup transmitter is operational. Telemetry channel alarms will then only occur when the corresponding transmitter is operational. Depending upon how the status inputs are derived from the transmitter, you may want to have an alarm indicated by the change of state of the status channels themselves. I.E., it is possible through the use of the mute function and the manner in which the status used to operate the mute function to have a transmitter fail and no alarm indication. Because of the wide varity of transmitters in use, it is not possible to give specific details. The user must select his best method of incorporating this function.

4.5.9 ACK Key

The "ACK" (acknowledge) key is used to clear alarms. At the remote terminal, the following conditions cause alarms:

- A status channel with "falling edge" attribute experiences a falling edge.
- A status channel with "rising edge" attribute experiences a rising edge.
- o An analog channel violates its lower limit.
- o An analog channel violates its upper limit.
- o The fail-safe time-out period has been intiated.
- o The fail-safe time-out period has expired.

When an alarm occurs, the audible alarm sounds (if it has been enabled via the rear-panel socket) and the channel display flashes to indicate

the alarm. This will continue until "ACK" (acknowledge) is pushed.

Once "ACK" has been pushed, the system automatically selects the channel where the alarm condition was detected. (If several alarms have occurred, the channel where the first alarm occurred is selected.) The alarm-causing condition may now be observed on the indicator LED's as follows"

- o If a status alarm has occurred, the appropriate status LED will be flashing at 2 Hz.
- o If a telemetry input has gone below its upper limit, the "LOW" LED will be flashing at 2 Hz.
- If a telemetry input has risen above its upper limit, the "HI" LED will be flashing at 2 Hz.

The second push of the "ACK" key clears the alarm, causing the flashing to end.

For example, suppose Channel 10 is selected when telemetry Channel 3 falls below its lower limit. First the audible alarm sounds if it has been enabled, and the channel display starts flashing to indicate the presence of the alarm. To examine the alarm, push "ACK". Then the sonalert is switched off and the system selects Channel 3. We see the "LOW ALARM" LED flashing at 2 Hz, indicating that the alarm arose because Channel 3 fell below its lower limit. Pushing "ACK" again causes "LOW ALARM" to cease flashing. If the low limit is still being violated, the LED will remain steadily on; if it has risen back within limits, the LED will go off.

Suppose a little later, status Channel 6, which has been given a falling edge alarm attribute, changes from "ON" to "OFF". Then the sonalert will again come on, and the channel display will again flash. After pushing "ACK", the audible alarm is switched off, the

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system selects Channel 6, and the LED displaying Status Channel 6 may be observed flashing at 2 Hz. When "ACK" is pushed the second time, the flashing ceases.

To summarize, each alarm is cleared by pushing "ACK" twice. The first push turns off the audible alarm, changes channels, and displays the alarm condition via flashing lights. Acknowledged limit violations continue to be displayed via steadily-ON (not flashing) LED's, until the telemetry value has returned within limits (or limit checking is disabled, or mute status begins).

4.5.10 Lamp Test

The Lamp Test function tests the LED's and the seven-segment displays on the front panel. "LAMP TEST" is a push-on/push-off function - the first push begins the test; the second push ends it.

4.5.11 Maintenance Override

The Maintenance Override function is used to establish local control of the Remote Terminal. If the system is not in Maintenance Override mode, raise and lower commands from the Remote Terminal are disabled.

Conversely, if the system is in Maintenance Override mode, raise and lower commands from the Control Terminal are inhibited and any failsafe condition is discontinued.

Maintenance Override status is invoked and ended by the "MAINT O'RIDE" key. Current Maintenance Override status is indicated by the LED over the function key. If the system is in a Maintenance Override status, the LED will be lit.

4.6 FAILSAFE FUNCTIONS

MRC-1 Remote Terminals provide a "FAILSAFE" output as required in broadcast applications. The failsafe output is activated 45 seconds after signals from the Control Terminal cease ("CONTROL FAILSAFE"). The failsafe output is ended immediately on receipt of a valid message from the Control Terminal, or when maintenance override mode is entered.

In FCC television broadcasting applications, a second type of "FAILSAFE" output is required: If aural plate voltage, aural plate current, aural power output, or visual power output metering vanish for an one hour period, a failsafe output is required ("TELEMETRY FAILSAFE").

A telemetry failsafe is also required if the Remote Terminal is unable to communicate with the Control Terminal for an one hour period.

At the MRC-1 Remote Terminal, there is a single failsafe output which is activated for either or both types of failsafe.

"TELEMETRY" failsafe will occur only if certain key sequences activating it have been entered. These will be demonstrated by example:

Suppose Telemetry Input 13 is aural plate voltage, input 15 is aural plate current; input 17 is aural power output, and input 25 is visual power output. We may initiate failsafe monitoring of these four channels by the following four key sequences:

"1 3 SHFT 1"

This specifies that Telemetry Channel 13 shall be monitored as the first telemetry failsafe channel.

"1 5 SHFT 2"

This specifies that Telemetry Channel 15 shall be monitored as the second telemetry failsafe channel.

"1 7 SHFT 3"

This specifies that Telemetry Channel 17 shall be monitored as the third telemetry failsafe channel.

"2 5 SHFT 4"

This specifies that Telemetry Channel 25 shall be monitored as the fourth telemetry failsafe channel.

All four telemetry failsafe channels having been established, monitoring commences, and should less than about 256 mV be observed at any of the four specified telemetry inputs, the one-hour countdown will begin.

Telemetry failsafe channels may be removed and displayed in a manner exactly analogous to muting, limits or mapped commmand channels; therefore:

"Ø SHFT 1"

removes the first telemetry failsafe channel and ends failsafe monitoring. Similarly:

"Ø SHFT 2" "Ø SHFT 3" "Ø SHFT 4"

remove the other channels.

Entering "SHFT 1", "SHFT 2", "SHFT 3", "SHFT 4" will display those telemetry failsafe channels which have been established previously, or " \emptyset " if none has been established. If any or all of

the four telemetry failsafe channels have not been established, then telemetry failsafe is inhibited, and only control failsafe is possible.

Selecting "CHANNEL ZERO" will result in a display of the remaining time until failsafe in the VALUE-EDIT window, i.e., entering

"Ø CH"

will cause the remaining time to be displayed. This will, of course, normally be "6 \emptyset ", indicating that all is well. Should telemetry failsafe be inhibited, "CHANNEL ZERO" may not be selected; "E" will be displayed if this is attempted.

In the event of any kind of failsafe, all command outputs are inhibited. As described above, putting the terminal into Maintenance Override status ends all failsafe conditions and re-enables command outputs.

When Maintenance Override mode is ended, all timers are reset, so there is once again a 45-second wait until control failsafe and an one-hour wait until telemetry failsafe, regardless of past conditions at the Remote Terminal. In addition, should all four telemetry failsafe channels vanish, then telemetry failsafe is ended.

4.7 MRC-1 REMOTE REFERENCE DATA

The following is a condensed description of MRC-1 Remote Terminal key sequences and functions for quick reference purposes.

SELECT NEW CHANNEL:	Х	Х	CH
ADVANCE ONE CHANNEL:			CH
SELECT NEW SITE:	х	SI	TE
INVERT/DEINVERT STATUS CHANNEL:		I	NV

LATCH/UNLATCH STATUS CHANNEL SHFT LATCH ADD/REMOVE FALLING EDGE ALARM ADD/REMOVE RISING EDGE ALARM SHFT RELEASE ALL LATCHED CHANNELS SHFT STAT CLR CALIBRATE, LINEAR MODE XXXXLIN CALIBRATE, POWER MODE X X X X SHFT POWER (Sign of X X X X must be positive) CALIBRATE, INDIRECT MODE: - X X X X SHFT POWER (Sign of X X X X must be negative) Display will be proportional to product of two preceding channels. Channels 1 and 2 may not be calibrated in this mode. ESTABLISH LOWER LIMIT: X X X X LOW LIM (Point position of limit need not match point position of calibration) DISPLAY LOWER LIMIT LOW LIM REMOVE LOWER LIMIT Ø LOW LIM X X X X SHFT UPPER LIM ESTABLISH UPPER LIMIT: (Point position of limit need not match point position of calibration) DISPLAY UPPER LIMIT: SHFT UPPER LIM REMOVE UPPER LIMIT: Ø SHFT UPPER LIM ENABLE/DISABLE LIMIT CHECKING: LIMS ESTABLISH RAISE CHANNEL: X X SHFT MAP RAISE DISPLAY RAISE CHANNEL: SHFT MAP RAISE REMOVE RAISE CHANNEL: Ø SHFT MAP RAISE ESTABLISH LOWER CHANNEL: X X SHFT MAP LOWER DISPLAY LOWER CHANNEL: SHFT MAP LOWER REMOVE LOWER CHANNEL: Ø SHFT MAP LOWER

ESTABLISH LATCHING COMMAND CHANNEL: (Where X X in both lines is the channel to be made latching)	X X	X X	SHFT SHFT	МАР МАР	RAISE LOWER
RAISE:					RAISE
LOWER:					LOWER
TURN ON LATCHING COMMAND CHANNEL:					RAISE
TURN OFF LATCHING COMMAND CHANNEL:					LOWER
ESTABLISH MUTE CHANNEL:			хх	SHFI	MUTE
 A. Mute condition occurs when mute channel is "OFF" (after latch and invert, if applicable.) B. No limit checking during mute condition or for 4 seconds thereafter. 					
DISPLAY MUTE CHANNEL				SHFI	MUTE
REMOVE MUTE CHANNEL:			ø	SHFI	MUTE
 ACKNOWLEDGE ALARM: A. First push displays channel number and condition, silences audible alarm. B. Second push ends flashing alarm indication. C. In the case of limit violations, steadily-on alarm indication will persist until: analog value is back in bounds; or, mute status begins; or, limit checking is disabled. 				AC	K ACK
BEGIN LAMP TEST:				LAMP	TEST
BEGIN LAMP TEST: END LAMP TEST:				LAMP	TEST TEST
<pre>BEGIN LAMP TEST: END LAMP TEST: BEGIN MAINTENANCE OVERRIDE: A. Ends any failsafe condition, B. Inhibits any RAISE/LOWER commands from control end.</pre>			MAJ	LAMP LAMP INT C	TEST TEST 'RIDE
<pre>BEGIN LAMP TEST: END LAMP TEST: BEGIN MAINTENANCE OVERRIDE: A. Ends any failsafe condition. B. Inhibits any RAISE/LOWER commands from control end. END MAINTENANCE OVERRIDE A. Resets failsafe timers. B. Inhibits commands from remote end.</pre>			MA I	LAMP LAMP INT C	TEST TEST 'RIDE

1

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Telemetry failsafe takes place if the analog value on any established telemetry failsafe channel remains below about 0.3 yolts for 1 hour, or the Control Terminal fails to receive transmissions from the Remote Terminal for 1 hour. Telemetry failsafe ends if all four telemetry failsafe channels fall to zero.

DISPLAY TM FAILSAFE CHANNEL N:

REMOVE TM FAILSAFE CHANNEL N:

MISCELLANEOUS:

Control failsafe takes place if a Remote Terminal receives no successful communications directed to it for 45 seconds.

Alarms are disabled for 10 seconds after reset.

CALIBRATION OVERFLOW DISPLAY:

A/D SATURATION DISPLAY (6144 COUNTS)

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SHFT N Ø SHFT N

EEEE

5.0 INSTALLATION

5.1 INTRODUCTION

The purpose of this section is to provide installation details for the MRC-1 Remote Terminal. It also provides other data should the user expand or otherwise modify the system in the future.

CAUTION

ALWAYS REMOVE POWER FROM THE TERMINAL AND DISCONNECT THE BATTERY WHENEVER PRINTED CIRCUIT MODULES ARE REMOVED OR REPLACED IN THE UNIT. FAILURE TO OBSERVE THIS CAUTION MAY CAUSE DAMAGE TO ONE OR MORE MODULES.

5.2 PHYSICAL INSTALLATION

The MRC-1 is designed for industry standard RTMA rack mounting. It is suggested that the Remote Terminal be mounted in the rack at approximately 65 inches height for best operation accessibility. With the power supply shipping screw removed, insert the terminal in the rack or cabinet and install 10/32 x 1" screws with fiber washers through the oval holes in the chassis flanges. Torque screws firmly to provide a secure mounting. Once installed in the rack, all assemblies that normally require service can be removed without removing the chassis from the rack. The extender board is stowed to the left of the power supply. The flat ribbon cable between the front panel and CPU card may have to be disconnected to remove the extender board. At this time, remove the extender board and store in another location at the Remote Terminal site in order to provide maximum ventilation to the Terminal.

5.3 PHONE LINE CONNECTION - 4-WIRE

If you are using a 4-wire interconnect service, the pair of wires

MRC-1 REMOTE TERMINAL Rev. 10 Nov. 1980 to the Control Terminal is connected to terminals 4 and 6 of the Modem Telco Interface card (third from right assembly at rear of unit). The pair from the Control Terminal is connected to terminals 1 and 3. Note that the Modem Telco Interface contains fuses mounted internal to the card. Should you suspect that, as a result of lightning strike, the phone lines have been hit, remove the two screws securing the Modem Telco Interface card and check and/ or replace fuses, as required.

5.4 PHONE LINE CONNECTION - 2-WIRE

If you are using a two-wire interconnect arrangement, place a short jumper between terminals 2 and 4. Then, connect the telephone line to terminals 1 and 5 of the Modem Telco Interface card. See the preceding paragraph for lightning protection fuses.

5.5 FM SUBCARRIER INTERCONNECT

BNC connector J3 is the output of the Remote Terminal and is connected to the equipment over which the subcarrier signal will be transmitted. A BNC connector J2 is used for the subcarrier data being received from the Control Terminal. Note that the components of the subcarrier interface module are frequency dependent. Should your requirements for subcarrier frequencies change in the future, some changes in component values may be required. The component values for various bands of subcarrier frequencies are detailed in Section 8 for the subcarrier interface card, if ordered as part of the system.

5.6 MIXED COMMUNICATIONS

If the system is ordered with mixed communications functions; i.e., telco in/subcarrier out, or telco out/subcarrier in, the connection procedure is similar to that outlined for the previous methods

MRC-1 REMOTE TERMINAL 5-2 Rev. 9 June 1980 of communications link interconnection. The subcarrier function (either in or out, as appropriate) is a BNC connector while the telephone circuit is a terminal block connection.

5.7 AUDIBLE ALARM

The control of the audible alarm of the Remote Terminal is accessed through pins 5 and 6 of Jl on the CPU interface card (right module viewed from rear of chassis).

Several alternatives are available to the user. The simplest is to jumper pins 5 and 6 on the connector. In this case, the audible alarm will always be activated when an alarm condition is detected. In the event that the Remote Terminal is located in a studio booth, it is possible to have external control of the audible alarm so that it will be muted when a mike is active if those facilities are available in the studio. Figure 5.1 indicates a typical arrangement of muting the alarm when mikes are active.



RY IS NO WHEN MIKE IS ACTIVE.

RY IS NO WHEN NO MIKES ARE ACTIVE.

FIGURE 5-1 AUDIBLE ALARM CONNECTIONS

The relay contact (supplied by user) is assumed to be N.O. when any mike is active and N.C. when no mikes are active. The signal labeled to EXTERNAL INDICATOR may be used to operate a usersupplied indicator for an alarm indication.

NOTE: The "ALARM DRIVE" and "INT ALARM" connections are each associated with a trace which runs across the C.P.U. Interface Board, through the Mother Board, across the C.P.U. Board and eventually terminates at the Alarm Driver on the front panel.

> Because these connections are generally used at a studio location, and seldom in an R.F. environment, no filtering was included for them.

Considering the susceptibility of any digital logic system to R.F. spikes, it is our suggestion that all MRC-1 customers who use these connections for remote alarms or remote alarm enable switches in an R.F. environment should incorporate a small LC filter in order to isolate the MRC-1 from R.F. interference. It will be easiest to do this by locating the inductors and capacitors near the female plug on the cable when the cable for this jack is made up. Below is a diagram of the procedure to follow.



MAI Part Numbers: 14-287.25, 4020343, Inductor R.F. 6.80 µH 05-397.25, 4310207, Capacitor .1 µF/50 V 20%

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5.8 EXTERNAL BATTERY

The Remote Terminal normally requires the use of an external battery to maintain the contents of memory in the event of a power failure. The battery is supplied to maintain memory contents for a period of time during a power failure (not complete terminal operation, however). To connect the battery, first attach the battery holder to the chassis, insert battery and connect the terminals in accordance with Figure 5.2. Batteries are always shipped disconnected to prevent discharge during transit. The positive (+) battery terminal is connected to the red binding post terminal and the negative (-) is connected to the black binding post.

The user may use other batteries in place of the one supplied. In this case, the maximum voltage that may be applied to the terminal posts is 7.0 volts. The nominal design voltage is 6.0 volts, with a float charge of 6.7 volts and a maximum float charge current of 75 ma. If you use an external battery and charger, the charger voltage <u>must never</u> exceed 7.0 volts and must be filtered with no more than 10 mV ripple.

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FIGURE 5-2 BATTERY INSTALLATION REMOTE TERMINAL

5.9 SITE SELECTION

It is necessary to program the Remote Terminal with the number of the site for the terminal. It is assumed that sites are numbered sequentially from 1 to N where N is the last site number with no numbers skipped. Note that early production units use a soldered diode matrix instead of the switches. Refer to Figure 5.3 for location and connection chart.

The switches are set as shown in the table below for the number of sites in the system:

SITE

SWITCH POSITIONS

	1	2	3	4
1	OFF	OFF	off	OFF
2	ON	OFF	OFF	OFF
3	OFF	ON	OFF	OFF
4	ON	ON	OFF	OFF
5	OFF	OFF	ON	OFF
6	ON	OFF	ON	OFF
7	OFF	ON	ON	OFF
8	ON	ON	ON	OFF
9	OFF	OFF	OFF	ON

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DIODES INSTALLED (Diodes are 1N270 or equivalent)

SITE	SAL	SA2	SA3	SA4
1	None	None	None	None
2	Diode	None	None	None
3	None	Diode	None	None
4	Diode	Diode	None	None
5	None	None	Diode	None
6	Diode	None	Diode	None
7	None	Diode	Diode	None
8	Diode	Diode	Diode	None
9	None	None	None	Diode

FIGURE 5.3

SITE IDENTIFICATION DIODES (Early Production Units Only)

5.10 FAIL SAFE

The fail-safe output is controlled by a relay capable of switching a load of up to 24 VDC at currents of up to 1 ampere. During normal operation the relay will close a connection between pins 3 and 4 of the rear connector on the CPU Interface Board. When MRC-1 power is removed or a fail-safe condition occurs, the relay will open. Figure 5-4 illustrates a typical application of the fail-safe output.

Inductive loads (relay coils, etc.) should have a "clamping" diode wired across them to inhibit negative voltage spikes. External relays should be used when it is desired to switch to greater loads (or AC loads which must have a Series R $(100\Omega)/C$ (luf) network across them).

These relays may also be interfaced with transistor-transistor logic (TTL) digital circuits. The relay contacts should be wired so that one side is referenced to the digital common (ground), and the other relay contact to the digital input. A pull-up resistor may be necessary, and it is advisable to wire a 1 µf capacitor and 100 ohm resistor (in series) across the relay output to suppress contact bounce. For further details, refer to Section 8, CPU Interface.



FIGURE 5-4 TYPICAL FAIL SAFE OUTPUT

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5.11 MAINTENANCE OVERRIDE

An external indicator is provided in the form of a relay to provide remote indication that the Remote Terminal has been placed in the Maintenance Override mode of operation. This indication is normally used to illuminate a light near the exit of the transmitter room to warn the operator the Remote Terminal has been left in the Maintenance Override Mode. When in the Maintenance Override mode, no commands are accepted by the Remote Terminal from the Control Terminal; hence, you may save yourself a trip to the transmitter site by getting into the habit of removing the Remote Terminal from the Maintenance Override mode before you leave. There is no way to exercise this function from the Control Terminal. You may use a relay or TTL logic for indirect control of the lamp, in which case the wiring illustrated for the failsafe output can be followed (Figure 5-4), except terminals 1 and 2 of J1 are used. A small lamp may be driven directly, as illustrated in Figure 5-5.



FIGURE 5-5 TYPICAL MAINTENANCE OVERRIDE CONDITION



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5.12 INPUT/OUTPUT CONNECTORS

The connectors for telemetry (analog), status and commands may now be wired up. A definite wiring pattern has been established for the telemetry (analog) input, TTL status input, optically isolated status input, open collector command output, and the optically isolated command output printed circuit modules through both the filtered and unfiltered interface cards. The most positive voltages of the 16 inputs or outputs are wired consecutively from pins 1 through 16. The negative (or ground return) input or output is wired consecutively from pins 20 through 35. This allows twisted pairs to be used as connections to the modules to reduce external field noise pickup and, at the same time, allows a simple pattern to the connection with the two leads at a slight diagonal on the connector. Proper grounding and shielding techniques should be followed throughout.

For those applications requiring control of high voltage or AC power, a relay isolated command output option is available. The connection from the relay panel to a command output module through an interface card has been pre-wired and only requires it be plugged in.

5.3 INSTALLATION COMPLETION

This completes installation of a Remote Terminal. Power may now be applied to the terminal. Depress the "ACK" key on the Remote Terminal front panel in order to clear the "cold start" condition which occurs whenever power is applied to the Remote Terminal after the contents of memory have been lost. You will observe the three power indicator LEDs on the internally-mounted CPU board illuminate. After a short period, the Reset LED on the CPU board will go out. After a short delay (less than 1 second), the Output and Input LEDs on the modem board should begin to flicker indicating that data is being sent and received. The modems are factory

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adjusted for +0.0 dBm output level and a -16.0 dBm receive level. Should the actual levels of your system be radically different, some adjustment of the send and receive levels may be required. Refer to Section 8 for wireline modem and/or subcarrier modem adjustments. External loads if run from DC must have a damping diode across them (e.g. DC relay coil). Connect the diode so that it will normally not conduct. External loads, if AC, must have a series R.C. network across them. (Values of 1 µf and 100Ω are suggested.)

At this point, you may enter command sequences at the keyboard to calibrate telemetry (analog) channels, observe and set up status channels, and to set up command outputs.

For the user's convenience, a set of tables (Tables 5-1, 5-2, and 5-3) are provided that allow the user to record the manner in which he has set up the Remote Terminal. You may reproduce these forms as required for your purposes.

Each of the 32 telemetry channels is indicated on the left side of each table and, when completed, they will provide the user a guide for future reference as to how the Remote Terminal was set up. Most column headings are directly related to the set up functions outlined in Section 4 of this manual. The columns labeled "+ Input" and "- Input" are filled in to indicate the connector pins at the interface card. For the command outputs, since the output is mapped to the telemetry channel, the terminals actually connected must be inserted by the user. In Table 5-1, the column labeled "TYPE" is for the type of calibration; i.e., linear (L), power (P), or indirect (I).

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TELE- METRY METRY DESCRIPTION OF VALUE MEASURED TYPE L, P, I NOMINAL CALIBRATION HIGH LIMITS LOW LIMITS MUTED BY STATUS + - 1 - - 1 20 1 20 3 - - - 1 20 1 20 4 - - - 4 23 22 1 20 <th>-</th> <th></th> <th>LEPELL</th> <th>(ANALOG) DAI</th> <th>1</th> <th></th> <th></th> <th></th> <th></th>	-		LEPELL	(ANALOG) DAI	1				
METRY CHANNEL DESCRIPTION OF VALUE MEASURED L, P, I TYPE L, P, I NOMINAL CALIBRATION HIGH LIMITS LOW LIMITS MUTED BY STATUS + - 1 - - - 1 20 1 20 2 - - - - - 2 2 1 20 3 - - - - 3 22 2 4 - - - - 4 23 5 - - - - 6 25 7 - - - - 9 28 10 - - - 10 29 11 - - - 11 30 12 - - - 11 32 14 - - - 14 33 15 - - - 14 33 16 -	TELE-								
CHANNEL L, P, I CALIBRATION LIMITS LIMITS STATUS INPUT INPUT 1 - - - 1 20 2 - - - 2 1 20 3 - - - 2 2 1 20 3 - - - 4 22 21 3 - - - 4 22 21 4 - - - 4 22 21 5 - - - - 4 22 6 - - - - 6 25 7 - - - - 8 27 9 - - - 10 29 28 10 - - - 11 30 12 - - - 12 31	METRY	DESCRIPTION OF VALUE MEASURED	TYPE	NOMINAL	HIGH	LOW	MUTED BY	+	-
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	CHANNEL		L,P,I	CALIBRATION	LIMITS	LIMITS	STATUS	INPUT	INPUT
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	1							1	20
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	2							2	21
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	3							3	22
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	4			1				4	23
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	5							5	24
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	6							6	25
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	7							7	26
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	8		1					8	27
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	9							9	28
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	10			2.1	1			10	29
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	11							11	30
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	12							12	31
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	13							13	32
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	14							14	33
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	15							15	34
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	16	· · · · · · · · · · · · · · · · · · ·						16	35
18 2 21 19 3 22 20 4 23 21 5 24 22 6 25 23 7 26 24 8 27 25 9 28 26 10 29	17							1	20
19 3 22 20 4 23 21 5 24 22 6 25 23 7 26 24 8 27 25 9 28 26 10 29	18							2	21
20 4 23 21 5 24 22 6 25 23 7 26 24 8 27 25 9 28 26 10 29	19	•						3	22
21 5 24 22 6 25 23 7 26 24 8 27 25 9 28 26 10 29	20							4	23
22 6 23 7 24 8 25 9 26 10	21							5	24
23 7 26 24 8 27 25 9 28 26 10 29	22							6	25
24 8 27 25 9 28 26 10 29	23							7	26
25 9 28 26 10 29	24				* · · · · · · · · · · · · · · · · · · ·			8	27
26 10 29	25 .	*	1					9	28
	26							10	29
27 11 30	27	•				1		11	30
28 12 31	28							12	31
29 . 13 32	29			19 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1				13	32
30 14 33	30				2 P			14	33
31 15 34	31							15	34
32 16 35	32		1					16	35

TELEMETRY (ANALOG) DATA

TABLE 5-1

TELEMETRY (ANALOG) DATA TABLE

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STATUS DATA

$\begin{array}{c c c c c c c c c c c c c c c c c c c $	TELE- METRY CHANNELS	DESCRIPTION OF SOURCE OF STATUS	INVERT	LATCH	ALARM	ALARM	+ INPUT	- INPUI	2
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	1						1	20	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	2						2	21	Ĺ
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	3						3	22	Ĺ
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	4						4	23	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	5						5	24	Ê -
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	6						6	25	Ч
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	7			1	1.		7	26	#
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	8						8	27	19
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	9						9	28	AF
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	10		1 4 P. 4 C. 1				10	29	0
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	11			· · · · · · · · · · · · · · · · · · ·	4. 4		11	30	Ê.
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	12				1		12	31	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	13						13	32	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	14				1		14	33	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	15		×		1	1	15	34	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	16						16	35	-
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	17				1.4		1	20	1
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	18						2	21	1
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	19				·		3	22	1
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	20						4	23	
22 6 25 24 7 26 25 9 28 27 11 30 28 113 32 30 14 33 31 15 34 32 16 35	21						5	24	
23 7 26 24 8 27 25 9 28 26 11 30 28 112 31 30 14 33 31 15 34 32 16 35	22					1	6	25	1
24 8 27 25 9 28 26 - 10 29 27 11 30 29 13 32 30 14 33 31 15 34 32 16 35	23					1	7	26	0
25 9 28 27 10 29 28 11 30 29 13 32 30 14 33 31 15 34 32 16 35	24		8 4 4			1	8	27	#
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	25						9	28	19
27 11 30 28 12 31 29 13 32 30 14 33 31 15 34 32 16 35	26				-	1	10	29	A
28 12 31 30 13 32 31 15 34 32 16 35	27						11	30	10
29 13 32 30 14 33 31 15 34 32 16 35	28		1			1	12	31	1
30 14 33 31 15 34 32 16 35	29			1		1	13	32	t
$\begin{vmatrix} 31 \\ 32 \end{vmatrix}$ 15 34 16 35	30	4			1	1	14	33	1
	31						15	34	1
	32						16	35	1

TABLE 5-2

STATUS DATA TABLE

TELE-		RAISE COMMAND				LOWER COMMAND	1	
METRY	OUTPUT	FUNCTION PERFORMED	+	-	OUTPUT	FUNCTION PERFORMED	+	-
CHANNEL	NUMBER		OUT	OUT	NUMBER		OUT	OUT
1					· · · · · · · · ·			
2			-					
3								
4								
5								
6		and the second			and the second			
7								
8						,		
9								
10								
11								
12								
13								
14								
15								
16								
17								
18								
19								
20							·	
21								
22								
23								
24								
25								
26								
27			1					
28	*		1					
29			1		1			
30			1					
31								
32			1		1			

TABLE 5-3

COMMAND OUTPUT TABLE

 $\hat{\mathbf{x}}$

6.0 HARDWARE/SOFTWARE OVERVIEW

6.1 INTRODUCTION

The purpose of this section is to provide the user with a general overview of the hardware and software of the MRC-l Remote Terminal. It is not a detailed explanation of microprocessors, but rather, the basic design concepts incorporated into the MRC-l. The user is referred to many excellent texts on microprocessors including M6800 Microcomputer System Design Data, published by Motorola, Inc.

Figure 6-1 is a block representation of the major components of an MRC-1 Remote Terminal. The chassis houses the assemblies. A mother board is located approximately three quarters of the way back from the front of the terminal. The functional cards (i.e., CPU, memory, modem, options, etc.) plug into the mother board from the front.

The user's connection to a functional card occurs through an interface card that plugs into the rear of the mother board. The interface card provides the physical connectors, terminals or barrier strips to which the user makes his connection. In some cases, there can be several interface cards that can be associated with a given functional card. For example, a modem card can have one of four interface cards depending upon the type of communications circuit. In other cases, the same interface card can serve several functional cards. As an example, the Filtered Interface card is normally used with the Telemetry (Analog), Status and Command cards.

6-1

The mother board provides;

- o power distribution to all cards,
- o interconnection between functional and interface cards,

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FUNCTIONAL CARDS INTERFACE CARDS FRONT ACCESS REAR ACCESS FRONT PANEL SLOT I + BATTERY CPU CPU > ALARM INTERFACE FAILSAFE > MAINT SLOT 2 8 X 4 BUS MEMORY DATA, CONTROL, ADDRESS, POWER SLOT 3 TELCO OR COMMUNICATIONS MODEM SUBCARRIER CIRCUIT(S) INTERFACE SLOT 5,6 . ANALOG FILTERED ANALOG INPUTS INPUT INTERFACE 16 OR 32 SLOT 8,9 50 TTL OR STATUS FILTERED INPUTS OPTICAL INSULATED 16 OR 32 INTERFACE STATUS INPUT SLOT 11, 12, 13, 14 OPEN COLLECTOR FILTERED OR COMMAND OUTPUTS OPTICAL INSULATED 16,32,48, OR 64 INTERFACE COMMAND OUTPUT POWER SUPPLY AC MAINS 120 / 240 AC + 5, +15, -15 VDC

FIGURE 6-I REMOTE TERMINAL BLOCK DIAGRAM

and distribution of control, data, and address
 busses to the functional cards.

All modules and subassemblies, except for the mother board, are removable without disassembling the chassis.

6.2 BUS ARCHITECTURE

The MRC-1 is designed using a bus structure which allows flexible configuration changes. Fifty control signals and power lines are bussed to each card slot. Cards are accessed by digital words on the address bus and do not require an absolute physical slot to be assigned for each card. An exception to this rule is the CPU card, which must always be plugged into the first slot to obtain an AC power sample for the real-time clock and power fail circuits.

Each printed circuit card edge connector has 100 pins. The even pins contain the common bus signals. The odd pins are used to communicate via interface cards to the external world through the rear panel. To prevent confusion, the even wire-wrap pins are sheared off during manufacturing, leaving only the odd pins for card input/output connections. Signal assignments for the connector pins are shown in Table 6-1.

Note that signal ground, +5, +15, and -15 voltages are available to both functional and interface cards.

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TABLE 6-1

MRC-1 BUS ARCHITECTURE

PIN	NAME	DESCRIPTION
1,2,3,4	GROUND	System common signal ground
5,6	PLUS 15V	Positive 15V supply Remote 1.5 amps capacity Control .8 amps capacity
7,8	NEGATIVE 15V	Negative 15V supply Remote 1.5 amps capacity Control .8 amps capacity
9,10	STANDBY 5V	5-volt supply back up by an external battery
12 14 16 18 20 22 24 26	DØ D1 D2 D3 D4 D5 D6 D7	Bidirectional 3-state data bus is used to transfer data between the microprocessor, its peripher- als and memory
28 30 32 34 36 38 40 42 44 46 48 50 52 54 56 58	AØ Al A2 A3 A4 A5 A6 A7 A8 A9 A10 A11 A12 A13 A14 A15	<pre>16-pin address bus Both memory and input/output devices are addressed using these lines.</pre>
60	*RESET	This active low input is used to reset and start the microprocessor

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TABLE 6-1 (continued)

PIN	NAME	DESCRIPTION
		from a power down condition, re- sulting from a power failure or an initial start-up of the pro- cessor. The signal is generated by the CPU interface card and is used to reset functions in the CPU and various cards that have reset capability.
62	Е	l MHz clock signal used to syn- chronize all system functions
64	R/*W	This output signals the peripherals and memory devices whether the CPU is in the READ (High) or WRITE (Low) state. The normal standby state of this signal is READ.
66	VMA	Valid Memory Address. This output from the CPU card indicates to peripheral devices that there is a valid address on the bus.
68	PRE	Input/Output Preselect. This line is high when the input/output de- vice address space is accessed.
70 -	RTC	Real Time Clock. A 50 or 60 Hz signal derived from the AC power line and used as a timing signal.
72	*DMA	Direct Memory Access. When this signal goes low, the CPU card re- leases control over the address bus.
74	BA	Bus Available. This signal will normally be in the low state; it will go to a high state to indi- cate that the microprocessor has stopped and the address bus is available. This will occur if the processor is in a HALT state, or if a WAIT instruction is en- countered by the microprocessor.

MRC-1 REMOTE TERMINAL

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TABLE 6-1 (continued)

PIN	NAME	DESCRIPTION
76	*HALT	When this signal is in the low state, all microprocessor acti- vity will be halted. In the HALT mode, the microprocessor will stop at the end of an in- struction, Bus Available will be at a high state, Valid Memory Address will be at a low state.
78	BAUD	19230 Hz square wave used to set the baud rate of ACIA's (Asyn- chronous Communications Inter- face Adapters). Data rates of 1200 or 300 baud are possible using this clock.
80	*INTØ	Lowest Priority
82	*INT1	Active low prioritized interrupts.
84	*INT2	When one of these lines goes to a low state, the microprocessor
86	*INT3	suspends its normal operation
88	*INT4	and begins servicing an interrupt routine. A higher priority rou-
90	*INT5	tine takes precedence over a
92	*INT6	lower priority.
94	*INT7	Highest Priority
96	*NMI	Non-Maskable Interrupt When this line is pulled to a low state, the processor completes its current instruction and then bran- ches to an interrupt routine. Interrupt cannot be disabled by setting a mask bit.
97 thru 100	PLUS 5V	Positive 5V power supply Remote: 6 amps Control: 3 amps

MRC-1 REMOTE TERMINAL

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6.3 SOFTWARE OVERVIEW

When power is restored to a Remote Terminal, there are two things that could have occurred. First, memory could have been lost because of an extended power interruption. If this condition is detected by the software, it is assumed that the Remote Terminal must be recalibrated prior to any use. This requires manual intervention. An alarm condition exists and must be acknowledged by an operator at the Remote Terminal before recalibration can proceed. During this period, the software determines the identification number of the Remote Terminal by reading the switches on the rear of the front panel. Note that each Remote Terminal must have a unique address.

If the Remote Terminal did not lose its memory data as the result of a power failure, a brief internal re-initialization cycle occurs where the software determines the number and type of modules that are in the Remote Terminal. This allows the user to add additional modules within the design capabilities at any time. Power must be turned off <u>and the battery disconnected</u> before removing or inserting printed circuit cards. When power is restored, the software takes inventory of what is currently available and adjusts its internal record keeping accordingly.

As the user performs setup key sequence functions, the data from the key sequence, i.e., telemetry (analog) calibration factors, limits, etc., are retained in the Remote Terminal memory. This data may be recalled by other key sequences either from the Remote or Control Terminals. The point to note is that all factors that affect a Remote Terminal are retained at that Remote Terminal.

Once the Remote Terminal is active, it is always listening to the communications circuit for a message addressed to itself from the Control Terminal. This is called a polling message. In response

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to the poll, the Remote Terminal sends a brief answer indicating whether or not an alarm condition exists at the Remote Terminal. For convenience of operation, the software in the Remote Terminal allows the Control Terminal user and the operator of the front panel independent display of all data concerning the Remote Terminal. The Control Terminal operator may view any telemetry channel at the same time the Remote Terminal user is displaying any other or the same telemetry channel. There is one function the Maintenance Override - which can be activated at the Remote Terminal to disable command activation from the Control Terminal. However, all other display functions at the Control Terminal are enabled.

Telemetry (analog) data is acquired in a cyclic sequence from the analog-to-digital (A/D) converters. When an A/D completes one conversion, the input number is incremented and the next conversion started while the previous conversion is applied through a digital filter and then limit checked. Note that limit checks occur on each conversion as each new sample is acquired. If there are two analog cards in the Remote Terminal, the process is being applied to both simultaneously.

Approximately every four seconds, the software causes each A/D converter to be switched to a set of four reference voltages. At this time, the A/D gain and offset values are determined and all subsequent input samples are corrected.

Status input data is sampled approximately 60 times per second. The attributes that have been assigned to each status input are checked and the results displayed on the front panel.

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MRC-1 REMOTE TERMINAL

As a result of a RAISE or LOWER key being depressed, the software determines the output line that has been mapped to the telemetry channel, activates the specified output, and then, checks the output register for operation. If operational, it activates the RAISE or LOWER LED.

During communications with the Control Terminal, extensive error checking is performed to ensure receipt of valid data. The Remote Terminal must receive one valid message within 45 seconds of the previous valid message in order to maintain the fail-safe output active. If the time period is exceeded, the fail-safe output is de-activated.

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7.0 MAINTENANCE

7.1 PURPOSE

The purpose of this section is to provide a guide to the maintenance of the MRC-1 at the module level. Section 8 of this manual provides the schematics, card layouts, troubleshooting and adjustment information for the individual card or assembly.

CAUTION

ALWAYS REMOVE POWER FROM THE TERMINAL AND DISCONNECT THE BATTERY WHENEVER PRINTED CIRCUIT MODULES ARE REMOVED OR REPLACED IN THE UNIT. FAILURE TO OBSERVE THIS CAUTION MAY CAUSE DAMAGE TO ONE OR MODULES.

7.2 HANDLING CMOS DEVICES

The MRC-1 contains several CMOS devices, such as 6802 MPU, 6821 PIA, 6850 ACIA, and 2716 EPROMS, which, unfortunately, can be damaged by severe electrical transient voltages. A person walking over a waxed floor, depending upon floor conditions and humidity, can generate voltage potential in excess of 15kV. The following is recommended to reduce damage to the CMOS devices:

- 1. All CMOS devices should be stored in materials that are anti-static. CMOS devices must not be inserted into Styrofoam.
- All CMOS devices should be placed on a grounded bench surface and the user should be grounded before touching the device.

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- Nylon, or other static generating materials, should not come into contact with the device.
- 4. Do <u>not</u> remove boards or CMOS devices with power applied or with battery connected.
- 5. Treat boards that contain CMOS devices just like the device itself.
- 6. When wrapping a module for shipment, never use any plastic material that is not marked as being antistatic. Most anti-static plastic material is a pale pink color and identified as such.
- Always use grounded test equipment to diagnose problems and ground the test equipment to the unit before placing probes on the circuits.

7.3 CARD ADDRESS AND OPTION SWITCHES -

Most card assemblies contain small switches referred to as DIP switches that select the address of the card and, in some cases, provide various common options on the card. Each switch is explained in Section 8 of this manual for the specific module.

Since each card (except the CPU card) can be placed in any card slot, 2 through 15 on the mother board, there needs to be some way of identifying the card when it is inserted. This identification is called the board address and is composed of two parts:

- A fixed hardwired address that identifies the card type
- 2. A variable part of the address that identifies the particular card of a given type

MRC-1 REMOTE TERMINAL 7-2 Rev. 10 Nov. 1980 For example, if the system contains two Status Input cards, they are identical in all respects except for the DIP switch positions. This allows the software to distinguish between the card that is assigned to Channels 1-16 and the card that is assigned to Channels 17-32.

A uniform convention has been established for setting the switch positions within a given type of board. This is diagrammed below. The UP arrow represents the switch in the ON position; the DOWN arrow, the OFF position. (Note: On most cards, ON is UP, OFF is DOWN, but it can be the other way. Refer to the switch itself.)

DEVICE	CHANNEL	BCD SWITCH	DIP	SWI	TCH	PO	SITIONS
NUMBER	ASSOCIATION	POSITION		1	2	3	4
1	1 - 16	0		¥	+	¥	+
2	17 - 32	l		+	¥	¥	¥
3	33 - 48	2		¥	↑	¥	÷
4	49 - 64	3		↑	↑	¥	ŧ

For troubleshooting purposes, you may interchange cards of the same type - BUT - be sure to set the switches to the proper setting before inserting the card.

7.4 FAULT ISOLATION - LEVEL 1

The MRC-1 contains several indications to aid in fault isolation down to the card level. Always go through these steps before attempting to service the equipment.

 The three power LED indicators on the CPU card indicate the presence of voltages. The LED's should all glow with approximately the same brightness. If in doubt, check the voltages with a voltmeter.

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- 2. Depress the RESET switch on the CPU board. This forces the CPU to begin the program from the beginning. When reset, all LED's on the front panel will illuminate briefly. Should the LED's remain ON, the fault could be either in the CPU or memory cards.
- 3. If simple command functions like site, lamp test or channel keys function properly, the most likely candidate is the modem. In most likelihoods, the levels need adjustment (refer to the card description in Section 8). If the top LED of the modem is flashing, it indicates that the modem is being keyed. An AC voltmeter across the output circuit should indicate a voltage that varies in step with the LED. If there is no voltage, check the fuses in the interface card.

If data is getting out onto the communications circuit from the Control Terminal, determine if the Remote Terminal is receiving data. The bottom LED on the Remote modem should flash in step with the transmit LED of the Control Terminal. When the Remote Terminal transmits, its transmit LED will illuminate which, in turn, should cause the receive LED at the Control Terminal to be illuminated. Note that you can force the modem to transmit by activating the TEST switch on the front of the modem card.

When using a 2-wire line, the modem hears itself transmit. You will see the transmit LED flash and the receive LED ON most of the time with a periodic short duration OFF period.

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7.5 FAULT ISOLATION - LEVEL 2

The following is a guide to the isolation of problems that are associated with the various sensor inputs to the MRC-1. Each input or output, if subjected to an overvoltage or overcurrent condition, will, in general, affect only a single sensor. If any single telemetry (analog), status or command function fails to function properly, first check the external wiring carefully. With the suspect module placed on the extender card, determine if the signal is present at the input (or output) of the final transistor or gate on the card to your system. If opticallyisolated inputs or outputs are involved, be sure that a source is provided and measure the voltages differentially with respect to the chassis. Also, with the analog signals, a minimum voltage of 0.256V must be present across the two inputs in order to calibrate a telemetry channel.

Because of the very heavy filtering that is done on all the lines that pass through the interface cards, do not expect the system to respond to very short-duration pulses. The problem of keeping stray RF energy out of the Remote Terminal places a number of constraints on the response time of all inputs and outputs of the MRC-1.

Along the same line, it is possible that opening up and/or operating a Remote Terminal with cards on an extender board may run into problems due to the RF field present. MRC-1's have been subjected to operation in AM, FM, TV and combination transmitter environments with confirmed success. However, since we have no control over your particular environment, no guarantee is made that the unit will function open in all circumstances.

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8.0 CIRCUIT DESCRIPTIONS

8.1 INTRODUCTION

The circuit description for the various printed circuit modules and assemblies in a standard MRC-1 are contained in this section in the form of a documentation package for each assembly.

Note: On some boards, early production units may contain DM81LS97 integrated circuits in place of the SN74LS244 I.C.'s shown in the prints and mentioned in the descriptions. Similarly, early production units may contain DM81LS98 circuits in place of SN74LS240. (These changes were made due to considerations of parts availability, not due to problems with the older parts.)

Figure 8.1 shows pin-outs for the older and newer parts.

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SN74LS244 (on newer production units)

Figure 8.1

SN74LS240 is the same as SN74LS244 except for inversion of the outputs. Similarly, DM81LS98 is an inverting version of DM81LS97.

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REMOTE TERMINAL FRONT PANEL

Assembly 20C2703 Schematic 91C7127 PC Board 51B5842

I. PURPOSE

This module has five functions:

- Display site number, channel number, and value on seven-segment displays
- 2. Display thirty-two user status inputs (if installed) on discrete LED's
- 3. Display system status on discrete LED's
- 4. Provide an audible alarm
- 5. Encode keyboard entries for use by the CPU board

II. THEORY OF OPERATION

A. <u>Overall</u>: The front panel can be looked upon as a X-Y matrix, the X direction being data, and the Y direction being a location. The X path consists of six bits, while the Y path is five bits describing $32 (2^5)$ locations, 21 of which are used.

Location bits B0-B4 are decoded using a 4 to 16-bit decoder (U22) to provide locations 1 through 16, and a 3 to 8-bit decoder (U23) to provide locations 17 through 21. When accessing locations 1 through 16, all inputs of U20 are high, forcing the output low. This enables tri-state

REMOTE TERMINAL FRONT PANEL(20C2703) Rev. 9 June 1980 -1buffer U17, allowing data to be sent to U1-U16. When accessing locations 17 through 21, one of the inputs of U20 will be low, forcing the output high, causing pin 12 of U19 to go low. This enables tri-state buffer U21, allowing data from the keyboard matrix to be sent to the CPU board. No locations are accessed unless CB2 (J2-11) is low. This signal is normally high, and pulses low for 7 microseconds when writing new data into locations 1 through 16. It is held low while reading the keyboard.

B. <u>Seven-Segment Displays</u>: Y locations 1 through 8 are used to select the eight seven-segment displays. Data is applied at J2-1 through J2-6 (A0-A5) to the inputs of U17. U17 is used to buffer the relatively low drive capabilities of the signals from the CPU board. Bits A0 through A3 are applied to the A, B, C, and D inputs of the TIL-308 displays. The resultant displays are shown in Fig. 1. Bit A4 is used to control the left-hand decimal point.

C. <u>User Status</u>: Data for the user status appears on A0-A5 and is clocked into hex D latches Ul through U6. This data is active low; the LED is ON if the corresponding bit is low. Resistors R1-R32 are used to limit the current through the LED's.

D. <u>System Status</u>: Data for system status is supplied in the same manner as the user status. U7 and U8 are used to store the status and drive the LED's.

E. <u>Audible Alarm</u>: Data bit A4 at location 16 (U8) is latched in at U8 and fed to audible alarm driver Q1. This

REMOTE TERMINAL FRONT PANEL (20C2703) 24 Aug 1979 -2bit is active high and drives the Sonalert if J2-15 (alarm drive) and J2-16 (internal alarm) are connected together by the user.

F. <u>Keyboard</u>: During accessing of locations 17 through 21, data lines A0-A5 will normally be low, indicating that no push buttons are activated. A push-button activation will cause the appropriate location line to be connected to a data line, causing the data bit to go high.

III. TIMING DIAGRAMS



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IV. TROUBLESHOOTING

- Verify that the site, channel, and value displays blank out, and all of the discrete LED's are lit during reset (depressing the RESET switch on the CPU board). If this does not occur, check pins 14 and 13 of U18; both should go low during reset. If this does not occur, refer to the section on the CPU interface board.
- 2. If certain numbers will not appear on a display, suspect the display IC. If certain numbers will not appear on all the displays, there may be a stuck bit on A0-A5. A stuck bit should also show up on the status lights; this will show up on LAMP TEST, where the LED will not change its state. Stuck bits may be caused by a defective U1-U17 or U21, or a failure on the CPU board. Remove U17 from its socket. All LED's should be OFF and the BCD displays should read "F". If they do not, this indicates either a short to ground or a defective input on Ul-Ul6. Remove Ul-Ul6, one at a time, (leaving only one out at a time) until the displays read correctly. If doing this for all of Ul-Ul6 does not solve the problem, check with an ohmmeter (with the power OFF) from A0-A5 to ground to check for shorts.
- 3. Most failures in the keyboard will be caused by a malfunctioning key-switch. If a key-switch will not function, try shorting across its two contacts on the rear of the PC board with a jumper wire. If this performs the appropriate function, replace the switch. Another possible problem is if the key-switch is shorted, this

REMOTE TERMINAL FRONT PANEL (20C2703) - 24 Aug 1979 -4-

will result in an apparently dead keyboard. The easiest way to check for this is to remove power from the unit and check across each key-switch with an ohmmeter, looking for a shorted switch.

REMOTE TERMINAL FRONT PANEL (20C2703) 24 Aug 1979 -5-



1/76 DIETERICH-POST CLEARPRINT MED-

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1. 1 -

PRINT PHANTOM ITEMS

PRINT COMPONENTS

PRINT PHANTUM/CUMPONENT CUMMENTS

PARENT ITEM 9231716	CAUSS REF ITEM	DESURIPTION REM TERM FRT PANEL MRC-1 ENGR DRAW 2002703 – L	BATCH TTY	1	ITEM TYPE D UNIT MEAS EA	LOW LEVEL 04 PLANNER 514

_U^ 11⊑1	LL CJ	CUMPONENT & Crugs Ref.	DESCRIPTION & CUMMENT	ENGINEERING DRAWING NUMBER	QUANTITY PER	UM TYP	OP T N 3R	FIRST OP SEG	L T AD J	EFFECTIVE DATE	S O
T	05	3-71155	PUB REMOTE & CONTROL FR PANEL	5185842 EL	1-000	EA 9				~	
۷	05	3000005	IL SN74LSJAN HX INV	5N 74L 5044	1.000	FA 4					
З	05	3000 735	IL SNI4LSSON SI SIN NANU UZO	5N74L530N	1.001	EA 4					
4	05	3000 742	IL SN74LS13dN 3-BLINEDECCEMUX U23	5N74L5138N	1.000	FA 4					
5	05	3000982	10 SN74367 HEX BUF 3/ST U17.013	SN 74367 J	2.000	EA 4					
U	05	305 3415	IC SN74LS368 HEX INV 3/ST U21	SN74L S 358AN	1.000	FA 4					
7	05	3006407	IC SN74154N 4-16LINE DEMUX U22	SN 74154N	1.000	EA 4					
ð	05	3000507	IL SN74174N HX D EDGE/TR UI+U2+U3+U4+U5+U6+U7+U8	SN 741 74N	8-000	EA 4					
7	0 >	3690021	IC TIL-308 DISP 7 SEG L3P U9+010+011+012+013+014+015+0	TIL-300 16	4.000	EA 4					
11	06	3630027	XT NS242924LF5+2W160MU25V+1A7P QL	212924-LF5	1.003	EA 4					
12	Ü5	3370127	LEU PED 2+0020 WIDE DIFFUSED CK1+CR2+CR3+CR4+CR5+CR6+CR7+ CR12+CR13+CR14+CR15+CR16+CR1 CR21+CR22+CR23+CR24+CR25+CR20 CR30+CR31+CR32+CR38+CR39+CR40	FLV160 CK3+CR9+CR10+CR11+ 7+CK13+CR19+CK20+ 6+CK27+CR28+CK29+ 0	35.090	EA 4					
13	00	3390614	LED GRN 7-12920 DIFFUSED 75DEG CK33+CK34+CR35+CR36	HL MP-3507	4=009	EA 4					
14	05	33901+3	LED YEL IU.020 NARROW DIFFUSED CK37+6441+6842+6843	MV-5354	4.000	EA 4					
15	00	3250024	SKT DUAL IN LINE 14 PIN Ul79020	640357-1	2.000	EA 4					
16	00	3256032	SKT DUAL IN LINE 16 PIN UI+U2+U3+U4+U5+U6+U7+U8+U9+U1 U15+U16+U17+U13+U21+U23	640358-1. 10+UL1+UL2+UL3+UL4	20.000	EA 4					
17	05	325 10 73	SKT DUAL IN LINE 24 PIN	040301-1	1.000	EA 4					
18	05	4310207	CAP .1UF/50V 20% L1+L2+C3+C4+C5+C6+C7+C8+C4+C1 C15+C16+C17+C18+C19+C20+C21+C	CY20C104M 10+C11+C12+C13+C14 C22+C23	23.00U	EA 4					
19	Οœ	4200105	CAP AXIAL 47/6V TANT C24	T3178476K006AS	1.000	EA 4	2				
20	Űu	4410130	RES 120 OHM 1/4W 102 R33.R34.R35.R36	RC 07GF 121K	4-000	EA 4					
21	05	4410103	PES 220 UHM 1/40 10% R370R410R420R43	RC076F221K	4.000	EA 4					

DATE 0/13/85 TIME 9.33.17 PAGE 2 VMEAT

PRINT PHANTUM ITEMS PRINT COMPONENTS PRINT PHANTUM/COMPONENT COMMENTS

РАн: 41 4201715	11.1	M LAUSS REF	I TêM	DESCRIPTION REM TERM ENSK DRAW 2002763	L L	176-1	d A	ТСн	414	1	ITEM T UNIT M	YPE U IEAS EA	L')W LEV PLANNER	EL 04 514
TLM ITCM	LL CJ	CJMPUNENT L Chuiss Ref.	DESCRIPTIO	N 6	ENGINEEPIN DRAWING NU	J Y∃ER	GUANTITY PER	l UM	TEM TYP	OPT NBR	FIRST OP SEQ	L T AD J	cFFECTIVe FRJM	DATES Tu
22	Ûo	4410109	KLS 330 0H RL+K2+R3 415+415+	M 1/4W 10% +R4+R5+R6+R7+R8+R9+R1 R17+R13+R19+P20+R21+5	RCUTSF331K 10+R11+R12+ 122+R23+R24	4130K140 08250R25	35.00J	EA	4					
23	նս	4-1.12+7	RES IN UHH	429,430,531,435,9838,65 1/4W 10%	KC 070F102K		2.000	EA	4					
24	J-J	4-+10319	R44+452 RES LUK JH	IM 1/4# 10%	RCU73F103K		d.000	EA	4					
20	.)5	3110350	R45.R45.	R47+R43+R49+R50+R51+ H FLEX NT ANGLE W/D	153 1427-1002		1.000	EA	4					
21	د(.	317.1104	SW PB SPST		TFU		25.000	FA	4					
_` a	05	111111	EIN NU LEU	END ILU MACI	05A?019-1	51	აისას	FA	4					
2.9	05	31/1311	STN D LT U	RY MRC1	0542019-2	51	4.000	EA	4					
30	Jb	311324	BINILT	RY MRCL	0522019-3	81	1.000	EA	4					
31	0.	3197372	ETN 2 LT U	AY MALL	05A2019-4	61	1.000	EA	4					
36	35	311,142	UTN BLE S	KY 4461	U5A2019-5	61	1.000	ĒĄ	4					
1.1	05	3, 3, 3, 3, 5, 2		RY MRCL	05A2519-6	81	1=000	FA	4					
14	0.5	1131300	HIN S IT I		(15 42 5 1 1-7	H 1	1-000	EA	4					
	2.	3. 1. 17.		5 4021		04 D1	1.000							
	.1.2	3143373	514 5 11 6		0742019-0	51	1.000	EA	4					
36	05	311-306	Shi / LT G	RA MACT	UDA2017-9	BT	1.000	EA	4					
37	じっ	3190394	STN H LT U	KY M4C1	05A2619-10	31	1.000	EA	4					
3 d	05	319,3402	BIN 9 LT G	AY MRL1	USA2619-11	91	1.000	ΕA	4					
14	05	31 10410	91N . 3LU	MKC1	05A2619-12	31	1.000	EA	4	,				
46	60	3190428	BIN - BLU	MRCI	05A2619-13	81	1.000	EA	4					
41	1)5	319:1420	STN SITE L	T GAY MHCI	U5A2014-14	91	1.000	EA	4					
42	ปร	3193444	BIN CH LT	GRY MRCI	USA2619-15	BI	1.000	EA	4					
43	05	3140451	BIN LIN BL	U MHCI	U5A2019-16	81	1.000	EA	4					

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PRINT PHANTUM ITEMS PRINT CUMPONENTS PRINT PHANTUM/CUMPONENT CUMMENTS

PRIM PHATION/COM	PUNE VI COMMENTS					
PARENT LIEN J201715	CRUSS REF ITEM	DESCRIPTION REM TERM FRT PANFL MRC-1 ENGR DRAW 2002703 L	RAICH MIA	ı	ITEM TYPE D UNIT MEAS EA	LIA LEVEL 34 PLANNER 514

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PDC Malt	LL Cu	CAUSS REF.	DESCREPTION &	ENGINELRING DRAWING NUMBER	JUANTITY PER	ITEM UM TYP	OP T NBR	FTRST OP SEQ	L T A D J	EFFECTIVL FRUM	UATES TO
4 -9	5	1190409	STN INV YEU MRCI	0542519-17 81	1.000	EA 4					
45	05	3170417	STN Z GLU MRCL	U542619-18 81	1.000	FA 4					
* 0	115	3170405	HIN LIMS BLU 19 LL	059501A-16 e1	reada	Ea 4					
41	05	319.14.3	HIN SHET BLU HRLL	J542019-20 41	1.000	EA 4					
4 d	0.>	3190219	NEN LU LIM BLU MRCL	6542017-22 41	1.010	EA 4					
41	7.7	1010024	SUF PAHO PHPS 2/50 x 1/2 551	BENDER HEAD	∠ ∙ບາບ	EA 4					
っし	05	1010131	WSHR LK #2 SR SST	LULKWASHER #2	2.000	EA ÷					
51	00	1010107	NUT HEX 2/56 SST	F- 554	2.000	EA 4					
52	US	きょきょういせ	UIN NU LEGEND LE GRY MRCI	05A2019-27 81	2.000	EA 4					
53	υs	31 1009	SW LIP 3	205 d	1.000	tA 4					
54	05	3000015	101 10210 1000 JOM GE 001	11270	6.000	EA 4					
50	95	1010149	APHK LT #2 21	Mw-4J0	2.000	FA 4					
50	()5	1210320	LUG GND	36	2.000	EA 4					

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CPU BOARD

Schematic 91D7132 Assembly 20B2710 PC Board 51B5849

I. PURPOSE

This module has six (6) functions:

- 1. CPU and Buffers
- 2. 2K EPROM and Priority Interrupts
- 3. I/O Preselect
- 4. Bit Rate Generator
- 5. Front-Panel Drive
- 6. Indicators and Controls for CPU Interface Board

II. ELECTRICAL ADJUSTMENTS

When power is applied to the unit for the first time, R30 should be adjusted. Turn R30 counterclockwise until CR4 (reset) illuminates. Then, turn clockwise until the LED goes off. Continue turning R30 for one more full turn. S1 is used to generate a *PF and *RESET signal, and is used mainly for troubleshooting. A jumper from U9 pin 1 to ground is used to disable the internal RAM on the CPU and is normally installed. A jumper between P1-10 and U1 pin 35 is used to supply power to the internal RAM on the CPU and is normally installed.

III. THEORY OF OPERATION

Overall: The CPU generates the addresses from which data will be stored or retrieved. The address bus

CPU BOARD (91D7132) Rev. 10 Nov. 1980

-1-

consists of 16 bits, allowing 65536 (2^{16}) addresses. These lines are used on the CPU to select the PIA (Peripheral Interface Adapter), the EPROM (Erasable Programmable Read Only Memory), and the PIC (Priority Interrupt Controller).

The data bus (D0-D7) is used to carry the data between the CPU and other parts in the system. This bus is bi-directional. When the CPU writes data, the CPU outputs and the peripherals input. Conversely, when the CPU reads data, the CPU inputs and the peripherals output. The direction of data flow is controlled by the R/W (Read or Write) line. Data is read into the CPU when this line is high. The VMA (Valid Memory Address) output of the CPU signals to the address decoding logic that the address line has a valid address on it. No data transfers occur unless this line is high. Output line E (Enable) is a l MHz square used for bus timing. Data transfers occur when this line is high. BA (Bus Available) signals that the CPU has gone inactive as a result of a request generated by an external device, such as DMA (Direct Memory Access).

The PIC is used to sequence interrupts to the CPU by allowing higher priority devices to go first. The EPROM is used to store the program (or part of it). The PIA is used to drive the front panel along with six (6) miscellaneous functions. The bit rate generator is used to divide the 1 MHz E signal to approximately 19200 Hz, suitable to run 1200 or 300 baud.

A. CPU and Buffers

Y1 and U1 form a 4.00 MHz crystal oscillator, operating in the parallel resonant mode. C21 and C22 are incorporated to ensure that Y1 does not start oscillating in the third-overtone mode.

CPU BOARD (91D7132) Rev. 9 June 1980

-2-

U9A disables the internal RAM of the CPU during power up and power down. If the jumper is inserted from pin 1 to ground. the internal RAM will always be disabled. This is the case when a RAM/ROM memory board is used in the system. The NMI input is used for a device requiring very fast service from the CPU. The jumper from P1-10 to U1 pin 35 is used to power the ON CPU RAM; it is not used if a RAM/ROM memory board is used in the The HALT input stops the CPU after it is finished executsystem. ing the present instruction. The CPU then releases itself from the bus and sets the BA (U1, pin 7) output high. This action signifies to the device that pulled HALT low to commence transfer of data on the bus. Address lines A0 through A7 are buffered by tri-state octal buffer U5; likewise, lines A8 through A15 are The enables for U5 and U6 are controlled by VMA buffered by U6. from the CPU. In this way, the address lines to the rest of the system are only active when valid addresses are available. VMA is also gated with the *DMA input by UlOA. This allows a DMA controller to simulate VMA to the rest of the system by pulling *DMA low. Data lines D0-D3 are buffered by U7; likewise, D4-D7 are buffered by U8. UlOB and UlOC are used to enable U7 and U8. One input of UlOB and UlOC is fed out of phase from the R/W line so only one can be enabled at a time. The other input of UlOB and UlOC is driven by Ul7B, which only allows the buffers to be activated if BA is low and if none of the I/O or memory is activated on the CPU board. This is required to prevent both the bus buffers and the PIA or EPROM from trying to feed data to the CPU simultaneously.

B. 2K EPROM and Priority Interrupts

U4 is addressed at locations F800-FFFF which are decoded by U19. Address lines All-Al5 are applied to the inputs of U19 along with VMA and R/W. The R/W is including so that a write operation to

CPU BOARD (91D7132) Rev. 28 April 1981

-3-

F8000-FFFF will not cause a buss conflict between U4 and the CPU.

The PIC (U3) is addressed at locations FFEO-FFFF which are decoded by U18, U15B and U17A. Address lines A5-A15 are applied to the inputs U18 and U15B along with VMA. During normal operation, address lines A1 through A4 are passed from the A1-A4 inputs of U3 to outputs Z1-Z4 which allows normal addressing of the EPROM. If an interrupt input of U3 is pulled low, it will pull its IRQ output low, generating an interrupt of the CPU. In case of an interrupt, the CPU will fetch the address of the service routine at locations FFF8 and FFF9. These two addresses are decoded by U3, and used to modify its Z1-Z4 outputs in accordance with which interrupt is active, allowing a modified address to reach U4. In this manner, there are eight (8) interrupt service addresses instead of one (1).

C. I/O Preselect

I/O is assigned addresses 8000 through 81FF in this system. Rather than decode all 16 address lines on each I/O board, an I/O preselect system is used. Address lines A9-A15 and VMA are gated together in U16A, U16B and U15A to form *PRE.

This signal goes low when a valid address from 8000 to 81FF is on the address bus. This signal is inverted by U12C to form an active high signal and put on the bus. Most I/O boards conform to the following addressing convention:

A15/A14/A13/A12/A11/A10/A9/A8/A7/A6/A5/A4/A3/A2/A1/A0 1 0 0 0 0 0 0 T T T B B B B R R

CPU BOARD (91D7132) 23 Jan 1979

Where:	l = High
	2 = Low
	T = Board Type
	B = Board Number
	R = Register Select

D. Bit Rate Generator

IC's U13 and U14 along with U10D form a synchronous divide by 52 circuit. U14 counts from 3 to 15 providing a division of 13 while U13 divides the output of U14 by 4. In this manner, a 1923Ø Hz square wave is generated at the baud output. This clock is used by ACIAs (Asynchronous Communications Interface Adapters) to provide data at either 1202 baud or 300.5 baud, which is within 0.2 percent of the standard 1200 and 300 baud.

E. Front-Panel Drive

U2 is used to drive the front panel and is located at addresses 8004 through 8007. There are three chip select inputs on the MC6821; 2 active high and 1 active low. The active low input is connected to *PRE which will go active with addresses 8000-81FF. Address lines A6, A7 and A8 are NOR'ed together at Ul6C and fed to the first active high input. Address line A2 is applied to the second active high input to U2 providing the "04" offset to the base address of 8000. Lines CA1 and CA2 are used as interrupt inputs and allow interrupts every 16.7 ms for 60 Hz or 20 ms for 50 Hz, and also for loss of main power. The interrupt output of U2 is connected on the board to interrupt input 7 of U3. This is the highest priority interrupt. Output lines PA6 and PA7 are applied to the CPU interface card and used for an external maintenance override and failsafe outputs. Output line PB6 and input line PB7 are used for control of the low-battery detector on the CPU interface card. Lines PA0-PA5 are bi-directional and carry data to and from the front panel. Output lines PB0-PB4 are used

CPU BOARD (91D7132) 23 Jan 1979
to access various elements on the front panel.

F. Indicators and Controls for CPU Interface Board

Switch S1 is connected from *PF to ground and is used to simulate a power down/power up sequence. This switch is mainly used for troubleshooting. CR4 indicates activity of the reset line and is used to adjust the power fail threshold potentiometer R30. CR1-CR3 are provided to give a visual indication of operation of the +15, -15 and +5V power sources.



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FOR 50 Hz t = 20 ms FOR 60 Hz t = 16.7 ms





CPU BOARD (91D7132) 24 Aug 1979

V. TROUBLESHOOTING

- 1. CPU and Buffers
 - A. Verify +5, +12 and -12 volts are present on board.
 - B. The RESET LED (CR4) should be OFF except when switch Sl is depressed or during initial power up.
 - C. Verify the ENABLE signal by checking IC Ul pin 37. A l MHz square wave should be observed. If this signal is not present, verify proper +5 volt supply voltage is present at pin 8. Pins l and 21 should be grounded. If proper IC voltages are present, suspect the crystal or MC6802 IC.
 - D. If RAM enable jumper is present, IC Ul pin 36 should be low. If no jumper is present, verify pin 36 of IC Ul is high.
 - E. Verify the following levels on IC Ul (MC6802):

*HALT	Pin	2	Ħ	+5	volts	(±.25V)
*NMI	Pin	6	=	+5	volts	(±.25V)
BA	Pin	7	=	0	volts	(±.25V)
*RESET	Pin	40	=	+5	volts	(±.25V)

- F. Check IC Ul pin 4 for real time clock interrupt signal (60 Hz pulse). If this signal is absent, check IC U2 pin 40 for the real time clock signal from the CPU interface card.
- G. Check for activity on the Read/Write line, pin 34, and valid memory address, pin 5. Both lines should toggle in a non-periodic manner. If this is not observed, the problem may be in the microprocessor IC or another IC connected to these lines.
- H. Using an oscilloscope, observe the address and data lines,

CPU BOARD (91D7132) 24 Aug 1979

-7-

pins 9 through 33. These lines are three-state and often appear to float in between HI and LOW. The inputs and outputs of the SN74LS244 should appear similar. The data and address lines may be observed using an extender card and checking the even numbered pins between 12 and 58.

2. 2K EPROM and Priority Interrupt

A. Check IC U4 (TMS2716) for proper supply voltages.

+5V	Pin	24
-5V	Pin	21
GND	Pin	12
+12V	Pin	19

- B. Attach an oscilloscope to chip select (pin 18) of IC U4. After pushing the reset push button, two low-going pulses should be seen. If pulses are not present, check IC U19.
- C. Check data and address lines for activity.
- D. Observe pin 23 of IC U3. It should be normally high with low-going pulses approximately every 20 ms. If these pulses are not present, check IC U3 pin 11 for these pulses.

3. I/O Preselect

- A. Check the inputs of IC Ul6A and IC Ul6B for activity coincidental with activity on addresses A9 through Al4.
- B. Check pin 8 or IC U15A for low-going pulses. If no pulses are observed, check input signals on pins 9, 10, 12 and 13.
- C. Output from the Inverter Buffer (IC Ul2C) should look similar to IC Ul5A pin 8, only inverted.

CPU BOARD (91D7132) Rev. 9 June 1980

4. Bit Rate Generator

- A. Check for the 1 MHz ENABLE signal on pin 2 of IC U13 and IC U14. If signal is not present, trace back to the origin, IC U1 pin 37.
- B. Check each pin of IC U13 and IC U14, which is pulled high by R7 to verify a "HIGH" very near +5 volts.
- C. Pin 15 of IC U14 should have a 1 μ s pulse every 13 μ sec. IC U13 pin 13 should have a 52 μ sec square wave.

CPU BOARD (91D7132) 24 Aug 1979



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DATE -8/26/85 TIME 16.01.39 PAGE 1 VMEAL

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PRINT PHANTUM ITEMS PRINT CUMPONENTS PRINT PHANTOM/COMPONENT COMMENTS

PAR 9200	ENT 11 288	EM	CROSS REF	LTEM DESCRIPTION ASSY ENGR DRAW 200271	•6802 0	2 CPU MRC-1/1A R	,	ВА	тсн	QTY	1	I TEM UNIT	TYPE L MEAS EA	LOW Plan	L EV E	L 0. 514	2
BD LTE	M LL M CL	CC CF	MPONENT &	DESCRIPTION & COMMENT		ENGINEERING DRAWING NUMBER		QUANTITY	UM	TYP	OP T NBR	FIRST OP SEQ	LT ADJ	EFFECT FROM	IVE	DATE	s 0
1	03	34	71927	PCB CENTRAL PROCESSING UNI	T	51C5849 G		1.000	EA	9			n		444 (4		
2	04	12	250075	EJCTR CD LLEFT.RIGHT & 2 P	INSI	41-1274L .C12409	-	-1.000	PR	4							
3	03	3.	70065	SW RT ANG SPOT		81215D9AGE		1.000	EA	4							
4	05	11	10350	CONN SCOTCH FLEX RT ANGLE	W/D	3428-1002		1.000	EA	4							
5	05	33	840163	XTAL 4.00 MHZ MRC/TCS		30A0066 C		1.000	EA	4	+1		с. — с. к				
6	03	34	33287	LULLUGIC CD CPU		1081068-01 E		1.000	EA	4							
7	06	42	280186	CAP EPOX-DIP 220/10V		K2 20E I 0		1.000	EA	4							
	05	42	10004	CAP MICA DIP 18PF 5%		D4-15-180J	÷.	2.000	EA	- 4		• • • •	a X r		*	÷ •	
9	05	43	10207	CAP +10F/50V 20% C1+C2+C3+C4+C5+C6+C7+C8+	C9,C1	CY20C104M	14,	19.000	EA	4							
			· ·	C15.C16.C17.C18.C19													
10	05	- 44	10171	RES 270 OHM 1/4W 10% R28,R29		RC 07GF 271K		2.000	EA	4	*** * **		** 1				
13	00	44	10247	RES IK OHM 1/4W 10% R2+R7+R8+R26+R27+R31		RC 07GF 102K		6.000	EA	4							
14	06	44	10304	RES 3.3K DHM 1/4W 10% R1.R4.R5.R6.R9		RCOTGF332K		5.000	EA	- 4 -	•••••	94897 ()		* * *			1.0
15	06	44	10379	RES 10K 0HM 1/4w 10% R16+R17+R18+R19+R20+R21+	R22.F	RC 07GF 103K		8.000	EA	4				• •			
16	05	44	10619	RES 2.2MEG OHM 1/4W 10% R3		RC070F225K		1.000	EA	4							
17	05	40	30075	POT CER PC PIN 1K OHM .75m R30	151	3006P-1-102		1.000	EA	-4 -				1			
84	06	33	190614	LED GRN 7-12020 DIFFUSED 7 CR1+CR2+CR3+CR4	5UEG	HL MP-3507		4.000	EA	4							×
19	05	30	0669	IC SN74LSOON JU 21N NAND		SN74LSOON		1.000	EA	4							
20		36	60693	IC SN74LSD8N QU 21N AND		SN74LSOBN			EA						**		- 47 - 41
15	03	36	100719	IC SN74LS20N DU 41N NAND		SN74LS20N		1.000	EA	4							
22	03	36	60727	IC SN74LS27N TR 31N NOR UL6-UL7		SN74L527N		2.000	EA	4							
23	05	36	60735	IC SNT4LS3ON ST 81N NAND	1	SN 74LS 30N	4. cm	-2.000	EA	- 4			9 F	18 - 18 - 18		**	÷.
24	05	30	60826	IC SN74LS163AN BINCOUNT PRI U13,014	ESET	SN74LS163AN		2.000	EA	4		x 1	1 4 -4				

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PRINT PHANTOM ITENS PRINT COMPONENTS PRINT PHANTUM/COMPONENT COMMENTS

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*1	PARENT ITEM 9200268	CHOSS REF ITEM	DESCRIPTION ASSY.6802 Engr Draw 2002710	CPU MRC-1/1A R	BATCH QTY	- 1	ITEM TYPE 1 UNIT MEAS EA	LOW LEVEL Planner	02 514
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	BOM	LL CD	COMPONENT & CROSS REF.	DESCRIPTION & COMMENT	ENGINEERING DRAWING NUMBER	QUANTITY	UM	TYP	OPT NBR	FIRST OP SEQ	LT	EFFECTIVE DAT	ES TO
-	-	- Yi	6 14		·· ·· ··	· · · · · · · · · · · ·							
	25	05	3660867	IC SN74LS367 HEX BUF 3/ST U11	SN 74L 5 367 AN	1.000	EA	4	5 X - 14				
	26	05	3660875	IC SN74LS368 HEX INV 3/ST U12	SN74LS368AN	1.000	EA	4					
	- 27	05	3600859	IC SN74LS244N OCT BUS/DRIV ST	SN74LS244N	4.000	EA	4	-				
	29	05	3710027	LC MC6821P PIA INTERFACE U2	MC 6821 P	1.000	EA	4					
	30	04	3710019	IC MC6802P MICROPROCESSOR	MC 6802 P	1.000	EA	4					
	- 31	60	3710035	IC MC6828P PRIOR INTERRUPT U3	MC 6828P	1.000	EA	-4 -		34-1			
i.	34	00	3250024	SKT DUAL IN LINE 14 PIN U9+U10+U15+U16+U17+U18+U19	640357-1	7 .000	EA	4		a. 1 - 5			
	35	06	325J032	SKT DUAL IN LINE 16 PIN	64035d-1	4=000	EA	4					
1.1	36	05	3250057	SKT DUAL IN LINE 20 PIN	640464-1	4.000	EA	4.	iya w	1990 - 1996 1997 - 1996 1996 1996 1996 1996 1996 1996 1996	-9	8	
	37	05	3250073	SKT DUAL IN LINE 24 PIN	640361-1	2.000	EA	4		S. 441			
	38	05	3250099	SKT DUAL IN LINE 40 PIN	640379-1	2.000	EA	4					
	•0	05	1030030	SCR PNHD PHPS 3/48 X 3/8 SST	BINDER HEAD	2+000	EA	4		n san Rome	-		
	41	04	1030089	WSHR LK #3 SR SST	LOCKWASHER #3	2.000	EA	4	den a				
	42	05	1030055	NUT HEX 3/48 SM PATT SST	NUT 3/48 SM	2.000	EA	4					

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CPU INTERFACE

Schematic 91C7215 Component Layout 20C2781 PC Board 51C5907

I. PURPOSE

The CPU Interface module has eight functions:

- 1. Power failure sensing.
- 2. Power-on reset.
- 3. 50-Hz or 60-Hz real time clock.
- 4. Battery backup switching and charging.
- 5. Low battery voltage sensing.
- 6. Output relays for failsafe and maintenance override indication.
- 7. Connection for audible alarm muting.
- 8. Auto-restart in the event of malfunction.

II. SPECIFICATIONS

- 1. The maximum battery charging current is 75 mA. This is suitable for up to 7.5 Ah Gel-Cell batteries. For a larger battery, use an external charger.
- For a battery voltage of 6 V, it is float-charged at 6.95 V. The battery is considered discharged when the battery voltage under load drops below 5.0 V. The maximum voltage applied to the battery terminals should not exceed 7.05 V.
- 3. The voltage and current ratings of the maintenance override and failsafe relays are 24 Vdc and 1 A. Relay contacts are brought on to the rear panel connector.
- 4. Aural external drive output:

Power user supplied; output is open collector switched to chassis ground.

III. ELECTRICAL ADJUSTMENTS

 Battery Charge Voltage (R28): This control is set at the factory for 6.95 V ±.1 V into a 270 ohm load. This is the correct float-charge voltage for the supplied batteries and should not need adjustment.

IV. THEORY OF OPERATION

1. Power Failure Sensing

AC voltage from the secondary of the power supply transformer is supplied at pins Pl-11 and Pl-13. The ac is full-wave rectified by CRl and CR2, and then filtered using Cl. A potentiometer is connected to Pl-91 and ground on the CPU board. Rl, R2 and the potentiometer form an adjustable attenuator that is used to compensate for variances in local line voltage and frequency. ULA and R4 form a comparator with hysteresis. The threshold is maintained constant with CR3, a 3.1 V Zener diode. When normal line voltage is applied, the positive input of ULA is above 3.1 V, causing the output to be high. If the ac supply should fail for a period of time (nominally 10 ms), the positive input to the comparator will fall below 3.1 V and cause the output *PF to go low.

2. Power-On Reset

When power is applied to the unit, *PF will go high, allowing C4 to charge through R8. This voltage is applied to the negative input of a comparator consisting of UlB and the 3.1 V reference. After approximately 400 ms, the negative input will reach the reference level causing the output of UlB to go low, which removes the base drive to Ql allowing the collector to be pulled high by R14. When power is removed from the unit, *PF will go low, discharging C4 through R7 and CR4. Operation is much quicker in this direction and reactivates *RESET approximately 3 ms after *PF goes low.

3. Real Time Clock

AC voltage from the power supply transformer secondary is supplied at Pl-13 and rectified by CR5. This is applied through voltage divider R15 and R16 to the positive input of a voltage comparator (UlC). On the output of the comparator is a rectangular wave having a duty cycle of about 55%.

4. Battery Backup Switching and Charging

Fifteen volts from the power supply is regulated down to 7.45 volts by U2. This is passed through CR10 to the battery terminal. R28 is adjusted so that 6.75 V is applied at the battery terminals with no load. R29 is used to

protect U2 in case of a short across the battery terminals. During normal operation, Q3 is biased on through R26 by the +15 V supply; this allows the main 5 V supply to be applied to the 5 V standby bus. When either the +15 V or main 5 V supply fails, the base of Q5 is pulled toward ground by either CR7 or CR8. This forward biases Q4, allowing the battery voltage to be passed to the 5 V standby bus. The 6 V at the battery terminals is reduced to an acceptable voltage by the voltage drops of CR9, Q4 and Q5.

5. Low Battery Voltage Sensing

A comparator (ULD) is used as a bistable multivibrator. When main power is not applied, the voltage at the output of UlD will reflect the voltage of the 5 V standby bus. This voltage is dropped 0.6 V by CR6 and fed back to the positive input of UlD to keep the output high. If the voltage at the positive input falls below the reference voltage, the output of UID will be forced low. This occurs when the 5 V standby bus falls to 3.1 V. This removes the voltage at the positive input, which effectively latches the output low. Upon reapplication of main power, C6 filters out any glitches that might alter the state of UlD. If the output of UlD did go low, this will tell the computer that the battery failed during the power outage. To reset the latch, a pulse of at least 10 ms is applied by the CPU to P1-71. This causes 02 to conduct, removing the reference voltage to the comparator. The voltage divider of R22 and R25 is used to provide at least 0.4 V at the positive input to cause the output to go high when the reference voltage is removed.

6. Maintenance Override and Failsafe Relays

To activate the Failsafe output, P1-79 is set high from the CPU module. U5 ensures that the relay will not close when the *RESET line is in its low state, thus preventing a "glitch" when the unit is plugged in or the reset button is pushed. Each gate of U5 has an open-collector output which can sink the current required to activate the relay when both inputs to the gate are in their "high" state. Voltage regulator U4 provides +12 V to the other side of the coil. When the Failsafe relay is activated, closure occurs between pins 3 and 4 of the rear connector.

The Maintenance Override output is almost identical. P1-77 is set high from the CPU module to activate the relay. A closure will then be observed between pins 1 and 2 of the rear connector. Closure between the Failsafe terminals will be observed when the unit is <u>not</u> in a failsafe condition. Closure across the Maintenance Override terminals will be observed when the unit is in a Maintenance Override condition.

In modules installed in a Control Terminal, these relays are never activated and serve no function. The relays are installed, however, to preserve interchangeability with modules installed in Remote Terminals.

The Maintenance Override and Failsafe relays are capable of switching a load of up to 24 Vdc at currents of up to 1 ampere. Inductive loads (relay coils, etc) should have a "clamping" diode wired across them to inhibit negative voltage spikes. External relays should be used when it is desired to switch greater loads (or ac loads).

These relays may also be interfaced with transistortransistor logic (TTL) digital circuits. The relay contacts should be wired so that one side is referenced to the digital input. A pull-up resistor may be necessary, and it is advisable to wire a 1 μ F capacitor and a 100-ohm resistor (in series) across the relay output to suppress contact bounce. See Figure 1.1.





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7. Auto-Restart in the Event of Program Malfunction

Integrated circuit U3 is a dual retriggerable monostable multivibrator ("one-shot"). During normal program operation, line P1-71 is continually strobed from the CPU module. Each pulse reaching pin 1 of U3 "retriggers" the first stage of U3 for another 500 ms. The output at pin 13 will remain high as long as pulses at pin 1 arrive at least every 500 ms. Should these pulses cease (because the program has ceased running properly), the output at pin 13 falls to ground. The falling edge at pin 9 causes a 1 ms pulse at pin 5. If the jumper marked "Auto-Restart" has been installed, transistor Q6 is switched on, causing the *RESET line to fall to ground and re-initiating operation of the program.

The jumper marked "Continuous Restart" enables continuous retries, should the first attempt to restart be unsuccessful. This feature does not appear on some early production units.

8. Alarm Drive

An alarm drive output is available to the user at pin 5 of connector J1 at the rear of the chassis. When the system is in a condition where an audible alarm is appropriate (see the Operation section of the manual), a transistor on the front panel assembly is switched on, enabling current to sink to ground. The collector of this transistor is brought out to pin 5 via a trace extending across the CPU module and onto the CPU Interface module. No more than +12 V should be placed on this pin, and a current-limiting resistor should be used so that no more than 25 mA may flow through the transistor. This input is not RF-filtered (since a studio environment is assumed). Figure 1.2 shows a suggested circuit to use if filtering is necessary. We suggest that the components be mounted in the cable near the connector.

9. Internal Alarm

The Sonalert on the front panel is enabled when pin 6 of Jl is connected by a simple jumper to pin 5. Current limiting is provided internally. Unless the jumper is installed, the audible alarm is disabled. Pins 5 and 6 may also be used for remotely disabling the Sonalert (for instance, when a microphone in the studio is active) if a switch is placed between the pins.



Figure 1.2 RF filter circuit.

V. TROUBLESHOOTING

- 1. Read the section on troubleshooting presented in Section 10.4 (Fault Isolation).
- 2. Specific areas on this module that must be functional for operation of the CPU are as follows:
 - a. Verify presence of +5 V on the 5 V standby bus (emitter of Q4). If it is not there, check for short to ground or Q3 open.
 - b. Check for waveform at P1-11 and P1-13 (ac power in). If not there, check CR1, CR2, C1, and the two 100-ohm resistors mounted on the dc power supply (R113 and R114).
 - c. Check voltage at pin 4 of Ul. It should be between3.0 and 3.2 volts. If not, check Ul and CR3.
 - d. Check voltage at Ul pin 2 (*PF). If it is low, try readjusting the trim potentiometer on the CPU module (R30). If this does not correct it, check for shorts or replace Ul.
 - e. If *PF is normal but *RESET is still low, check for at least 4.5 V at pin 6 of Ul and 2.5 to 3.5 V at pin 7. If these are normal, pin 1 of Ul should be less than 0.5 V. If not, suspect Ul. The collector of Ql (P1-59) should be near +5 V. If not, check U3 pin 5, which should be near ground. If not, suspect U3. If U3 pin 5 is indeed near ground, suspect Ql, Q6, or a short to ground at P1-59.

- f. Check waveform at Ul pin 13. If a 60-Hz square wave is not present, suspect CR5 or Ul.
- 3. Circuits that will not stop operation of the CPU are:
 - a. Maintenance override and failsafe drivers can be checked with a VOM; most probable cause of failure is U4 or U5.
 - b. When main power is applied to the unit, Ul pin 14 should be near +5 V. If it is not, try momentarily grounding pin 8. If pin 14 is still low, suspect CR6, C6 or Ul.
 - c. If the voltage at the red (+) battery terminal is not around 7.3 V, suspect U2 or R28 if the voltage is too high. If too low, suspect Q4 or Q5.



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MEMORY BOARD 8 X 4

Schematic 91D7135 Component Layout 20B2712 PC Board 51B5850

I. PURPOSE

This memory board contains additional memory for program and data storage. Up to 8 kilobytes of erasable programmable read only memory (EPROM) may be installed for program storage. Data is both written and read into random access memory (RAM). This board has provisions for four kilobytes of RAM.

II. TECHNICAL DESCRIPTION

Address ranges for both PROM and EPROM are selected independently using slide switches of DIP switch Sl, allowing multiple memory boards to be used in special applications. Slide switches 1 and 2 are used to assign EPROM addresses, which occur in 8kbyte blocks from 8000 to FFFF hex. The output of IC Ul2, Pin 6 is used as an enable strobe for the EPROM chip select decoder (IC Ul3), allowing the proper memory IC to be selected. Slide switches 3 and 4 are used in assigning RAM addresses which are in 4kbyte blocks ranging from $\emptyset\emptyset\emptyset\emptyset$ to 3FFF hex. Pin 8 of IC Ul2 is used as a RAM access enable strobe for the half of IC Ul3 used to select the proper RAM IC.

Each TMS2716 EPROM is 8 bits by 2048 words; however, the

MEMORY BOARD 8 X 4 (91D7135) 24 Aug 1979

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TMS4045 RAM is only 4 bits wide by 1024 words. Two RAM IC's are enabled at the same time to allow storage and retrieval of 8-bit data words.

Slide switch 5 disables the address buffers when EPROM is selected. Normally, this switch is closed so EPROM can be read. In applications which require additional memory cards with RAM only, this switch would be opened on the cards without EPROM. Slide switch 6 disables EPROM when RAM is accessed. Its operation is similar to the operation of slide switch 5.

III. TROUBLESHOOTING

- A. Make sure the slide switches are in proper position. In a standard Remote or Control Terminal, all memory board slide switches should be in the ON position.
- B. Verify proper +12, -5, +5 volt supply voltages are present. It is best to measure these voltages at the actual memory IC pins.
- C. Check EPROM ENABLE signal (IC Ul2, Pin 6) by observing waveform. EPROM should be enabled frequently when the system is operating properly. If no toggling is observed, check the address select circuitry (IC Ul1 and Ul2).
- D. Check the RAM ENABLE signal (IC Ul2, Pin 8) by observing waveform. It should frequently toggle if address selection circuitry is operating properly.
- E. Verify that the SN74LS244 bus drivers are enabled, allowing data to be read and written from the data bus.

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MODEM II BOARD

Schematic 91D7233 PC Board 51C5909 Component Layout 20D2787

I. PURPOSE

The modem (MOdulator/DEModulator) is used to communicate digital information between Remote and Control Terminals via the telephone lines.

II. SPECIFICATIONS

Transmission Format	7-bit ASCII plus even parity in a 10-bit frame. Transmissions are bi-directional and non-simultan- eous.
Transmission Speed	1200 baud/300 band switchable
Error Detection	Character parity and longitudinal check-sum on messages
Modulation	Two-frequency continuous phase FSK MARK = 2200 Hz SPACE = 1200 Hz
Interface	600Ω telephone lines, strappable two or four-wire configuration.

III. TECHNICAL DESCRIPTION

The MC6850 Asynchronous Communications Interface Adapter (IC U8) provides the data formatting and control to interface serial asynchronous communications information to the 8-bit data bus. The functional configuration of the ACIA

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MODEM II BOARD (91D7233) Rev. 20 March 1981 is programmed automatically during system initialization. A programmable control register provides variable word lengths, clock division ratios, transmit control, receiver control and interrupts. The baud-rate generator (IC U16) provides the clock frequency for the ACIA.

The modem has switch-programmable address specification, allowing multiple modem boards to be used in special applications. BCD switch S3, IC U10 and IC U12 provide address decoding for the board. In normal system operation, with only one modem per unit, switch S3 is left in the "0" position. Two SN74LS244 bus drivers (IC U3 and IC U4) are used to write and read data onto the bus. Parts of IC U6 and IC U7 are used to enable reading and writing according to the status of the read/write line and the board address.

Outgoing serial data is modulated into dual tone frequency shift keying by the XR2206 function generator (IC Ul5). Serial data input is applied to pin 9. A high input causes a low frequency (Mark) of 1200 Hz to be generated. A low input causes a high frequency (Space) of 2200 Hz to be generated. Resistor R38 is used to reduce harmonic distortion.

Transistor Q3 serves as a switch to turn on the modulator according to the request to send ($\overline{\text{RTS}}$) from the ACIA. Switch S2 and parts of IC Ull and IC Ul3 will turn on the modem continuously for test purposes. The output of the oscillator is AC coupled and fed into a 741 op amp before being transmitted via the telco interface board.

The Deadman Circuit (IC U9) turns off the modulator if communications are disrupted for more than 2.5 seconds.

MODEM II BOARD (91D7233) -2-Rev. 27 February 1981 The incoming FSK signal is fed through a bandpass filter consisting of half of IC Ul4. The filtered signal is amplified via part of IC Ul4 and clamped by CRl and CR2. The clamped signal is then demodulated by the XR2211 (IC Ul). The output of the demodulator is buffered by part of Ul3.

The amplified signal from the third part of IC Ul3 is peakdetected by CR8, CR7, CR6, and the fourth part of IC Ul4. This signal is buffered by parts of IC U5 and inverted by transistor Ql to provide data carrier detect (*DCD).

IV. BASIC MODEM ADJUSTMENT

Normally no adjustment needs be made to the high frequency, low frequency, and VCO controls (R36, R35, and R11). These are painted at the factory with red lacquer to discourage casual adjustment. The procedure for making these adjustments is described in Section V, but it should be stressed that such adjustments under normal circumstances are unnecessary.

Each of the procedures outlined below assumes a one-site system. For multi-site systems, each Remote Terminal must be connected in turn and adjusted.

It is suggested that initial adjustment be made with the units back-to-back on the bench to gain familiarity with the controls prior to installation.

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It should be noted that in Section 2, a "Series 3002 (unconditioned) Data Channel per Bell System Technical Reference PUB-41ØØ4" is specified. Therefore, this type of line should be specifically requested from the phone company. (It is guaranteed to have certain characteristics when FSK data signals

MODEM II BOARD (91D7233) Rev. 27 February 1981 are transmitted across it.)

In the following adjustment procedure refer to drawing 15B1117 which is bound in with the next group of blueprints for the location of controls and test points on the modem board.

<u>Step 1</u>: Connect the Control and Remote back-to-back on the bench. For a two-wire system, see Figure 1.1. For a fourwire system, see Figure 1.2. For a mixed telco and subcarrier system, see Figure 1.3. For systems using a subcarrier interconnect in both directions, see Figure 1.4.

NOTE: A simulated telephone line with 30 dB loss may be constructed using a T pad with 560 ohms in each arm and 37 ohms to common.



Figure 1.0 - SIMULATED 30 dB PHONE LINE

A Simpson 260 VOM or similar equipment may be used in this adjustment procedure.

<u>Step 2</u>: Apply power to both terminals. Push "ACK" ("acknowledge") at the Remote Terminal keyboard. Disable all active sites at the Control Terminal as follows (see Control Terminal manual Section 4.6.3 for a full explanation of this):

a. Push "SET-UP". The SET-UP LED should come on.b. Press "SITE ENAB" ("site enable"). The SITE window will

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Figure 1.2 - Four-Wire Interconnect

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Figure 1.4 - Subcarrier Interconnect

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display ".1".

- c. If you have a multi-site system, repeat step (b) for each additional site (select site 2, press site enable, etc.).
- d. The TRANSMIT LED on the front of the modem card should be off, indicating no sites are enabled.

<u>Step 3</u>: Place the toggle switch on the front of the modem cards (S2) in either TEST position at both terminals. This causes both modulators to generate a continuous tone.

<u>Step 4</u>: Adjust the output levels. Use R10 ("send level adjust") on the front of the modem boards.

<u>Two-wire systems</u>: Measure the output level across terminals 1 and 5. Zero dBm should be observed at both the Control and Remote Terminals.

Four-wire system: Measure the output level across terminals 4 and 6. Zero dBm should be observed at both the Control and Remote Terminals.

<u>Mixed systems</u>: Measure the output level at the Telco Output terminals at the appropriate terminal. Zero dBm should be observed. Using a calibrated oscilloscope, measure the voltage at the Subcarrier Output BNC connector at the other terminal. 1.5 volts peak-to-peak should be observed. The OUTPUT potentiometer above the BNC connector should be adjusted if necessary to meet this requirement. The waveform observed should conform to drawing 15All14. Adjust R10 ("send level adjust") on the front of the modem board if necessary to meet this requirement. (Note: The COARSE and FINE adjustments above the BNC connector have been set at the factory and should not require further adjustment.)

Subcarrier-In/Subcarrier-Out systems: Measure the output at both terminals at the subcarrier output BNC connector and adjust as described immediately above (under "mixed systems").

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<u>Step 5</u>: Put the Control Terminal in OPERATE mode (using S2) and the Remote terminal in the right (TEST) position. Adjust the Control Terminal input level using R12 ("receive level adjust") on the front edge of the Control Terminal's modem board. Measure the input levels across test points 6 and 3. Turn R12 clockwise to increase voltage level.

<u>Two-wire system</u>: Between .5 and .6 volts AC should be observed across the test points. (-30 dBm input)

All other systems: Between .5 and .6 volts AC should be observed across the test points. (-30 dBm input)

<u>Step 6</u>: Put the Remote Terminal in OPERATE mode and the Control terminal in the down (TEST) position (using S2). Adjust the Remote Terminal input level (exactly as was done in step 5 at the Control Terminal).

<u>Step 7</u>: Place both terminals in OPERATE mode. Push the RESET button on the front of the CPU boards at both terminals. Reenable the Remote Terminal by using the "SITE ENAB" key at the Control Terminal keyboard (Refer to Section 4.6.3 of the Control Terminal manual for a full explanation.) This step is essentially the reverse operation to step 2, above.

<u>Step 8</u>: The Control Terminal and Remote Terminal should now be "talking" successfully. A channel number should appear in the CHANNEL display at the Control Terminal. Pushing the CH ("channel") key at the Control Terminal should cause the channel display at the Control Terminal to advance by one channel.

NOTE: The channel numbers at the Control and Remote Terminals are <u>independent</u> of each other. One channel may be observed at the Control Terminal and a different channel at the Remote Terminal. However, both channel numbers are stored at the

MODEM II BOARD (91D7233) -8-Rev.21 October 1981 Remote Terminal and for a channel number to appear at the Control Terminal, the number must be fetched from the Remote Terminal thus indicating a successful communication.

The Control Terminal initiates each communication by sending an interrogation to the Remote Terminal. The Remote Terminal replies with its response. As a result, a regular "heartbeat" can be observed on the Transmit LED at the Control Terminal. If the Remote Terminal does not properly receive a message it does not respond and the unit appears to "skip a beat." In a properly adjusted system, a regular pattern of long and short pulses can be observed on the Transmit LED's.

<u>Two Wire Systems</u>: In a two-wire system, each unit can "hear itself speak" so the Receive LED remains on most of the time. Sometimes a pulsation or flicker can be observed.

Other Systems: The Transmit and Receive LED's will flash alternately at both terminals. If a Receive LED remains steadily the input level on the board is probably too high.

Step 9:

Systems Involving Subcarrier: Upon completion of the back-to-back tests and after connection to the actual interconnecting radio link it may be necessary to adjust the OUTPUT pot on the appropriate interface cards at the rear of the terminals, in order to assure proper modulation of the interconnecting radio circuits.

V. FREQUENCY AND VOC ADJUSTMENTS

High frequency, low frequency, and VCO should not nor-

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MODEM II BOARD (91D7233) Rev. 27 February 1981 mally need adjustment. To emphasize this fact, R36, R35, and R11 are painted with red lacquer at the factory after their initial alignment. This section is included in case a need arises to re-align the board, perhaps following a repair accomplished by the user. Refer to drawing 15B1117 which is bound in with the next group of blueprints for the location of controls and test points on the Modem Board.

NOTE: If the frequency counter does not give stable readings the following steps are suggested:

A. Place a 10 K Ω resistor between the frequency counter input and TPl (white) to increase frequency counter input impedence.

 B. Reduce false triggering by placing a capacitor between TPl (white) and ground.

It is suggested that the terminals be connected back-to-back at the same location (see preceding section) so that both ends are easily accessible.

<u>Step 1</u>: With the terminals not connected to each other, prepare to set the frequencies as follows: Connect frequency counter between TP1 (white) and ground (TP3, black).

Step 2: Set the high frequency. Place S2 in HI position and adjust R56 to obtain a frequency of 2200 Hz.

Step 3: Set the low frequency. Place S2 in LOW position and adjust R53 to obtain a frequency of 1200 Hz.

Step 4: Set S1 to CAL position. Connect frequency counter to TP4 (yellow). Adjust R11 (VCO fine tune) to obtain a

MODEM II BOARD (91D7233) -10-Rev. 27 February 1981 frequency of 1700 Hz at TP4.

<u>Step 5</u>: Return S1 & S2 to OPER position and adjust the input and output levels as described in Section IV above, with the terminals connected.

VI. INSTALLATION AND TROUBLESHOOTING

A. Refer to Section IV for instructions for adjustment of the input and output levels.

If trouble is encountered:

B. Check DIP Switch positions. Normally slide switch1 is ON and other switches are in the OFF position.Make sure Sl is in the OPERATE position at all terminals.

C. Verify that proper power supply voltages are present.

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MODEM-TELCO INTERFACE

Schematic 91A7147 Component Layout 20B2716 PC Board 51B5856

I. PURPOSE

The Modem-Telco Interface module interconnects the Modem with either a 2-wire or 4-wire dedicated-circuitry telephone line. Telephone line interconnections are balanced, isolated, fused and filtered.

II. SPECIFICATIONS

Output Distortion	1.5% or less
Input/Output Impedance	300 ohms or 600 ohms
	strappable by user

III. THEORY OF OPERATION

Telephone line inputs are filtered to reduce RF interference. Each input line is individually fused, using an AGC 1/4-amp fuse. Transformers T1 and T2 are 600-ohm to 600-ohm matching transformers. Resistors R1, R2, R4 and R5 are used to convert 600 ohms to 300 ohms for use in the 2-wire mode. Resistors R3 and R6 are used in the 4-wire mode to make the impedance of the phone line connections approximately 600 ohms. Diodes D1 through D4 are used to protect the transformers and Modem module from large transients on the telephone line.

Two interconnection schemes are possible using this module. The 2-wire scheme uses a single pair of wires for communicating in both directions. The 4-wire system uses two pairs of wires separating both telemetry and control signals. The connections necessary for 2-wire interconnections are shown in Figure 1. Figure 2 illustrates 4-wire connections. When interconnecting a Control Terminal with Remote Terminals, no special line polarity must be observed as each input has a balanced 300-ohm or 600-ohm impedance.

A Bell 3002, unconditioned data circuit is specified. The use of long (over 1000 ft) dc continuous circuits is not recommended as their ac frequency response is not guaranteed, and induced currents may prove troublesome.

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IV. TROUBLESHOOTING

- 1. Check fuses and fuse clips for continuity.
- 2. After lightning damage:
 - a. Check inductors for open circuits.
 - b. Diodes D1 through D4 may be shorted.
 - c. Capacitors Cl through C8 may be shorted.
 - d. Check transformer continuity.

Modem-Telco Interface Rev. 24 Aug 79 1 ··· · · · ·





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Figure 2. Four-wire interconnections for Modem-Telco Interface modules.

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TELCO IN/SUBCARRIER OUT

Schematic 91B7144 Component Layout 20A2737 PC Board 51B5865

I. PURPOSE

The Telco In/Subcarrier Out module transmits data via an FM subcarrier and interfaces the modem demodulator with the telephone line for received data. This module is the companion module for Moseley Telco Out/Subcarrier In (20B2736). Operation in several standard subcarrier bands is possible by specifying different frequency-selective components.

II. THEORY OF OPERATION

Incoming data on the telephone line is filtered by L1 and L2 to reduce radio frequency interference. Fuses F1 and F2 are used for protection from large surges on the phone line. Resistors R13, R14, and R15 form a 600-ohm impedance matching network between the phone line and the transformer. T1 is a 600-ohm to 600-ohm impedance matching transformer.

Integrated circuit UI is a function generator, which is used to generate an FM signal from the frequency shift keyed output of the Modem module. The frequency of oscillation is controlled by applying a control voltage to the activated timing pin (pin 7). Resistors R8, R9, R10, and R11 form a voltage divider network used to adjust the frequency control voltage. Timing capacitor C4 is also used for frequency control. Its value is dependent on which subcarrier band is used. Capacitor C5 is a bypass capacitor required by U1. Resistors R6 and R7 are used to reduce the total harmonic distortion (THD). This can be reduced to 0.5% by trimming, or in the worst case, approximately 2.5%. The dc output level is adjusted by applying a voltage bias to U1 pin 3, using OUTPUT Adjust R4.

III. ADJUSTMENTS

Subcarrier Generator (U1)

1. Remove modulation applied to the subcarrier generator using Send Level Adjust R10 on the modem.

Telco In/Subcarrier Out

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- Connect a frequency counter to the SUBCARR OUT connector (J3). Adjust subcarrier frequency using pots R9 and R10. R9 is a course frequency adjustment, and R10 is a fine frequency adjustment. Both pots are accessible from the rear panel and are labelled "COARSE" and "FINE".
- 3. Disconnect the frequency counter and connect a distortion analyzer to the SUBCARR OUT connector (J3). Adjust Distortion pot R6 for minimum distortion. Using this control approximately 0.5% distortion is obtainable. If no distortion analyzer is available, no adjustment on this pot is required. The worst case distortion is approximately 2.5%, which is quite acceptable in most applications.
- 4. Disconnect the analyzer and attach an oscilloscope to SUBCARR OUT J3. To understand this adjustment, refer to Figure 1.7 in the modem section for representative waveforms. Adjust the oscilloscope to display about six periods of the unmodulated subcarrier as shown in (A). Using the modem Send Level Adjust (R10), increase subcarrier modulation until the fifth crossover occurs midway as shown in (B).
- 5. Adjust the output level to 2.5 volts peak-to-peak using OUTPUT Adjust R4. This pot is accessible through the rear panel.

IV. TROUBLESHOOTING

- A. Verify that +12 Vdc is present on pin 4 of Ul.
- B. Modulator
- 1. Verify that the modem is generating an FSK signal, which may be observed at pin 7 of the function generator Ul.
- If no output is observed, check chip voltages and grounds. If Ul is replaced, verify proper adjustment by performing the subcarrier generator adjustment procedure described in Subsection III.
- Note the Modem module must be properly adjusted and working correctly for the Telco In/Subcarrier Out module to function. Refer to the Modem subsection of this manual for troubleshooting details.





TELCO OUT/SUBCARRIER IN

Schematic 91C7160 Component Layout 20B2736 PC Board 51A5870

I. PURPOSE

The Telco Out/Subcarrier In module interconnects transmitted signals from the modem with a dedicated telephone line, and demodulates FM subcarrier data transmissions to provide received data to the modem. This module is the companion module to the Telco In/Subcarrier Out assembly (20A2737). Operation in several different standard subcarrier bands is possible by selection of component values.

II. THEORY OF OPERATION

Integrated circuit Ul is a phase-locked loop used to demodulate the incoming FM subcarrier. The input filter connected to pin 2 is a telemetry extraction bandpass filter and is used to reject frequencies other than the telemetry subcarrier. The components used in the input filter are frequency dependent and are specified according to the subcarrier band being used. Recommended signal input at pin 2 is from 10 mV rms to 3 mV rms. The operating frequency is determined by C5, R5 and FREQ Adjust R6. Resistor R3 and capacitor C8 form a lock detect filter to eliminate chatter at the lock detect output (pin 6). Capacitor C9 is used as a bypass capacitor for an internal voltage reference.

The demodulated output is taken from the loop phase detector (pin 11), through a post detection filter made up of R7, C12, and buffer amplifier U2. This buffer amplifier is necessary because of the high impedance output at pin 11. U2 is a non-inverting unity gain operational amplifier.

III. ADJUSTMENTS

1. Telemetry Extraction Filter Adjustment

Apply a modulated subcarrier signal from a subcarrier generator to the input (J1). Adjust inductors L1 and L2 for maximum amplitude and minimum AM. The filter output should be similar in appearance to the subcarrier generator output.

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2. FM Demodulator Frequency Adjustment

Apply a modulated subcarrier signal to the input (J1). Adjust R6 (FREQ) for the cleanest FSK output. Note that some residual high-frequency subcarrier may be superimposed on the FSK signal; this is quite normal.

IV. TROUBLESHOOTING

- A. Verify that correct power supply voltages are present on the module (+15, +12, and -15 volts).
- B. Using an oscilloscope, observe the extraction filter output at Ul, pin 2. This signal should appear much like the subcarrier generator output. If it is distorted, check the input filter for proper tuning or defective components.
- C. Check demodulator frequency as described in the adjustment subsection above.
- D. Check operation of Buffer Amplifier U2.
- E. Check operation of the Modem module. Refer to the Modem subsection of this manual.



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SUBCARRIER INTERFACE

Schematic 91C7156 Component Layout 20B2719 PC Board 51B5858

I. PURPOSE

The Subcarrier Interface module when used with the Modem II module generates and demodulates FM subcarrier data transmissions.

II. THEORY OF OPERATION

Subcarrier generator U3 is used to generate an FM signal from the frequency shift keyed output of the Modem module. The frequency of oscillation is controlled by applying a control voltage to the activated timing pin (pin 7). Resistors R17, R18, R19 and R20 form a voltage divider network used to adjust the frequency control voltage. Timing capacitor C6 is also used for frequency control. Its value is dependent on which subcarrier band is used. Capacitor C20 is a bypass capacitor required by the IC. Resistors R15 and R16 are used to reduce the total harmonic distortion. This can be reduced to 0.5% by trimming, or in the worst case, approximately 2.5%. The dc output level is adjusted by applying a voltage bias to pin 3, using R14.

Ul is a phase-locked loop used to demodulate the incoming FM subcarrier. The input filter connected to pin 2 is a telemetry extraction bandpass filter and is used to reject frquencies other than the telemetry subcarrier. The components used in the input filter are frequency dependent and are specified according to the subcarrier band being used. Recommended signal input at pin 2 is from 10 mV rms to 3 mV rms. The operating frequency is determined by C5, R5 and R6. Resistor R3 and capacitor C9 form a lock detect filter to eliminate chatter at the lock detect output (pin 6). Capacitor C8 is used as a bypass capacitor for an internal voltage reference. The demodulated output is taken from the loop phase detector (pin 11), through a post detection filter made up of R7 and C12, to buffer amplifier U2. This buffer amplifier is necessary because of the high impedance output at pin 11. U2 is a noninverting unity gain operational amplifier.

U4 provides +12 V for use on the module.

Subcarrier Interface Rev. 24 Aug 79 -1-

III. ADJUSTMENTS

- A. Subcarrier Generator (U3)
- 1. Remove modulation applied to the subcarrier generator using Send Level Adjust R10 on the Modem II module.
- Connect a frequency counter to the GEN OUT connector (J3). Adjust the subcarrier frequency adjustments, COARSE Adjust R19 and FINE Adjust R20. Both pots are accessible from the rear panel.
- 3. Disconnect the frequency counter and connect a distortion analyzer to the GEN OUT connector (J3). Adjust Distortion pot R15 for minimum distortion. Using this control approximately 0.5% distortion is obtainable. If no distortion analyzer is available, no adjustment on this pot is required. The worst-case distortion is approximately 2.5%, which is quite acceptable in most applications.
- 4. Disconnect the analyzer and attach an oscilloscope to GEN OUT (J3). To understand this adjustment, see Figure 1.7 in the Modem II subsection for representative waveforms. Adjust the oscilloscope to display about six periods of the unmodulated subcarrier as shown in (A). Using the modem Send Level Adjust R10, increase subcarrier modulation until the fifth crossover occurs midway as shown in (B).
- 5. Adjust the output level to 2.5 volts peak-to-peak using OUT Adjust R14. This pot is accessible through the rear panel.
- B. Subcarrier Demodulator (U1)
- 1. Telemetry Extraction Filter Adjustment

Apply a modulated subcarrier signal to the DEMOD IN connector (J2). Adjust inductors Ll and L2 for maximum amplitude and minimum AM. The filter output should be similar in appearance to the subcarrier generator output.

2. FM Demodulator Frequency Adjustment

Apply a modulated subcarrier signal to the DEMOD IN connector (J2). Adjust FREQ Adjust R5 for the cleanest FSK output. Note that some residual high-frequency subcarrier may be superimposed on the FSK signal; this is quite normal.

IV. TROUBLESHOOTING

- A. Verify that correct power supply voltages are present on the module (+5, +12, and -15 volts).
- B. Modulator
- Verify that the modem is generating an FSK signal, which may be observed at U3, pin 7.

Subcarrier Interface

- If no output is observed, check chip voltages and grounds. If U3 is replaced, verify proper adjustment by performing the subcarrier adjustment procedure described previously.
- 3. Note the Modem module must be properly adjusted and working correctly for the Subcarrier Interface module to function. Refer to the Modem II subsection of this manual for troubleshooting details.
- C. Subcarrier Demodulator
- Using an oscilloscope, observe the extraction filter output at Ul, pin 2. This signal should appear much like the subcarrier generator output. If it is distorted, check the input filter for proper tuning or defective components.
- 2. Check demodulator frequency as described in the adjustment subsection.
- 3. Check operation of Buffer Amplifier U2.
- 4. Check operation of the Modem module. Refer to the Modem II subsection of this manual.

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ANALOG IMPUT III

Schematic 91D7343 Component Layout 20D2897 PC Board 51C6013

I. PURPOSE

The Analog Input III board is used to measure 16 differential analog inputs and convert these input voltages to digital signals suitable for use by the microprocessor.

II. SPECIFICATIONS

DC input resistance is 500 k Ω . However, it is recommended that the output impedance of the circuit driving the board not exceed 10 k Ω at .25 Hz, increasing to 25 k Ω at 4 Hz. Normal mode rejection at 60 Hz is 35 dB with a common mode rejection (within input voltage range) of at least 60 dB. For best overall accuracy, the normal mode input should be close to ±4 V, with maximum inputs not exceeding ±5 V.

Measurement accuracy is 0.4% ±1 bit. The maximum input voltage from either input to ground is ±5 V. Exceeding this voltage will cause improper operation of the board for the duration of the over-voltage condition. If either ininput voltage exceeds ±40 V, permanent damage to Ull-Ul5, or U7 may result.

III. ELECTRICAL ADJUSTMENTS

Board addressing is accomplished using HEX switch S1. Up to 16 different A/D channels per board can be accessed, with the lowest 16 data channels on board 0, the next 16

Analog Input III 1 July 1983 data channels on board 1, and so on. Switch programming positions are shown in Section 7.3. Sl is programmed at the factory and normally will not require changing. If a defective board is replaced, be sure that the address switch is set to the proper position.

IV. THEORY OF OPERATION

The address of the Analog Input is selected by switch S1, and is decoded by the 74LS86 (U9) and the 74LS30 (U5). The board occupies four adjacent address locations in the range from 8140 ± 817F (Hex), with the exact starting address programmed by S1.

When the microprocessor outputs the address of the analog input board, *BOARD SELECT is pulled low, enabling the MC6821 (U1) PIA and the 74LS245 (U8) octal transceiver. The enabled direction of the transceiver is determined by the R/*W line from the microprocessor.

PIA lines PAO-PA7 are used to read the eight least-significant bits of the MN574A (U2) output. The four mostsignificant bits are read with PBO-PB3. The channel to be converted is output on lines PB4-PB7 and CB2. Line CA2 is used to put the A/D either in read or convert mode, and line CA1 is used to monitor when the A/D conversion is complete.

The three most-significant bits of the channel select lines (CHSEL2-CHSEL4) are used on the inputs of the 74LS138 (U3) 3-to-8 decoder, which selects one of five MC14052 (U11-U15) differential analog multiplexers. Four of the MUXs are used for the sixteen user inputs.

Analog Input III 1 July 1983 -2-

The remaining MUX is used for the four self-check channels (OFFSET/GND, +Vref, -Vref, and +5 V).

The selected differential input signal is buffered by the TL072 (U7) op amps. The buffered differential signal is then converted to a single-ended signal by op amp LM308A (U6) which is configured as a unity-gain differential amplifier. This single-ended signal is then fed directly into the MN574A (U2) A/D converter.

The A/D converter is the heart of the Analog Input board. This hybird IC contains a successive-approximation register, a 12-bit D/A converter, control logic, a clock, switches, buffers, a comparator, and a precision reference. Since the A/D uses successive-approximation techniques, a conversion is completed in about 25 μ s.

The sequence of commands issued by the software is as follows:

- A. Wait for conversion to be completed.
- B. Set R/*C high (read mode).
- C. Read previously-converted data.
- D. Output channel to MUXs.
- E. Set R/*C low (convert mode).

V. TROUBLESHOOTING

Verify that the Analog Input board and the Filtered Interface board are firmly seated in the corresponding slots.

Analog Input III 1 July 1983 Check for power supply voltages on the board (see schematic).

Verify proper switch positon by checking for activity on *BOARD SELECT.

Check the R/*C and status lines of the A/D converter (U2-5 and 28) for activity.

Check analog switch addressing. Under normal operations, the system will be scanning all 20 channels.

Analog Input III 1 July 1983



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DATE 8/17/84 TIME 10,41,35 FAGE 1 VMEAI

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PRINT PHANTOM ITEMS PRINT COMPONENTS PRINT PHANTOM/COMPONENT COMMENTS

FARENT 9204827	ITEM	CROSS REI	ITEM DESCRIPTION ASS ENGR DRAW 20D28	Y,ANALOG INPUT III MRC-1/2 97 B	2 BATCH EFFEC	QTY : 8/17/84	1 ITEM 4 UNIT	TYPE 1 MEAS EA	LOW LEVEL 03 PLANNER 511	
BOM	LL I	COMPONENT &	DESCRIPTION &	ENGINEERING		ITEM OP	T FIRST	. LT /	EFFECTIVE DATES	;

BOM ITEM	LL CD	COMPONENT & CROSS REF.	DESCRIPTION & COMMENT	ENGINEERING DRAWING NUMBER	QUANTITY PER	I UM	TEM TYF	OPT NBR	FIRST OF SEQ	L.T ADJ	EFFECTIVE DATES FROM TO
1	04	3473600	PCB ANALOG INPUT III	51C6013 A	1.000	EA	4				
2	04	1250075	EJCTR CD (LEFT, RIGHT & 2 PINS)	41-1274L,C12409	1.000	PR	4				
З	04	3430378	LBL LOGIC CD A/D	10A1068-10 CO	1,000	ËA	4				
4	06	3250016	SKT DUAL IN LINE B FIN	640463-1	2,000	EA	4				
5	06	3250024	SKT DUAL IN LINE 14 PIN	640357-1	3,000	EA	4				
6	06	3250032	SKT DUAL IN LINE 16 PIN U3.U11.U12.U13.U14.U15	640358-1	6,000	EA	4				
7	05	3250057	SKT DUAL IN LINE 20 PIN U8.010	640464-1	2,000	EA	4				
8	04	3250081	SKT DUAL IN LINE 28 FIN	640362-1	1.000	EA	4				
9	05	3250099	SKT DUAL IN LINE 40 PIN U1	640379-1	1,000	EA	4				
11.	04	3150117	SW 16P BCB ROT OUTPUT YELLOW	230057G	1.000	EA	4				
12	04	4540233	RES DIP 10K 0HM 1/8W 2% (8X) R5,R8,R14,R15,R16,R17	316B103	6,000	ËA	4				
13	06	4410247	RES 1K OHM 1/4W 10% R1.R4	RC076F102K	2,000	EA	4				
14	05	4460952	RES 15MEG OHM 1/4W 5% R6.R7	RC07GF156J	2,000	ËÅ	4				
15	04	4510863	RES 49.9 DHM 1/8W 1% R2,R3	RN55E49R9F	2.000	EA	4				
16	05	4510103	RES 4.99K OHM 1/8W 1% R19	RN55E4991F	1.000	EA	4				
17	04	4510699	RES 10.2K OHM 1/8W 1% R21	RN55E1022F	1.000	EA	4				
18	04	4510715	RES 11.3K OHM 1/8W 1% R20	RN55E1132F	1.000	EA	4				
19	06	3650132	RGLTR MC79L05 05V 0+1A T092 VR1	MC79L05 ACP	1.000	ËA	4				
20	04	4510657	RES 22.1K OHM 1/8W 1% R18	RN55E2212F	1,000	EA	4 ·				
21	04	4210191	CAP MICA DIP 51PF C10	DM-15-510J	1.000	EA	4				
22	06	4280079	CAP EPOX-BIP 10/25V C2,C5,C7,C22,C23,C27,C29,C30 C35,C36,C37,C38,C39,C40,C41,C C47,C48,C49,C50,C51,C52,C53,C C59,C60,C61	196D106X0025KAI ,C31,C32,C33,C34, C42,C43,C44,C45,C46, C54,C55,C56,C57,C58,	39,000	EA	4				

MOSE	LEY	ASSOC SINGLE	LEVEL BILL - REFERENCE NUMBER	SEQUENCE	1	ATE	8/17	/84	TIME 10.	41.35	PAGE	2	VMEAI
PRINT P PRINT C PRINT P	Hant Ompo Hant	OM ITEMS NENTS DH/COMPONENT COM	IMENTS				÷				×		
PARENT 	ITE	M CROSS REF	ITEM DESCRIPTION ASSY,ANA ENGR DRAW 2002897	LOG INPUT III MRC-1. B	/2 1	ATCH	QTY 8/1	1 7/84	ITEM T UNIT M	YPE 1 Eas ea	LOW L FLANN	EVEL ÆR	03 511
BOM ITEM	L.L. CD	COMPONENT & CROSS REF.	DESCRIPTION & COMMENT	ENGINEERING DRAWING NUMBER	QUANTIT PER	r UM	ITEM TYP	OP'T NBR	FIRST OP SEQ	LT ADJ	EFFECTI FROM	VE D	ATES TO
23	06	4280186	CAP EPOX-DIP 220/10V C64	K220E10	1.000) EA	4						
24	05	4310207	CAF .1UF/50V 20% C1,C3,C4,C6,C8,C9,C11,C12,C1 C18,C19,C20,C21,C24,C25,C24	CY20C104M 3,C14,C15,C16,C17, 528.C42.C47	23.000) EA	4						
26	04	4020244	IDCTR RF 10 UH	9230-44	2.00) EA	4						
28	05	3660735	IC SN74LS30N SI 81N NAND U4.U5	SN74LS30N	2.000) EA	4						
29	04	3660743	IC SN74LSB6N QU 21N EXCL. OR	SN74L886N	1.000) EA	4						
30	05	3660792	IC SN74LS130N 3-BLINEDECDEMUX U3	SN74LS138N	1,000) E.A	4						
31	05	3660859	IC SN74LS244N OCT BUS/DRIV ST U10	SN74L5244N	1,000) EA	4						
32 -	05	3661162	IC SN74LS245N OCT BUS TRNCVR UB	SN74LS245N	1.000) E.A	4						
33	04	3680220	IC DIFFERENTIAL AMUX 4CH	MC14052BCP	5.00) EA	4						
34	04	3680279	IC A/D CONVERTER 12 BITS	AD574AKD	1.000) EA	4						
- 35	-05	3710027	IC MC6021P PIA INTERFACE	MC6821P	1.000) EA	4						
36	04	3730157	IC LM308AN OFAMP FRECISION	LM308AN	1.000) EA	4						
37	04	3730876	IC DUAL OF-AMP U?	TL072A	1.000) EA	4						
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STATUS INPUT, TTL II

Schematic 91C7237 Assembly 20D2798 PC Board 51C5912

I. PURPOSE

The Status Input, TTL II module is used to interface the MRC system with 16 TTL inputs. The inputs can be used separately as status or as a single 16-bit word.

II. SPECIFICATIONS

Inputs are TTL active low. Input voltage should be restricted from 0 to +5 volts or module damage may result. A switch closure across the input pins is all that is required to operate a status channel.

III. MODULE ADDRESS SPECIFICATION

Switch S1 is used to assign a module address from 0 to 15. Module 0 will output channels 1 through 16; module 1 will output channels 16 through 32, etc. Programming of S1 is shown in Figure 1. If replacement modules are installed for any reason, verify that S1 is set correctly.

IV. THEORY OF OPERATION

U6, in conjunction with switch S1, is a programmable inverter for address selection. U5 ANDS the outputs of U6 with PRE (I/O Select), A6, A7 and *A8 to form the module address. When switch S1 is set to "0", the module is addressed in its lowest address range, 30C0 to 80C3. When switch S1 is set to "F", the module is addressed from 80FC to 80FF.

When the correct address is decoded, pin 8 of U5 goes to a low state, enabling decoder U4. U1 and U2 are tristate buffers used to gate 8 bits of status information onto the data bus. U3 provides a unique module ID pattern on the data bus when selected.

When address lines AO and Al are both low and U4 is enabled, status bits 1 through 8 are gated onto the data bus. When AO is high and Al is low, status bits 9 through 16 are gated onto the bus. When AO is low and Al is high, the unique module ID is gated onto the bus.

Status Input, TTL II Rev. 24 June 82 -1-

V. TROUBLESHOOTING

Check for periodic low pulses on U5 pin 8, indicating the CPU is attempting to read data from this module. Low-going pulses should also be observed on pins 1 and 19 of U1 and U2.

Address	Channels
0	1-16
1	17-32
2	33-48
3	49-64
4	65-80
5	81-96
6	97-112
7	113-128
8	129-144
9	145-160
A	161-176
в	177-192
C	193-208
D	209-224
E	225-240
F	241-256

Figure 1. S1 programming.

Status Input, TTL II Rev. 27 Feb 81 -2-



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_		1	1	_
-			-	-
16	CAPACITON , 220HE IOV	C8	4280186	1
15	" , Juf SOV	C1-C7	4310207	7
14	RESISTOR, IOK VAW 107	R2-R21	4410379	150
13	" . IK 14W 10%	RI	4410247	1
12	SWITCH , BCD, 100 576	SI YELLOW	3150117	
11	SOCKET, I.C., 14 PIN	U5,U6	3250024	2
10	" • 16 PIN	U4	3250032	11
9	" " 20 PIN	UI,U2,U3,U7	3250057	4
8	1.C.SV74L5244	07	3660859	
7	# 5174L5240	01,02,03	3660974	3
6	# SN74L5139	U4	3660800	1
5	# SN74L5 86	UG	3660743	1
4	SN TALS 30	U 5	3660735	1
3	LABEL , IOA 1067-7		3430345	
2	EJECTOR PAIR, CI2409/	2	1250075	1
	P C BOARD SICSSIZ-10,-2	1	3472446	1
ITEN NO.	DESCRIPTION	REF DESIG	STOCK NO.	QTY
	A Pass	* M		
	1001 11.	COMPONE STATUS IND	TT, TTL	UT -
		ALL THE AVENUE	200279	ala
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USED ON MRC FAMILY TTEM NO: 92034/5

5 SCHEMATIC SICT237 REV.

I. UNLESS OTHERWISE SPECIFIED:

4. P C BOARD SICS912 REV. -10,-21

RESISTOR VALUES ARE IN OHMS 1/4W 10% CAPACITOR VALUES ARE IN MICROFARADS 2. I C SOCKETS TO BE INSTALLED AT EACH I C LOCATION 3. SWITCH SI TO BE INSTALLED WITHOUT A SOCKET

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STATUS INPUT, OPTO II

Schematic 91C7236 Component Layout 20D2795 PC Board 51C5911

I. PURPOSE

The Status Input, Opto II module is used to bring 16 on/off inputs into the CPU. It can be used for individual bits (status) or as a 16-bit word. Optical isolators are used for maximum noise rejection.

II. SPECIFICATIONS

Each input requires between 5 mA and 30 mA of current (user supplied) to drive the optical isolator for that input. The unit is shipped with 1800 ohm current-limiting resistors. These are suitable for input voltages from 20 V to 48 V. For lower voltages, the resistors will have to be changed to 560 ohms. This will allow operation with input voltages from 6 V to 15 V. The maximum voltage from any input to ground should not exceed \pm 50 Vdc. Exceeding this voltage may cause damage to the module.

III. ELECTRICAL ADJUSTMENTS

Switch Sl is used to assign a module address from 0 to 15. Module 0 will output channels 1 through 16; module 1 will output channels 17 through 32, etc. Programming of Sl is given in Figure 1. Sl is programmed at the factory and will normally only be reset if a defective module is replaced. In this case, the switch on the new module should be set to the same position as the module it is replacing.

IV. THEORY OF OPERATION

Ul, in conjunction with Sl, is used as a programmable inverter for address selection. U2 ANDS the output of Ul along with PRE (I/O Select), A6, A7, and *A8 to form the address at which the module will operate.

With switch Sl set to "0", the address for the module will begin at 80C0 and end at 80C3 as each module uses four addresses. If switch Sl is set to "F", the address for the module will begin at 80FC and end at 80FF.

Status Input, Opto II Rev. 27 Feb 81 -1-

The output of U2 is used to enable 1-of-4 decoder U3, with only the first three outputs being used. The outputs of U3 are active low enables for tristate buffers U4, U5 and U22.

U4A-D and U5A-D are used to bring the first eight channels onto the data bus, while U4E-H and U5E-H are used to bring the second eight channels onto the data bus. U22 provides a unique module ID pattern on the data bus when selected.

V. TROUBLESHOOTING

As a general guideline, if only certain bits on a module fail to function properly, the cause is usually associated with the input optical isolators. Complete module failure is associated with Ul through U3. If there are multiple modules in the user system, the modules may be interchanged (after setting switch S1) to pinpoint the cause. Before swapping modules, check all inputs to ensure that excessive currents are not being applied.

Verify that pin 5 of the optical isolator drops below 0.8 volts when current is passed through the appropriate input. If not, suspect the optical isolator or a defective input on U4 or U5. Check for a periodic low pulse on U2 pin 8. This indicates that the CPU is trying to read data from this module. Low-going pulses should also appear on pins 1 and 19 of U4 and U5. If not, suspect U1 through U3 or S1.

-2-

Address		Channels
0		1-16
l		17-32
2	1.	33-48
3		49-64
4		65-80
5		81-96
6		97-112
7		113-128
8	×	129-144
9		145-160
A		161-176
в		177-192
С		193-208
D		209-224
Ε		225-240
F		241-256



Status Input, Opto II Rev. 27 Feb 81

-3-



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19	CAPACITOR 2204 10V	C2	4280186	1
18	" .ipf sov	63-69	4310207	7
17	RESISTOR IDK, VA W, 10%	R1- R20	4410379	20
16	" 1.8 K, 1/4W, 10%	R21-R36	4410270	16
15	11 1K, Y4W. 10%	R37	4410247	1
14	SWITCH BCD, 176 2100	SI YELLOW	3150117	1
13	SOCKET, I.C., 6 PIN	06-021	3250008	16
12	# # 14 PIN	UI,U2	3250024	2
11	11 16 PIN	UB.	3250032	1
10	" + 20 PIN	U4,U5,U22,U23	3250057	4
9	I.C. TIL-112	06-021	3730777	16
8	" SN74L5244	U23	3660859	1
7	" SN 74L5240	U4,U5,U22	3660974	3
6	" SN74L5139	V3	3660800	1
5	" SN74L586	UI	3660743	1
4	+ SU741530	U2	3660735	1
3	LABEL MAL IDAID68-6		3430337	1
2	EJECTOR PAIR, CIENON-1-2		1250075	1
1	P C BOARD, 51C5911-10,-20		3472455	
HO	DESCRIPTION	REF DESIG	STOCK NO	QT.
	· · · · · · · · · · · · · · · · · · ·	COMPONENT	LAYOUT	

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OPEN COLLECTOR COMMAND OUTPUT

Schematic 91C7171 Component Layout 20C2755

I. PURPOSE

The Open Collector Command Output module provides 16 opencollector outputs for driving control relays.

II. SPECIFICATIONS

Maximum voltage that can be applied to outputs without causing output latch-up is 55 V. Up to 300 mA may be sinked by drivers U7 to Ul4.

III. ELECTRICAL ADJUSTMENTS

Switch S1 is used to assign a module address from 0 to 15. Module 0 will output channels 1 through 16; module 1 will output channels 16 through 32, etc. Programming of S1 is shown in Figure 1. S1 is programmed at the factory and will not normally require changing. Any replacement module should be switched to the same configuration as the original module.

IV. THEORY OF OPERATION

Ul, in conjunction with switch Sl, is used as a programmable inverter for address selection. U2 ANDS the outputs of Ul along with VMA (Valid Memory Address), PRE (I/O Select), A7 and A8 to form the module address location.

With all four switches in the OFF position, the address for the module will begin at 8180 and end at 8183 as each module requires four addresses. If all four switches are ON, the address will begin at 81BC and end at 81BF.

The output of U2 is inverted by U6 to form an active-high board select, which is fed to the chip select on U3 (pin 24) and to bus buffer selector U6. If the CPU requests data from PIA (Peripheral Interface Adapter) U3, the R/*W (Read/Write) line (J1-64) will be high, enabling pin 19 of U4 and U5 and allowing data to pass onto the data bus. This read function is used to check operation of the PIA. If R/*W is low, pin 19 of U4 and U5 will be low, enabling a command to be written into the PIA.

Command Output, O.C. Rev. 24 Aug 79 Output CB2 on U3 is used to disable all outputs simultaneously upon Reset. Transistors Q1 and Q2 are current sources to interface the PIA with drivers U7 to U14.

V. TROUBLESHOOTING

1. Partial Failure (Some Channels Work)

This indicates that at least some PIA channels are functioning. Trace back from the output driver to the output of the PIA. Example: Assume channel 1 does not function. If tally-back does not function, suspect U4, U5 or U3. If the tally-back functions, the failure is in the output driver.

2. Complete Failure (All Channels)

Check U3 pin 19 for a low level. If the ENABLE signal is low, check operation of Ql and Q2. If pin 19 is high, check U3 pin 24 for an active high pulse when a raise on this module is attempted. If no pulse is seen, verify operation of S1, U1, U2 and U6.

If a pulse is seen at U3 pin 19, verify that the pulses are repeated at Pin 1 of U4 and U5. If these pulses are present, suspect U4, U5 or U3.

Pos 4	Pos 3	Pos 2	Pos 1	Address	Channels
Off	Off	Off	Off	0	1-16
Off	Off	Off	On	1	17-32
Off	Off	On	Off	2	33-48
Off	Off	On	On	3	49-64
Off	On	Off	Off	4	65-80
Off	On	Off	On	_5	81-96
Off	On	On	Off	6	97-112
Off	On	On	On	7	113-128
On	Off	Off	Off	8	129-144
On	Off	Off	On	9	145-160
On	Off	On	Off	10	161-176
On	Off	On	On	11	177-192
On	On	Off	Off	12	193-208
On	On	Off	On	13	209-224
On	On	On	Off	14	225-240
On	On	On	On	15	241-256

Figure 1. Sl programming.

Command Output, O.C. Rev. 24 Aug 79 -3-



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		O.C. COMM. OUTPUT ASSY.		9203613	*
					33
S		21			32
					3)
-		1			30
					29
16	0	RESISTOR 2700	R11-26	44 2296	281
1		- IR WEW	R 10	44202L1	27
4	4	* IDK	R 1-4	110374	26
1	1	* £200	R6	HH 0259	25
3	3	* IK	8 5,7,8	44.0247	24
1	1	RESISTOR 470	89	54.5255	23
16	16	CAPACITOR .001	C16-31	73 3245	22
14	14	1/50	C+6.8-13	43:0207	21
1	1	CAPACITOR 220/10	67	425-10-	20
	-				19
1		SWITCH CTS 206-4	51	319/0011	19
					15
	1	AC. SOCKET AND ANDE 79-1	113	336 ** 31	16
2	2		14.5	3250057	15
3	1 3		U1.2.6	3250024	14
8	1 3	I.C. SOCKET AND AND HAD	U7-14	3250016	13
					12
		TRANSISTOR 24 3053	PE.	3630035	11
1		TRANSISTOR 2NZ924	91	3.3:3.7	10
1	1.1	LABEL	IOAIOL8-9	31303.0	9
8	8	* 5h75472	U7 -0/4	36-60941	8
1	1	· ME ABEI	U3	3710027	7
2	15	* THL5244	04,5	3060859	6
	1	74	01	3000743	2
		" 74 LS 10	UL	3600725	19
-		1.C. 74LLOO	UA	3660669	1-3-
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OPTICALLY ISOLATED COMMAND OUTPUT

Schematic 91C7129 Component Layout 20D2705 PC Board 51B5846

I. PURPOSE

The Optically Isolated Command Output module provides 16 optically isolated outputs for control of external equipment.

II. SPECIFICATIONS

The maximum voltage that should be applied to the outputs is 48 Vdc. The maximum voltage drop on an ON channel is 1.4 V, with a maximum 240 mA load. When a channel is OFF, the leakage current will not exceed 50 μ A. The outputs incorporate built-in reverse polarity and inductive load protection. The maximum voltage from an output line to ground is ±50 Vdc. Exceeding that voltage may cause damage to the module. The output is floating with respect to the chassis.

III. ELECTRICAL ADJUSTMENTS

Switch S1 is used to assign a module address from 0 to 15. Module 0 will output channels 1 through 16; module 1 will output channels 17 through 32, etc. Programming of S1 is given in Figure 1. S1 is programmed at the factory and will normally only be reset if a defective module is replaced. In this case, the switch on the new module should be set to the same position as the module it is replacing.

IV. THEORY OF OPERATION

Ul, in conjunction with Sl, is used as a programmable inverter for address selection. U2 ANDS the outputs of Ul along with VMA (Valid Memory Address), PRE (I/O Select), A7 (Address Line 7), and A8 (Address Line 8) to form the address at which the module will operate. With all four switches on Sl OFF, the address for the module will begin at 8180 and end at 8183 as each module requires four addresses. If all four switches on Sl are ON, the address for the module will begin at 81BC and end at 81BF.

Command Output, Opto Rev. 24 Aug 79 The output of U2 is inverted by U3B to form an active-high board select, which is fed to the chip select on U6 (pin 24) and the bus buffer selectors U3C and U3D. If the CPU desires to read data from the PIA (Peripheral Interface Adapter) U6, the R/W (Read/Write) line (J1-64) will be high. This causes the output of U3D to go low, which enables U4A-D and U5A-D to activate. This allows data from U6 to pass through U4 and U5 to the data bus. If the CPU desires to write data to U6, the R/W line will be low. This causes the output of U3C to go low, which enables U4E-H and U5E-H to activate. This allows data from the data bus to pass through U4 and U5 to U6.

Output CB2 on U6 (pin 19) is used to disable all outputs simultaneously. This occurs during failsafe. To enable outputs, CB2 is brought low, forward biasing Q33 and Q34 which supply +5 V to the optical isolators. Drivers Ql through Q16 are used to boost the output current of U6 to a sufficient value in order to drive optical isolators U7 through U22. The outputs of U7 through U22 are used to forward bias the Darlington output transistors Q17 through Q32 (floating from chassis).

V. TROUBLESHOOTING

1. Partial Failure (Some Channels Work)

This indicates that PIA U6 is at least partially functioning. Trace back from the output stage to the output of the PIA. Example: Assume output 1 does not function. If the tally-back does not function, suspect U4, U5 or U6. If the tally-back functions, the failure is in the output driver of U6 or the transistor buffers (Q17-Q32).

2. Complete Failure (All Channels)

Check U6 pin 19 for a low level. If it is low, verify that the emitter of Q32 is near 5 V. If it is not, suspect Q33 or Q34. Check U6 pin 24 for an active high pulse when a raise is attempted for a channel on the module. If no pulse is seen, check S1, U1, U2 and U3 pins for correct operation. If a pulse is seen, verify that pulses appear at U4 and U5 pins 1 and 19; if not, suspect U3. If these pulses are present, suspect U4, U5 or U6.

Command Output, Opto Rev. 9 June 80

Pos 4	Pos 3	Pos 2	Pos 1	Address	Channels
Off	Off	Off	Off	0	1-16
Off	Off	Off	On	1	17-32
Off	Off	On	Off	2	33-48
Off	Off	On	On	3	49-64
Off	On	Off	Off	4	65-80
Off	On	Off	On	5	81-96
Off	On	On	Off	6	97-112
Off	On	On	On	7	113-128
On	Off	Off	Off	8	129-144
On	Off	Off	On	9	145-160
On	Off	On	Off	10	161-176
On	Off	On	On	11	177-192
On	On	Off	Off	12	193-208
On	On	Off	On	13	209-224
On	On	On	Off	14	225-240
On	On	On	On	15	241-256

Figure 1. Sl programming.

Command Output, Opto Rev. 24 Aug 79

-3-





29	LABEL	IDAID62-B	343035 c	1
28	SOCIET.S MH, ICC-061-52-6	U7- U22	3250000	1
27	MO,SIETOR,INSUL ACTOSOTS -44	Q34	3250347	1
26			1050582	14
25	LOCKWASHER SPLIT RIND & L		1050632	1
24	SCREW PARHD #4-40 . Ve		1050129	1
23	SOCKET 14 Pin 640357-1	U1.U2.U3	3250.2-	13
22	- 20 - 640464-1	U4,U5	3250627	12
21	* 40 * 640379-1	VG	32561"	1
20	OILOSS OI BOSSA BOTIDARA	C2	428617.	1
19	- CY20CI04H .1/50	CI, C3-C6	4316217	5
18	1C M0C8030	07-022	3732228	1
17	RESISTOR + 0% 220.0	R17-R32	4415.60	1
16	" 22K	R1- R16	4412411	1
15	" юк	R34-R38	4410379	-
14	· 4.7K	R33	THIOSCE	
13	и ік	R39	1410247	
12	TRANSISTOR 2N3640	Q33	36306%	
	TRANSISTOR 2N3053	Q34	3630035	
10	SWITCH CTS 206-004	51	3190071	-
9	IC HC6821P	06	37/022	
8	. SH74L5244	04,05	3410959	
7	- 5N74L586	UI	30007-3	1
6	. 5N74L530	UZ	340735	1
5	. SH74L500	UD	3666609	Г
4	TRANSISTOR 2N5293	QIT THEU 932	3030316	
3	TRANSISTOR 282924	QI THRUQIS	3-30027	ī
2	EJECTOR SET CI2409/1 , /2		1250075	Г
	P C BOARD	SILS 840-R,21	347.401	F
TTEM	DESCRIPTION	REF. DES.	STOCK NO.	a
	Contraction of the second seco		T LAYOU	T

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FILTERED INTERFACE

Schematic 91A7119 Component Layout 20B2718 PC Board 51A5851

I. PURPOSE

The Filtered Interface module provides a means of connecting to an I/O module where RF filtering is required. Each line is passed through an LC lowpass filter to inhibit RF. A metal shield is used to prevent RF field leakage.

II. SPECIFICATIONS

Attentuation:

-10	dB	200	kHz	
-20	dB	70 0	kHz	
-40	dB	2	MHz	

III. TROUBLESHOOTING

Check for foreign particles across the connector pads, broken traces, and improper solder joints. Check the inductors for continuity and the capacitors for leakage.

Proper shielding and grounding techniques should be observed for all input/output lines.

Filtered Interface Rev. 24 Aug 79

NOTES:

PI

L UNLESS OTHERWISE SPECIFIED CAPACITOR VALUES ARE IN MICROFARADS 2. CI THRU C36 ARE .1 at 50V LI THRU L 36 ARE 6.8 uH 3. P.C. BOARD 5IA585I 4. COMPONENT LAYOUT 2082718

LI

L36

JI TYP. I THRU 36

(36 PLCS.)

CI

C36



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DIODE-FILTERED INTERFACE II

Schematic 91A7273 Component Layout 20C2823 PC Board 51C5941

I. PURPOSE

The Diode-Filtered Interface module provides filtering and damping for the Status Input, TTL II module. Each input is passed through an LC low-pass filter to inhibit RF. Diodes CR1-CR32 prevent voltages from rising above about 5.8 V or below -0.8 V when the input signal changes suddenly.

II. SPECIFICATIONS

The attenuation at various frequencies is essentially the same as that of the Filtered Interface module.

III. TROUBLESHOOTING

Check for foreign particles across the connector pads, broken traces, and improper solder joints. Check the inductors for continuity and the capacitors for leakage.

Proper shielding and grounding techniques should be observed for all input/output lines.

Diode-Filtered Interface -1-Rev. 24 June 82



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DC POWER SUPPLY (4 RU Chassis)

Schematic 91C7179 Assembly 21C2655

I. DESCRIPTION

The power supply provides +5 V, +15 V, and -15 V. The module is easily removed for adjustment, service, or replacement. No adjustments are required under normal conditions.

Attached to the rear of the power supply is a Corcom filter, which includes a fuse, an RF filter, and the voltage selection card. A nine-pin Molex connector interfaces the power supply with the chassis wiring harness.

The ac input voltage may be either 120 V or 240 V. The voltage selection card has positions for four input voltages; however, the 100 V and 220 V positions are not connected.

To service the power supply, remove two screws at the front of the power supply and one screw at the rear of the terminal. Slide the module forward.

II. ADJUSTMENT

Three voltage adjustment potentiometers are present for +5 V, +15 V, and -15 V. These adjustments are:

+5	V	V.ADJ.	R108
+15	V	+V.ADJ.	Rll
-15	v	-V.ADJ.	R16

A sealed potentiometer is included for current limiting for +5 V (R104).

III. 120 VOLT OPERATION

Unless otherwise tagged, the power supply is set for 120 V operation when it is shipped from the factory. Normally no changes are required.

-1-

The 120 V label should be visible on the voltage selection card. If a different voltage is visible, remove the card and reinsert so the 120 V label is on the top. The card may be removed by using needle-nose pliers. An MDL 2 A fuse is used for 120 V.

IV. 240 VOLT OPERATION

Change the voltage selection card so the 240 V label is visible when the card is installed. Use an MDL 1 A fuse.



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			-
TEFIM IRGA TETPM_19	AIITIIA	154.0210	0-
WED LOLD IND - CP CCT	RETIAD	IDADAGA	41
F BUS INCA 201	ALDUA	10900588	96
	ALPHA	104/90/	15
E DUD LUGA 291	ALPHA	1691919	44
E SIKU IOGA ORN 1555	ALPHA	1641588	43
4 STRD 22 GA GRAY BU-730-2208	MILSPEC	1640457	42
E STRD 22 GA WHT/GRN BU-730-22095	MLSPEL	1640689	41
2E STRD 226A 6RY/WHT BU-T30-22089	MLSPEL	1640622	40
RE STRD 226A WHT/BLU BU-730-22096	MLSPEC	1640697	39
E STRD 16GA RED 155.7	ALPHA	1641471	38
RE STRD 1864 RED 1555	ALPHA	1641570	37
E STRD IGGA BLACK 1557	ALPHA	1641455	36
E STRD 18GA BLACK 1555	ALPH A	1641554	35.
E STRD BGA GREEN 1555	ALPHA	1641703	34
E STRD 18GA BLUE 1555	ALPHA	1641612	33
RE STRD IBGA GRAY 1555	ALPHA	1641638	92
RE STRD 186A WHITE 1555	ALPHA	1691547	31
ZE STRD ISGA BROWN 1555	ALPHA	1641562	30
2F 57PA 1864 YELLOW 1555	AIPHA	11-41501	20
RESTRA 1844 VINEE IEEE	AIPHA	11.411.20	20
DAK TURING ETT POL 141	AI DUA	1510010	20
HAR TUDING FATLET HZ"	ALPAA	1360069	21
TINK (UDITIG FATEL) - ANG	ALMA	13600310	26
EW BIND. HD. 6-32X3/8	KELIAB	1090208	25
TLH TOGGLE FH 123	JBT	3160108	24
TCH BRACKET 5B3013	MAI	2063305	23
BLE CLAMP 834	SMITH	1270057	22
SHER #8FLAT SST	RELIAB	1130335	2/
EW BIND. HD. 8-32 X V2	RELIAB	1130103	20
ET AN 470 AD43	RELIAB	1210160	19
DUND LUG T 197	WALDOM	1090695	18
KWASHER INTL #8	RELIAB	1130293	17
HEX 8-32	RELIAB	//30277	16
EW STL. CAD. PLATE B-32X3/B	RELIAB	1130095	15
TACT SOCKET 60619-1	AMP	3250701	14
ITACT SOLLET 101173-1	AMP	3250735	13
KET HOUSING 1-AROTA A	AMR	375N-28	12
WAPAINA IAPEL IN A 1000 2	MAI	242 0071	12
E PATIAN LAPPI OC TOT	(TIAI	DADOOLE	
SE KATIIVG LABEL 85-1503	LUKCO/7	3930035	10
DE MUL I AMP	BV55	3310251	9
SE MDL ZAMP	BUSS	3370277	8
, DISC, CERAMIC. DI/GOOV CIDI, CIDZ	ERIE	43/0/73	7
NER INPUT FILTERED 614	CORCOM	3370046	6
KKET MOUNTING 58-2616	MAI	206/018	5
CLET HOLD DOWN 5A-2615	MAI	2060410	4
SISTUR, RCO76FIOIK 100 114W 10%	6 A/B	4410122	3
RMINAL MOSA	USELD	3290629	2
WER SUPPLY HEBB-TSW-A	POWER-ONE	5/00243	7
VER SUPPLY ASSY 71C7455	MAI	9100611	*
AESYD ID TIAN		STOCK NID	ITEM
		ABBOCIATES	NO
	A	Salis andres il mail	A MILL
100 M 01	POWER SUP	PLY ASSEM	BLY
	MOD MRCI 4	EU TOPMINI	2.VP
52° 202	UM LCC F-17-FJ	7102655	M
	TIDE TAKE WATER	LIGEDJ	17.1

EXTENDER BOARD

Assembly 20B2724 PC Board 51B5854

I. PURPOSE

11

The Extender board allows active modules to be mounted outside the Terminal for troubleshooting. Test leads can be attached to the connector leads for ease in examining bus signals and input/ output signals. This board contains no active components.

Exposure of MRC modules outside the protected RF chassis environment via the Extender board may cause the unit to be susceptible to RF effects.

Extender Board Rev. 24 Aug 79



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ITEM NUMBER: 9051434 ##### S/P MRC-1 MUSELEY ASSOCIATES, INC. KIT NUMBER: ST-50A 111 CASTILIAN DRIVE DATE 8/27/95 GULETA, CA. 93117 (005) 908-9021

CUMPONENT ITEM NO.	MANUFACTURER Part number	JTY PER
3390127	FLV160	10
3390143	NV-5354	2
3390614	HLMP-3507	2
300053	LED GRN 7-12020 DIFFUSED 75DEG 1N914	1
3000145	DIO 18914 75V 75MA SI A398 184154	1
3500202	DIO 1N4154 25V 4NS SI DO35 1N4740a 210.Ja	1
3000230	010 Z1N4740A 10V 1W 5% ALAY 1N4745A	1
3010003	DIU 21N4745A 16V 1m 5% AIAY 10D2	2
3610169	DIU 1002 200V 1A SI D039 SZ3+1	1
3630027	UIU ZSZ3+1 3+1V 2N2924-LE5	3
3030035	XT NS2N2924LFS.2w160M025V.1A7P 2N3053	1
3630191	XT NP2N3055 05W100M050V.7A	1
3-30316	XT PP2N4037 01w060M060V01A 2N5293	3
3650056	XT NP2N5293 35w800K080V04A	,
3=50074	RGLTR LM32982 6.9V 30MA T092	,
2 . 5 01	RGETR LM340T12/7612 VARV1.5A	1
3050124	RGLTR MC78L12 12V 0.1A T092	1
3050132	RGLTR MC79L05 05V 0.1A T092	1
3650140	MC79LIZAGLP RGLTR MC79LIZ izv/g.ia T092	1
3050157	MC79L15ACP RGLTR MC79L15 15V 0.1A T092	1
3050105	MC7905CT RGLTR MC7905T 05V 1.5A T0220_	1
3650173	UA7805UC RGLTR UA7805UC 05V 1.0A T0220	L
3660008	UA741CP 1C UA741P OPAMP GEN COMP	1
3660487	SN74154N IC SN74154N 4-161 INF DEMUX	1
3060537	SN74174N IC SN74174N HX D EDGE/TR	2

ITEM NUMBER: 9051434 **** S/P MRC-1 PAGE MUSELEY ASSOCIATES. INC. 111 CASTILIAN DRIVE KIT NUMBER: ST-50A DATE GOLETA, CA. 93117 (805) 968-9621

CUMPONENT	MANUFACTURER	JTY.
ITEM NO.	PART NUMBER	PER
3060509	SN741 SOON	2
	IC SN74LSDON GU 21N NAND	÷.
3660677	SN741 S02N	1
	IC SN74LSO2N QU 21N NOR	
3060005	SN741.S04N	1
	1C SN74LS04N HX INV	•
3660693	SN74LSO8N	1
	IC SN74LSOON UU 21N AND	
3660719	SN74LS20N	1
	IC SN74LS20N DU 41N NAND	
3660727	SN74LS27N	. 1
	IC SN74LS27N TR 31N NOR	
3660735	SN74LSJON	2
	IC SN74LS3CN SI DIN NAND	
3060743	SN74L SOON	2
	IC SN74LS86N QU 21N EXCL OR	
3660750	SN74LS107AN	1
	IC SN74LS107AN DU JK MAS/SL	
3060768	SN74LS123N	1
	IC SN74LS123N DURETRMONOMULTI	
3660776	SN74LS132N	1
	1C SN74LS132N GU 21N NAND ST	
3060792	SN74LS130N	1
	IC SN74LS138N 3-8LINEDECDEMUX	
3660800	SN74LS139N	1
	IC SN74LS139N DU2-4LNDECDEMUX	
3060826	SN74LS163AN	1
	IC SN74LS163AN BINCOUNT PRESET	
3660859	SN74LSZ44N	4
	IC SN74LS244N OCT BUS/DRIV ST	
3060807	SN74LS367AN	1
	IC SN74LS307 HEX BUF 3/ST	
3060875	SN74LS368AN	1
	IC SN74LS358 HEX INV 3/ST	
3060917	SN75451BP	1
	IC SN75451P DU AND HIGHV OC	
3660925	SN754528P	1
	IC SN754525P DU NAND HIGHV OC	
3660941	SN75472P	2
	IC SN75472N DU NAND HIGHV OC_	
3660958	SN74LS32N	1
	IC SN74L532 QUAD 2-INPUT NOR	
3060966	SN74LS260N	1
	IC SN74LS250N DU 5IN NOR	
3060974	SN74LSZ40N	2
	IC SN74LS240 DCT BUS/DRIV ST	
3680063	CD40403E	1
	IC CU4040BE 12 STAGE BIN CT	

2

DATE 8/27/85

ITEM NUMBER: 9051434 #### S/P MRC-1 MUSELEY ASSUCIATES, INC. KIT NUMBER: ST-50A DATE 8/27/85 111 CASTILIAN DRIVE GULETA + CA. 93117 (005) 900-9021

COMPONENT MANUFACTURER GTY. ITEM NO. PART NUMBER PER 3650162 SCL4U11AE 1 1C SCL4011AE QU 21N NAND 3680212 MC14411P 1 IC BIT RATE GENERATOR MC140528CP 3680220 2 IC DIFFERENTIAL AMUX 4CH 3590021 TIL-305 2 IC TIL-308 DISP 7 SEG LDP 3710019 MC6902P 1 IC MC6002P MICROPRUCESSOR 2 MCoB21P 3710027 1C MC6821P PIA INTERFACE 3710035 MC6823P 1 IC MC6828P PRIOR INTERRUPT 3710043 MC6850P 1 IC MC6850P ACIA INTERFACE 3710076 MM53107N 1 IC MM53107 OSC ZEXP17 DIV 3710225 M5L2114LP-3 1 IC M5L2114LP RAM STAT 1KX4 MRC 3730132 L F1 3300D 1 IC LF133JOD A-D CONV 4.5DIG 3730157 LM-3UBAN Ł IC LMBOBAN OPAMP PRECISION 1 3730207 LM-339N IC LM339N COMPARITOR QUAD 3730355 MC1400P 1 IC MC1488P QU LINE DRIVER PLST 3730353 MC1409P 1 IC MC1489 JU LINE RECEIVER 3730462 KC4130N 1 IC RC4136N DPAMP QUAD 741 3730595 ADB1200PCN 1 IC ADB1200PCN A-D CONV 12+SGN NE-531N 1 3730694 10 NE-531 OPAMP HI SLEW 1 3730777 TIL-112 IC TIL-112 OPTOCOUPLER XR-2200CP 3730319 1 IC XR-2206CP VCO WAVE GEN 3730827 XR-2211CP 1 IC XR-2211CP FSK MODEM 4 3730808 MOC-3030 IC MOC-8030 OPTICAL ISOLATOR 3730876 L TL072A

IC DUAL GP-AMP

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